## The newly revised GSICS DCC Calibration ATBD for Geostationary Visible imagers

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GSICS VIS/NIR Sub-group meeting June 10, 2021

#### Motivation and objectives

- Need a comprehensive ATBD to assist GSICS agencies in delivering GSICS DCC calibration products
  - an improvement upon the 2011 DCC ATBD
- Provide a reference template and guidelines for agencies to document GSICS operational DCC products and calibration activities
- Facilitate the consistent implementation of the algorithm across agencies and sharing of best practices
- Ultimately, the ATBD will serve as a key document for writing a joint agency paper on DCC calibration
  - include agency-specific implementation and validation results

### Outline

- Background
  - Key changes in the revised DCC Calibration ATBD
- DCC Calibration ATBD
  - DCC identification, Filtering, Angular/Statistical transformations
  - DCC Characterization using NOAA-20 VIIRS as a reference instrument
  - Derivation of reference DCC mode radiances for GEO domains
  - IR Brightness Temperature (BT) threshold normalization between GEO and VIIRS
  - Spectral Band Adjustment Factors (SBAF)
  - Seasonal correction of DCC responses
  - Transfer of VIIRS Calibration to GEO imagers using DCC modes
  - Uncertainty Analysis
- Summary

### Background

- First GSICS DCC Calibration ATBD was published in 2011
  - Focused on calibrating GEO visible channel (0.65  $\mu m)$
  - Described algorithm for temporal trending and radiometric scaling of GEO imager to Aqua-MODIS Band 1 using non-coincident DCC measurements

#### • Key highlights of this revised DCC ATBD

- Improved uncertainty (IR BT threshold normalization, seasonal corrections)
- Uses NOAA-20 VIIRS as a reference instrument for DCC characterization
- Provides more comprehensive details on the formulation and implementation of DCC method
  - Reference DCC modes for multiple GEO domains, SBAF computation, uncertainty analysis, GSICS DCC products
- Applies to all spectral channels with wavelengths up to 1  $\mu m$

#### **GEO Imagers DCC Identification Domains**



• ±20° Lat/Lon from the GEO sub-satellite point

### **DCC Characterization using NOAA-20 VIIRS**



- Identify DCC pixels within GEO domain using M15 (10.8  $\mu m)$  BT < 205 K
- Filtering
  - Spatial homogeneity tests for filtering DCC edges
    - $\sigma_{VIS} < 3\%$  and  $\sigma_{BT} < 1K$  for the 3x3 pixel block surrounding a DCC pixel
  - Angular thresholds for capturing the most Lambertian part of DCC
    - SZA < 40°, VZA < 40°, 10° < RAA < 170°

#### • Anisotropic Corrections

- Apply COS(SZA) and Earth-Sun distance corrections
- Apply Hu Angular Direction Model (ADM) to scale all DCC pixel radiances to a common set of solar and viewing conditions
- Compile DCC pixels into monthly probability distribution functions (PDFs) and compute their modes
- Derive mean and standard deviation of monthly DCC mode timeseries
  - Use the most stable record of the reference instrument (first 3-5 years)



NOAA-20 VIIRS I1 (0.65 µm) DCC mode

This study uses NOAA-20 VIIRS L1B Collection 2 products from NASA Land SIPS

- Regional variation of DCC mode is ~1%
  - brightest over 0°E longitude
  - TWP DCC radiances are lower

#### Reference DCC Mode Radiances ( $L_{VIIRS,Mode}$ ) for GEO Domains

NOAA-20 VIIRS Global Band		bal	GOES-W (e.g., GOES-15, 11)		GOES-E (e.g., GOES-12, 16)		0°E (e.g., Met-11, 10)		41°E (e.g., Met-8)		57°E (e.g., Met-7)	
	Mean	1- <b>o</b> %	Mean	1- <b>o</b> %	Mean	1- <b>o</b> %	Mean	1- <b>o</b> %	Mean	1- <b>o</b> %	Mean	1- <b>o</b> %
M3 (0.48 μm)	572.75	0.50	571.98	1.27	573.78	0.79	576.54	0.86	570.60	0.91	572.80	0.92
M4 (0.55 μm)	508.55	0.60	508.24	0.96	509.47	0.76	511.11	0.86	506.40	1.27	508.50	0.93
M5 (0.67 μm)	431.49	0.53	430.82	1.03	431.85	0.68	434.30	0.78	430.26	1.11	432.05	0.81
M7 (0.86 μm)	268.39	0.42	267.55	0.65	269.29	0.41	270.31	0.62	267.67	0.67	269.62	0.62
I1 (0.65 μm)	441.38	0.59	440.35	0.91	442.25	0.69	443.89	0.69	442.84	0.84	442.09	1.24
NOAA-20 VIIRS Band		82°E (e.g., INSAT-3D)		100°E (e.g., FY2G)		128°E (e.g., COMS)		(e.	140°E (e.g., MTSAT-2,			
			Mean	1- <b>o</b> %	Mean	1- <b>o</b> %	Mean	1- <b>o</b>	· % I	Mean	1- <b>o</b> %	
	M3 (0.48 μ	m)	570.60	1.24	569.37	0.93	571.72	1.0	06 5	70.81	0.87	
	M4 (0.55 μ	m)	505.63	1.34	504.91	1.16	507.06	1.0	)5 5	06.55	1.03	
	M5 (0.67 μ	m)	430.30	1.00	429.43	0.93	430.92	0.9	98 4	29.90	0.86	
	M7 (0.86 μ	m)	267.36	0.68	267.83	0.66	267.93	0.7	72 2	67.57	0.62	

- For visible channel (0.65 μm), two sets of reference mode values are provided based on M5 and I1 bands
- Units of these mode radiances are Wm<sup>-2</sup>μm<sup>-1</sup>sr<sup>-1</sup>

### VIIRS M5 vs I1

- Both are calibrated using the same solar diffuser onboard
- I1 band has higher spatial resolution than M5
- I1 SRF has a better spectral match with MODIS band 1 and visible channels in new generation GEO imagers
- Do you get the same GEO calibration slope using M5 and I1 as reference???
  - M5 is brighter (0.75%) than I1
  - GEO calibrations referenced to 11 and M5 bands should exhibit the same magnitude of difference



# GEO Imager DCC pixel identification and Processing

- DCC method does not require coincident measurements between GEO and VIIRS
- Five GEO images per day surrounding the 1:30 PM local time (equator crossing time of NOAA-20) are used for DCC sampling
- Angular thresholds and spatial homogeneity tests are the same as that used for the VIIRS DCC samples
- IR BT threshold may need to be adjusted for GEO
  - to account for any differences in SRFs and calibration of the IR channels between GEO and VIIRS
- VIIRS based reference mode radiances must be adjusted to account for the SRF differences (apply SBAF) between the GEO and VIIRS visible channels

#### **IR BT threshold normalization**



- GOES-16 ABI and Himawari-8 AHI IR channels would measure DCC BT slightly warmer than NOAA-20 VIIRS M15, provided they are all consistently calibrated
- A DCC pixel with a BT of 205 K measured by VIIRS M15 is recorded as 206.1 K by GOES-16 ABI B14
- For consistent DCC sampling between GEO and VIIRS, the GEO IR BT threshold must be adjusted to equivalent VIIRS BT
- The magnitude of BT adjustment might change over time depending upon the temporal stability of the IR calibration onboard GEO and VIIRS

### IR BT threshold vs DCC Samples



- IR BT threshold affects sample size
- Exponential relationship between sample size and BT threshold
- Adequate and consistent sampling is a key to the success of DCC method

#### IR BT threshold vs PDF mode



- BT threshold affects DCC PDF mode
  - Lower BT threshold results in a higher mode value
  - VIS/NIR bands PDF modes are more stable (~0.1%/K) compared to SWIR bands (~0.9%/K)

#### Advantages of IR BT threshold normalization

- Normalizing the GEO IR BT to that of the VIIRS IR channel
  - mitigates any dependency of the DCC PDF mode on BT threshold, thereby improves the inter-calibration accuracy
  - ensures consistent DCC sampling between the reference VIIRS and target GEO imagers

### **Angular Transformations**



- Prior to PDF formulation, DCC pixel radiances are corrected for anisotropy using Hu ADM
- Hu ADM reduces the temporal variability in the DCC mode response by more than 30% in VIS/NIR bands

$$L_{corrected} = \frac{L_{observed}}{d^2 \times \cos(SZA) \times BRF(SZA, VZA, RAA)}$$

#### BRF is a bidirectional reflectance factor from Hu ADM LUT

### PDF bin size ( $\Delta_{PDF}$ ) optimization



- Smaller △<sub>PDF</sub> results in spiky PDFs (with multiple peaks) and may result in noisier DCC time series
- Larger △<sub>PDF</sub> gives smoother PDFs, but may not detect small magnitude drifts

#### PDF bin size and drift detection



- DCC can detect calibration drifts greater than PDF bin size
- $\Delta_{PDF}$  equal to 0.2-0.4% of mode is optimal
- Magnitude of  $\Delta_{PDF}$  may need to be changed over time as sensor degrades

#### Deseasonalization



- Some GEO domains (e.g., Meteosats at 0°E) exhibit noticeable seasonality in DCC time series
- Ratio-to-moving-average method for seasonal correction
  - only seasonal components are removed
  - absolute mode values and temporal trends are preserved
- Temporal variability is reduced significantly

### Computation of monthly GEO calibration slope

Eqn. 1  $L_{GEO,Mode,reference} = SBAF \times L_{VIIRS,Mode} (Wm^{-2}\mu m^{-1}sr^{-1})$  From Table in slide 8 Constant in time

Eqn. 2 
$$\gamma_{cross-cal} = \frac{L_{GEO,Mode,reference}}{L_{GEO,Mode,observed}}$$
 (unitless)  
Eqn. 3  $\gamma_{GEO,cal-slope} = \frac{L_{GEO,Mode,predicted}}{C_{GEO,Mode,observed}}$  ( $Wm^{-2}\mu m^{-1}sr^{-1}/Count$ )

*L* stands for Radiance*C* represents Counts

 $L_{VIIRS,Mode}$  is the reference DCC mode radiance derived from VIIRS measurements  $L_{GEO,Mode,reference}$  is the estimated mode radiance for a GEO after adjusting  $L_{VIIRS,Mode}$  for spectral differences  $C_{GEO,Mode,observed}$  is the observed GEO DCC mode count (*Space count is subtracted from GEO counts before computing the mode*)

- Inter-comparison between GEO and VIIRS spectral channels can be performed by comparing their monthly mode values
- If both imagers DCC modes are in radiance units, their ratio provides the cross-calibration coefficient  $(\gamma_{cross-cal})$
- If GEO DCC modes are in counts, the ratio of VIIRS mode radiances over GEO mode counts estimates the monthly calibration slope for the GEO imager  $(\gamma_{GEO,cal-slope})$
- Prior to these operations,
  - VIIRS mode radiance must be corrected for spectral differences using SBAF
  - Space count or sensor offset must be subtracted from the GEO counts

#### **Computation of SBAF**

Earth Spectra (SCIAMACHY)	Reference (X-axis) SRF	Units
Arabia 1	Meteosat-9	Pseudo Radiance
Arabia 2	NOAA-10-AVHRR	Pseudo Scaled Radia
Badain Jaran Desert	NOAA-11-AVHRR	
Dome C	NOAA-12-AVHRR	
Greenland Central	NOAA-14-AVHRR	
Greenland South	NOAA-15-AVHRR	Spectral Filter 1
Libya 1	NOAA-16-AVHRR	Min um 1 0 24
Libya 4	NOAA-17-AVHRR	May um 1 1 75
Libyan Desert	NOAA-18-AVHRR	
Niger 1	NOAA-19-AVHRR	Min Rad 1: 0.0
Sonoran Desert	NOAA-20-VIIRS-V	Max Bad 1: 1000.0
Uyuni Desert	NOAA-20-VIIRS-V	1000.0
All-sky Tropical Land	NOAA-21-VIIRS-V	Min Ref 1 0.0
All-sky Tropical Ocean	NOAA-6-AVHRR	Max Ref 1 1.0
Clear-sky Tropical Oce	Central Wavelength:	
Marine Water Cloud	0.65 Micron (I1) 🗸	
Marine Ice Cloud		
Approximate DCC		Spectral Filter 2
Precise DCC	Target (Y-axis) SRF	Min um 2 0 24
North Pole	GIVIS-5	Max um 2 1 75
South Pole	GOES-10	
Global	GOES-11	Min Rad 2 0.0
Evergreen Needleleaf	GOES-12	Max Rad 2 1000.0
Evergreen Broadleaf F	GOES-13	
Deciduous Needleleaf	GOES-14	Min Ref 2 0.0
Deciduous Broadleaf F	GOES-15	Max Ref 2 1.0
Mixed Forests	GOES-16	
Closed Shrublands	GOES-17	
Open Shrublands	GOES-5	
Woody Savannas	GOES-6	
Savannas	GOES-7	
Grasslands	GOES-8	
Permanent Wetlands	GOES-9	
Croplands	Limenum O ALU	
Cropland/Natural Vege	0.64 Mieron (2) st	
Barren	0.04 MICION (2) V	

Cont	rols
Force Fit	
Linear	
2nd Order	
3rd Order	

 CERES IGCG provides an online SBAF computation tool based on SCIAMACHY hyperspectral datasets over Earth targets

https://cloudsway2.larc.nasa.gov/cgibin/site/showdoc?mnemonic=SBAF

#### SBAF computation steps

- 1. Select "Precise DCC" from the Earth Spectra column
- 2. Select "NOAA-20-VIIRS-V2F" for Reference (X-axis) SRF
- 3. Select appropriate Central Wavelength for reference VIIRS SRF
- 4. Select target GEO imager for Target (Y-axis) SRF
- 5. Select appropriate Central Wavelength for target GEO SRF
- Select "*Pseudo Radiance*" from Units column for radiance SBAF
- 7. Select "Force Fit" for Regression analysis
- 8. Click the **Plot** button

Plot

#### **DCC SBAF examples**



- VIIRS I1 SRF matches very well with GOES-16 ABI band 2 SRF
- Spectral corrections between VIIRS I1 and GOES-16 ABI band 2 is only 1%
- DCC SBAF between VIIRS M5 and ABI band 2 is 4%



Difference is due to VIIRS M5 vs I1 calibration bias (see slide 9)



Gain, (Wm<sup>-2</sup>μm<sup>-1</sup>sr<sup>-1</sup>)/Count

#### Comparison between DCC-IT and ATO-RM



- ATO-RM and DCC-IT trends show excellent agreement in estimating calibration slope for GOES-16 ABI VIS band
- Temporal trends disagree between the two methods
- Likely caused by a small drift observed in NOAA-20 VIIRS I1 band calibration in Collection 2
  - DCC-IT is not impacted by reference sensor calibration drifts, thereby revealing the true GEO degradation over time
  - ATO-RM may be influenced by any short-term calibration drifts in the reference VIIRS instrument

#### DCC-IT for inter-band calibration



- Very low atmospheric absorption over DCC
- Nearly flat reflectance spectra at VIS/NIR wavelengths (M1-M7 channels, <1.0 μm)</li>
- Allows inter-band calibration between nonoverlapping spectral channels



- Met-11 Ch 2 (0.81 μm) has a minimal overlap with VIIRS M7
- Met-11 Ch 2 can be intercalibrated with both VIIRS M5 or M7

### DCC-IT for inter-band calibration (contd.)



- Inter-calibration of Met-11 NIR channel reveals 1% relative radiometric bias between M5 and M7 bands of VIIRS
- Direct inter-comparison of DCC modes between M5 and M7 (slide 8) also estimates a 0.9% bias between these two channels
- Very robust and well-behaved SBAF regressions (no absorption and Lambertian reflectance)
- Not feasible to achieve this level of inter-band calibration with ground targets (atmospheric effects)



### **DCC Calibration in Reflectance**

- Scenario 1: Using L1B reflectance data for both VIIRS and GEO
  - Most preferred method (no dependency on reference solar spectra)
  - e.g., VIIRS, GOES-16 ABI, and SCIAMACHY are all reflectancebased calibration

 $\gamma_{cross-cal,reflectance}$ 

 $\frac{\rho_{VIIRS,Mode \times SBAF_{reflectance}}}{\rho_{GEO,Mode}}$ 

- ho is reflectance
- *ρ<sub>VIIRS,Mode</sub>* is the reference VIIRS mode reflectance which can be derived from VIIRS DCC PDFs in reflectance, or from mode radiance (slide 8) as follows:

 $\rho_{VIIRS,Mode} = L_{VIIRS,Mode} / E_{SUN}$ 

#### **VIIRS E<sub>SUN</sub> values using Thuillier 2003 Spectra**

NOAA-20 VIIRS band	E <sub>SUN</sub> (W m <sup>-2</sup> μm <sup>-1</sup> sr <sup>-1</sup> )
M3 (0.48 μm)	629.313
M4 (0.55 μm)	581.771
M5 (0.67 μm)	481.029
M7 (0.86 μm)	302.320
I1 (0.65 μm)	505.409

#### NASA Langley's E<sub>SUN</sub> computation tool

https://cloudsway2.larc.nasa.gov/cgibin/site/showdoc?mnemonic=SOLAR-CONSTANT-COMPARISONS

NOAA-20 VIIRS uses Thuillier 2003 solar spectra for computing  $\mathsf{E}_{\mathsf{SUN}}$  values

- $\rho_{GEO,Mode}$  is a monthly GEO DCC mode in reflectance unit
- SBAF<sub>reflectance</sub> is the spectral correction in reflectance (Select "Pseudo Scaled Radiance" from Units column on the SBAF tool)

(unitless)

### DCC Calibration in Reflectance (contd.)

#### • Scenario 2: Using GEO L1B radiances

- Convert GEO Mode radiance to reflectance using E<sub>SUN</sub>
- Apply the solar spectra (Thuillier 2003) used by the reference NOAA-20 VIIRS instrument to compute GEO  $E_{SUN}$  values

 $\gamma_{cross-cal,reflectance} = \frac{\rho_{VIIRS,Mode \times SBAF_{reflectance}}}{\rho_{GEO,Mode}}$ (unitless)

ABI E<sub>SUN</sub> values using Thuillier 2003 Spectra

GOES-16 ABI band	E <sub>SUN</sub> (W m <sup>-2</sup> μm <sup>-1</sup> sr <sup>-1</sup> )
B1 (0.47 μm)	648.717
B2 (0.64 μm)	509.719
B3 (0.87 μm)	303.909

#### NASA Langley's E<sub>SUN</sub> computation tool

https://cloudsway2.larc.nasa.gov/cgibin/site/showdoc?mnemonic=SOLAR-CONSTANT-COMPARISONS

### **Uncertainty Analysis**

- Major sources of uncertainty for GEO-VIIRS intercalibration
  - Uncertainty in the reference mode value from VIIRS (U<sub>Ref</sub>)
    - Temporal standard deviation (1-Sigma) of DCC time series (DCC reflectance natural variability over the GEO domain)
  - SBAF uncertainty (U<sub>SBAF</sub>)
    - Standard error of Regression Slope from SBAF tool
  - Temporal regression uncertainty (U<sub>RegFit</sub>)
    - Standard error (1-Sigma) of GEO calibration slopes temporal regression
- Absolute radiometric uncertainty of NOAA-20 VIIRS (±2% for RSB) is not considered
- Total uncertainty ( $U_{Total}$ ) is computed by summing individual uncertainties in quadrature to  $U_{Total} = \sqrt{U_{Ref}^2 + U_{SBAF}^2 + U_{RegFit}^2}$

#### GOES-16 ABI Band 2/VIIRS I1 Calibration Uncertainty

Source	Value (%)
<b>U</b> <sub>Ref</sub>	0.69
<b>U</b> <sub>SBAF</sub>	0.02
<b>U</b> <sub>RegFit</sub>	0.54
<b>U</b> <sub>Total</sub>	0.88

Other sources of uncertainty could be from BT normalization, SCIAMACHY relative calibration inconsistency between channels, SRF changes in orbit, etc.

### **GSICS Products**

- Monthly netCDF files containing
  - GEO imager DCC PDF data and statistics
  - Attributes:
    - **GEO sensor details:** space count, channel information, linear/squared count, scaled radiance or count bit resolution, BT threshold, homogeneity test parameters, ADM, etc.
    - **Reference sensor details:** band information, reference mode value and units, L1B collection, NASA or NOAA dataset, etc.

#### Summary

- The newly revised GSICS DCC ATBD offers several improvements:
  - Extends the methodology to all spectral channels between 0.4-1.0  $\mu m$
  - Inter-calibration uncertainty is reduced by applying
    - *IR BT threshold normalization between GEO and VIIRS*
    - deseasonalization of monthly DCC responses
  - Uses the most recent and well-calibrated NOAA-20 VIIRS sensor as a reference instrument for DCC characterization
  - Provides more comprehensive details on the formulation and implementation of DCC method
    - Reference DCC modes for multiple GEO domains, SBAF computation, uncertainty analysis, GSICS DCC products
  - In future, a dedicated ATBD will be presented for calibrating SWIR bands using DCC

#### **Future activities**

- ATBD will be ready by July of 2021
- Future monthly meetings will discuss the agency-specific GSICS DCC product implementation and paper (fall of 2021)