

FY-3F/OMS pre-launch calibration and instrument performance

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10 March 2022 GSICS UVN Spectrometer Breakout Session





OMS Limb pre-launch calibration and instrument performance

- OMS Nadir Specifications and observation modes
- Conclusion and next plan



Introduction to OMS limb instrument



OMS-limb is a spectrometer to be carried on FY-3F satellite working in the band of 290-500nm. By detecting the 15-60km limb ultraviolet / visible band spectral radiation of the atmosphere in the daylight, the vertical distribution information of O3, NO2, SO2 and stratospheric aerosol profiles can be retrieved.



Location of OMS Limb on the satellite



Detection gas type of OMS Limb

Variable	Explanation	
BrO	UV spectrometry. BrO lines around 300 nm. Limb sounding mechanically or electronically	
HCHO mole fraction	UV spectrometry. HCHO lines around 350 nm. Limb sounding mechanically or electronically	
CIO	UV Spectrometry. CIO lines around 300 nm.	
Atmospheric temperature	UV and VIS spectrometry.	
NO2 mole fraction	UV and VIS spectrometry. Several lines in the ranges around 220 nm and 400 nm.	
O3	UV and VIS spectrometry. Ozone lines in the bands around 340 nm (Huggins).	
PSC occurrence	UV and VIS spectrometry.	
SO2 mole fraction	UV spectrometry. SO2 lines around 350 nm.	
Specific humidity	cific humidity UV and VIS spectrometry. Limb sounding.	
Aerosol mass mixing ratio	UV and VIS spectrometry.	
Aerosol volcanic ash	UV and VIS spectrometry;	

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OMS limb observation mode





Global Space-based Inter-Calibration System



		OMS Limb sp	ecifications	
-	No.	Test items	Technical requirement	
	1	Spectral range / nm	290-500	
	2	Spectral resolution / nm	0.6	
	3	Spectral sampling interval	Continuous sampling pixel by pixel	Band1: 290-400pm FW/HM0.6pm
	4	Wavelength calibration accuracy / nm	0.01	Band2: 390-500nm, FWHM0.6nm Band3 (polarization): 290-500nm, FWHM4-40nm
	5	Spatial resolution / km	3 (vertical, i.e. the height direction of the Limb of the earth)	
	6	Instantaneous field of view / °	2.3 (horizontal) × 0.045 (vertical)	\
	7	Dynamic range	10 ⁵	
	8	Relative radiometric calibration accuracy	Better than 2%	
	9	Calibration accuracy of diffuse reflector	Better than 3%	
	10	Absolute radiometric calibration accuracy	Better than 3%	
	11	Signal to noise ratio	> 300@0.1mw /cm ² × sr × nm (radiance)	

OMS limb pre-launch calibration: Dark current







Difference model between imaging pixels DN and dark reference column pixels DN0



In the heat balance test on May 10-20, 2021, the monitoring test of ozone Limb spectral performance with vacuum / atmosphere and temperature was completed by using the internal mercury lamp of the instrument.





The bandpass of the instrument in the characteristic spectral line under vacuum and atmosphere, and the temperature range of 4 ~ 25 $^\circ\!\!C$ under vacuum.

OMS limb pre launch calibration - Radiometric Calibration

Global Space-based Inter-Calibration System







Radiation calibration of OMS limb

OMS limb pre launch calibration BRDF of Reference board



The two-dimensional turntable is used to drive the instrument to rotate, and the response of the diffuse board of the instrument at different angles is obtained.



OMS limb diffuse board angle characteristic calibration test





Fitting results and errors of angular characteristics of main diffuser of Band 1







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Scientific Objective

OMS-nadir is a payload on FengYun-3F in low Earth orbit that provides daily global information on concentrations of trace gases and aerosols. The selected wavelength range for OMS-nadir allows observation of atmospheric constituents, including the total column of O3, NO2, SO2, and O3 profile.

Instrument overview

- ✓ Hyper-spectral imagers make images in 2 spectral bands
- \checkmark No scanning mirrors cross track
- ✓ Scanning in flight direction (Push broom)
- ✓ Wide cross flight IFOV
- ✓ Narrow along flight IFOV
- ✓ 2D detectors (CCD)
- ✓ 2D grating spectrometer



The OMS-nadir instrument







OMS-nadir Instrument Specifications

Band coverage	UV1: 250-300nm UV2:300-320nm VIS: 320-500nm	
Swath Width	2900km	
Total field of view	112°	
Nadir ground pixel size (along track \times across track)	UV1: 21 km × 28 km UV2: 7 km × 7 km VIS: 7 km × 7 km	
Spectral resolution	UV1: 1 nm UV2: 0.5 nm VIS: 0.5 - 0.6 nm	
Polarization sensitivity	Depolarized using a scrambler	
Global coverage	1 day	
Local time	Descending node of 10:00 a.m.	



Scientific observation modes at the day side of the orbit

- \checkmark Collecting the sunlight reflected by the Earth.
- \checkmark Collecting the dark current from shielded pixels at the edge of the detector.

Calibration observation modes at the night side of the orbit

Sun measurements with two QVD diffusers

- ✓ One of the diffusers is for Sun calibration observation, acquiring the data to perform in-orbit spectral and radiometric calibration.
- \checkmark The other is to monitor optical degradation.

White light source (WLS) measurements with a diffuser

- ✓ Measuring changes in the CCD performance, in particular the pixel-to-pixel response non-uniformity.
- ✓ Monitoring radiometric throughput.

Led measurements

✓ Monitoring the CCD pixel behavior and linearity of the detector and electronics.



Conclusion and next plan

- Pre-launch calibration of engineering model of FY-3F/OMS was finished.
- Pre-launch calibration of flight model of FY-3F/OMS will be carried out in May, 2022.
- FY-3F is scheduled to launch at the end of 2022;
- In-orbit and inter calibration algorithms are under developing.









Thank you for the attention! Email: liyuan@cma.gov.cn



