Third Lunar Calibration Workshop 16-19 November 2020

Minutes of meeting – Webex sessions

1-18-2021

16/11	Lunar model	development	
Item	Chair: Tom St	tone / Sebastier	Wagner
16	T. Stone / S. Wagner	USGS / EUMETSAT	Introduction to the workshop and to the session
Seb we			ar calibration mini-sessions, which are intended to bridge the gap
			ration Workshop - which is now hoped to take place in 2021.
	ping (XIOPM)		
	kuyama (JMA)	-0)	
	nlers (ESA-EST		
Chris (?	d Fougnie (EUN	NEISAI)	
	ntine Lukashin (
	Woolliams (NPL		
Erin Ly		-)	
	ng Yu (NOAA)		
	u (NOAA)		
	opp (UCÁR)		
•	Qian (NOÁA)		
	í Tanaka (JMÁ)		
Hirokaz	u Yamamoto (A	AIST / GSJ)	
Hugh K	ieffer (Celestial	Reasonings)	
	oodward (NIST	.)	
	Kodera (JMA)		
	urpie (UMBC/N		
		aido University)	
	ce Ong (NASA)		
	Neneman (ESA	.)	
	ouvet (ESA) Dobber (EUME		
	Burgdorf (Uni Ha		
	ka Imai (AIST)	amburg	
	w Kowalewski (I	NASA)	
	Krijger (ESS)	,	
	u (KMA)		
	Etxaluze (RAL)		
	Sinclair (NPL)		
	Lamquin (ACR		
	hilipps (EUMET	'SAT)	
	Taylor (NPL)		
	ien Wagner (EU		
	Adriaensen (VII		
	n Maxwell (NIS ⁻ Brown (NIST)	1)	
	Miller (CSU)		
	eong Oh (KMA)		
	ing Choi (NOAA		
		., ESTEC, Japan)	
	Marbach (EUM		
	s Müller (MPE)		
	wison (EUMETS	SAT)	
	one (USGS)		
	buyama (AIST)		
	ang (UMD)	•	
	ng Xiong (NAS/	4)	
	ng (NASA)		
rucan	(XIOPM)		

Yuan Li (CMA) Yu Zhang (?) Zhipeng Ben Wang (NOAA)

	Toru Kouyama	AIST	Lunar Calibration Activities at AIST - An update on SP Lunar Model
	Rouyania		Model
which ł This ha	has been used to	o derive a hypers generate a reflec	nodel, based on the Spectral Profiler onboard Selene (Kagayu), spectral radiance map of the Moon's surface from 516-1600nm. stance map and can also be integrated to model the lunar irradiance
explore For ten Perforn	er nporal trending, nances for the S	the accuracy is s P model = simila	he degradation of a small sat sensor and Hayabusa-2 asteroid imilar to the ROLO. ar to the ROLO (within 1 or 2%). However, there is an issue when a model has been corrected with the ROLO model.
			A website – maybe in 2021 – also available from Toru directly. ts of observation time, position, SRF, spatial resolution to drive SP
	xpressed an inte was warmly weld		odel joining the GIRO lunar irradiance model inter-comparison,
Pixel-to termina	• •	on of modelled a	nd observed radiances show some large biases (~20%) near the
16b	Sarah Taylor	NPL	The Lunar Irradiance Model of ESA (LIME)
	· ·		
			I-based measurements with CIMEL photometer in Tenerife. of a spectral dependency on the c-coefficients.
Based Instrum	on ROLO mode	l – with additions e = 340-1640nm	of a spectral dependency on the c-coefficients. – including polarisation capabilities
Based Instrum Non-lin Tempe	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity	l – with additions e = 340-1640nm considered neglig / of detectors cha	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation
Based Instrum Non-lin Tempe Irradiar	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity	 I – with additions e = 340-1640nm considered neglig of detectors chatcher characterised with 	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity nece responsivity Phases -90° to + d using Langley	 I – with additions e = 340-1640nm considered neglig of detectors chatcher characterised with the second s	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% as 2.0-5.0 in 2hr – phase variations corrected – how?
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke Iterative Uncerta	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity nce responsivity Phases -90° to + d using Langley e atmospheric c ainty Analysis ac	I – with additions e = 340-1640nm considered neglig of detectors cha characterised wi -90°, Plot over Airmas orrection to TOA ccounts for correl	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% as 2.0-5.0 in 2hr – phase variations corrected – how? radiance lation within Langley plot.
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke Iterative Uncerta Now up	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity nce responsivity Phases -90° to + d using Langley e atmospheric c ainty Analysis ac odating model w	I – with additions e = 340-1640nm considered neglig of detectors cha characterised wi -90°, Plot over Airmas orrection to TOA	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% as 2.0-5.0 in 2hr – phase variations corrected – how? radiance lation within Langley plot. observations
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke Iterative Uncerta Now up 95% ur	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity nce responsivity Phases -90° to 4 d using Langley e atmospheric c ainty Analysis ac odating model w ncertainty ~2% (I – with additions e = 340-1640nm considered neglig of detectors chatcher characterised with -90°, Plot over Airmast orrection to TOA ccounts for correl ith 2.5years new k=2) on absolute 	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% ss 2.0-5.0 in 2hr – phase variations corrected – how? radiance lation within Langley plot. observations
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke Iterative Uncerta Now up 95% ur To fill th	on ROLO mode nent bands rang learity <0.1% - c rature sensitivity ce responsivity Phases -90° to + d using Langley e atmospheric c ainty Analysis ac odating model w neertainty ~2% (he spectral gaps brighter than GI	I – with additions e = 340-1640nm considered neglig y of detectors cha characterised wi -90°, Plot over Airmas orrection to TOA ccounts for correl ith 2.5years new k=2) on absolute s between the CII RO in VIS/NIR -	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% as 2.0-5.0 in 2hr – phase variations corrected – how? radiance lation within Langley plot. observations irradiance
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke Iterative Uncerta Now up 95% ur To fill tl ~7/8%	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity hases -90° to 4 d using Langley e atmospheric c ainty Analysis ac odating model w hacertainty ~2% (he spectral gaps brighter than GI Highlight differ update spectra	I – with additions e = 340-1640nm considered neglig y of detectors cha characterised wi -90°, Plot over Airmas orrection to TOA ccounts for correl ith 2.5years new k=2) on absolute s between the CII RO in VIS/NIR - ences between d	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% as 2.0-5.0 in 2hr – phase variations corrected – how? radiance lation within Langley plot. observations irradiance MEL bands, the Thuillier solar irradiance spectrum is used. also compared with VITO/CNES implementation of ROLO
Based Instrum Non-lin Tempe Irradiar Lunar F Tracke Iterative Uncerta Now up 95% ur To fill th ~7/8% Plan to + polar	on ROLO mode nent bands rang earity <0.1% - c rature sensitivity Phases -90° to + d using Langley e atmospheric c ainty Analysis ac odating model w neertainty ~2% (he spectral gaps brighter than GI Highlight differ update spectra isation	I – with additions e = 340-1640nm considered neglig y of detectors cha characterised wi -90°, Plot over Airmas orrection to TOA ccounts for correl ith 2.5years new k=2) on absolute s between the CII RO in VIS/NIR - 3 ences between d I interpolation (us	of a spectral dependency on the c-coefficients. – including polarisation capabilities ible aracterisation needed as no thermal stabilisation th standard uncertainty ~1% as 2.0-5.0 in 2hr – phase variations corrected – how? radiance lation within Langley plot. observations irradiance MEL bands, the Thuillier solar irradiance spectrum is used. also compared with VITO/CNES implementation of ROLO lifferent implementations of ROLO

Q: Experience of high-frequency atmospheric variations during Langley Plots?

• Site chosen for stability + uncertainty in Langley plots carefully monitored = key!

2% accurate with 95% confidence on the absolute scale. To reproduce a trend it would be less than 1%

Q: Detectors?

٠	Silicon + InGa	Si	
16c	Matthijs Krijger	ESS	A new lunar irradiance model based on SCIAMACHY and RELAB data
Derive	d Lunar Extende	•	ral Reflectance model (LESSSR) to fit SCIAMACHY observations
٠			different phase-dependence
٠		/ith 5nm resolutio	
•	•	nase angle valida	ined Inm (5% beyond)
•		EUMETSAT? - 1	
·			
		with SCIA acqui sation sensitivity.	sitions was the degradation in time and the loss of throughput.
Validat	ion against GO	ME-2 observation	s reveals wavelength-dependent bias ~±1%
• and a			ngitude sampled by SCIAMACHY and GOME-2?
	-		
		rbed samples. Co d by RELAB data	ould be an issue for modelling the soil reflectance when considering
16d	Hugh Kieffer	Celestial Reasonings	SLIMED: a continuous lunar model algorithm using many instruments
Iterativ "Adding	e – adjusted gai g rigorous uncer	tainty analysis in	ROLO. nent to bring them to a common scale – until convergence creases the workload by a factor of ~3" ly in 2D in ROLO.
			and SLIMED at 0 libration for different phases (slide 14).
data pr	ovider or on Hu or updated as	gh's own estimat	ach instrument dataset. It is based on available information from es and judgement (which would need to be confirmed by data coeff avoids giving an unrealistic weight to a specific instrument in
Q: Will •	That's the plan	d data be shared – to publish it al the SLIMED mo	I. A publication is under preparation. Hugh is looking for an US
Q: Hov •	/ do you handle Relies on instr		o have dealt with this.
16e	Kevin Turpie	University of Maryland	Update on the air-LUSI project to achieve absolute calibration with lunar models
Curren Small a	gh-accuracy Mc tly <1% (k=1) 4 atmospheric cor	oon observations 15-1000nm (targe rection max 3% f	from high-altitude aircraft eting <0.5%) with 3.7nm resolution rom molecular scattering mosphere (and almost all water), but below most ozone

Engineering flight campaign carried out with two ~2-hours flights Demo flight campaign carried out with 5 consecutive nights (= 5 different phases) with ~2 hours flights.

Air LUSI lunar irradiance measurement: below 1% uncertainty between ~400nm and ~970nm

Jason from NOAA: any plan to release the data? Kevin: yes. Timescale is to be confirmed (~1 month).

Q: Plans to extend into SWIR?

• Would need additional focal plane – e.g. part of Air-LUSI-2?

16f	All participants	Discussion

Use of Reference Spectrum to benchmark model comparisons

• Potential use of Air-LUSI observations to provide a Reference Spectrum

How well can we retrieve lunar irradiance from Moon observations? Modellers shall provide the focus of their models:

- Absolute Calibration
- Calibration trending
- Inter-channel calibration

Need for modellers to provide details on how the model handles:

- Moon reddening
- Libration

Hugh: Lunar Calibration Community should aim to replace ROLO model v3.11g with consensus-agreed reference model

Matthijs: Would be helpful to be able to provide viewing geometry as input to GIRO (and other models) - to disconnect the model from the viewing geometry

• **R.LCWS.2020.16f.1:** Model developers to consider how their models' inputs can be decoupled from the observations to allow inter-comparison and benchmarking on the various steps of lunar calibration.

Could also create a fake instrument, but all models should be able to consider specific observation geometry – e.g. one air-LUSI case

• **A.LCWS.2020.16f.1**: EUMETSAT (S. Wagner) to liaise with USGS (T. Stone) to realign the GIRO with respect to the last version of the ROLO model.

Kevin Turpie proposed that potential users of the Air-LUSI observations should let NASA know how relevant these are to the development of lunar calibration activities.

• **A.LCWS.2020.16f.2**: EUMETSAT (S. Wagner) to propose letter of recommendation by GSICS to NASA to highlight the benefits to continue the Air-LUSI campaigns to lunar calibration.

Model Inter-Comparison Exercise:

- Seb is planning web meeting for participants in first 2 weeks of December
- Will presents results of inter-comparison at future public meeting

• **A.LCWS.2020.16f.3**: EUMETSAT (S. Wagner) to report on the Model Inter-Comparison Exercise at the next GSICS annual meeting + Lunar Calibration Community.

Q: Possibility to establish public mailing list for lunar calibration community?

- e.g. list of participants
- **A.LCWS.2020.16f.4**: EUMETSAT (S. Wagner) to check possibilities to create a distribution list for the Lunar Calibration Community.

Participants to let us know if they don't want email or presentations shared

• **R.LCWS.2020.16f.2:** EUMETSAT (S. Wagner) to investigate the possibility to revisit the mechanism to share the GIRO model, whilst respecting the existing license agreement.

Q: NOAA progress on lunar radiance modelling? A: on hold for the time being

- **R.LCWS.2020.16f.3:** Satellite operators to consider providing data to Hugh Kieffer for further processing with the SLIMED model.
- Could also be pursued through GSICS to be followed-up offline

17711	Mission monitoring using Lunar Calibration
Itom	Chairy Sabastian Wagnar

Item	Chair: Sebast	ien wagner			
17	Sebastien	EUMETSAT	Introduction to the session		
A	Wagner				
Attende	Attendees – bold – present today – others copied from previous days				
	usivered (EUME	TOAT)			
	usivand (EUME Indro Burini (El				
	pping (XIOPM)	JWIETSAT)			
	Dkuyama (JMA))			
	hlers (ESA-ES				
	nd Fougnie (EU				
Chris (,			
•	antine Lukashir	n (NASA)			
	anze Seibert (U		nburg)		
	Smith (RAL)	•			
David	(?)				
Emma	Woolliams (NPL	_)			
-	/nch (?)				
	ing Yu (NOAA)				
	u (NOAA)				
	Copp (UCAR)				
	g Qian (NOAA)				
	i Tanaka (JMA)				
	zu Yamamoto (A				
	Kieffer (Celestia				
	Pradeep Thapliy				
	nes Frerick (ES				
	/oodward (NIST) i Kodera (JMA))			
r\azuk					

Kurihara Junichi (Hokkaido University) Kevin Turpie (UMBC/NASA) Lawrence Ong (NASA) Maciej Neneman (ESA) Marc Bouvet (ESA) Marcel Dobber (EUMETSAT) Martin Burgdorf (University of Hamburg) Masataka Imai (AIST) Matthew Kowalewski (NASA) Matthijs Krijger (ESS) Mireye Etxaluze (RAL) Minju Gu (KMA) Morven Sinclair (NPL) Nicolas Lamouin (ACRI) Pepe Philipps (EUMETSAT) Rakshith Shanbhag (EUMETSAT/TPZ) Roberto Colombo (University of Milano Bicocca) Roberto Bonsignori (EUMETSAT) Sarah Taylor (NPL) Sebastien Wagner (EUMETSAT) Stefan Adriaensen (VITO) Stephen Maxwell (NIST) Steven Brown (NIST) Steven Miller (CSU) Tae-Hyeong Oh (KMA) **Taeyoung Choi (NOAA)** Taichiro Hashiguchi (RESTEC, Japan) Thierry Marbach (EUMETSAT) Thomas Müller (MPE) Tim Hewison (EUMETSAT) Tom Stone (USGS) Tiger Yang (UMD) Toru Kouyama (AIST) Vincent Debaeker (EUMETSAT) Vinia Mattioli (EUMETSAT) Woordward (?) Xiaoxiong Xiong (NASA) Xu Geng (NASA) Yu Can (XIOPM) Yuan Li (CMA) Yu Zhang (?) Zhipeng Ben Wang (NOAA)

17a	Taichiro	RESTEC	Monitoring GCOM-C Radiometric Performances Using Lunar
	Hashiguchi		Calibration

Mission: 3 years of continuous observations. SGLI lunar calibration: achieved with a pitch manoeuver. For IRS sensor, a reconstruction method is needed.

Resulting Calibration coefficients show trends consistent with on-board reference within 1%?

Phase angle dependency is corrected through a parametrisation. The phase angle dependence is small for short wavelengths and gets larger for longer wavelengths (see slide 13).

Also compared results with AHI:

- SGLI was 15-20% darker (solid angle calculation issues?)
- Derived phase-angle correction from AHI & compared with SGLI approx 3% in SWIR band

Q: how to reconstruct image?

Use precise geometric model based on ground test data

٠	Use precise g	eometric model	based on ground test data
17b	Masataka Imai	AIST	Lunar Calibration Activities at AIST - Lunar calibration and micro satellites
satellit Obser Also cl The im degrad	tes. ve Moon with RI hecked inter-bai npact of tempera dation < 1%	SESAT + OOC nd ratio betweer ature was analys	sation for satellite instruments' degradation – especially small about once a month with abs phase ~ 10°±2.5° n OOC bands – consistent trend - validated with Railroad Valley sed to check potential correlations. After correction, OOC sensitivity in 405nm, but positive at 869nm
Q: Pha	ase angle range	? - see above	
Q: Are • •	Depends on ir Could also be	nstrument desig spectral effects	
17c	Maciej Neneman	ESTEC	Lunar Calibration and Sentinel-3 OLCI
Proces Missin OLCI-/ Residu Residu	ssing Facility – s g GIRO results A+B Observatio ual Stray Light =	see Remote Ser for OLCI-A obse ns consistent wi Total Irradiance n OLCI Quality V	y tuned, to optimise Moon views – will be introduced in Instrument hsing paper by Neneman et al., 2020 ervation ith LIME – mostly within ±2% uncertainty – except at Oa21 e/Disk Irradiance –1 – Oa21 very sensitive Norking Group are to perform further manoeuvres – e.g. with other
			dark levels, radiometry + nonlinearity
•	No smearing i w to explain sud Not sure – und Critical to use radiances are	n OLCI (already den change in C der investigation consistent solar obtained after a	nclude smearing due to sampling – similar to stray-light correction? corrected), some electronic cross-talk, but mostly optical straylight GIRO+LIME in Oa21 channel? n r spectra – re-sampled Wehrli spectrum for GIRO and LIME, as OLCI applying another solar irradiance spectrum (Thuillier). uring reflectance spectra, rather than irradiance
•		iment calibrati	lar irradiance spectrum used in the lunar irradiance models or ion should be documented and referenced when discussing
17d	Mireya Etxaluze Azkonaga	RAL	Deriving lunar irradiances from SLSTR lunar acquisition
Prelim	inary results		
SLSTF VISCA	R VISCAL reflec	om previous orb	ized on-ground pre-launch. bit. e with and without vicarious calibration (mostly PICS desert sites).

S3B VIS channels within 2% of LIME model without vicarious calibration (4% with vicarious calibration). S4 channel – S3B agree with LIME within 1.5%

S5 – agrees with LIME within 0.5%

S6 is ~10% lower than LIME, but vicarious calibration improves it

Q: How to handle different detectors?

- Only processed 1 image/detector so far can repeat for each detector and compare.
- Moon reconstruction and the interpolation method to reconstruct the moon is still work in progress.

Q: how to integrate irradiance from images?

• Differed to discussion section

17e	Jason Choi	NOAA	S-NPP and NOAA-20 VIIRS Instrument Trending using Lunar and Solar Diffuser Calibrations
	are results from ` /) - with lunar ca		d calibration – Solar Diffuser (SD) and Solar Diffuser Stability Monitor
Introdu			ed/observed solar radiance
•			ar observations ne solar diffuser degradation and its change in BRDF.
The F	factor corrects for	or some effects	s of the lunar phase (cosine function)
	s produced by lui are the beginnin		(GIRO) and the solar diffuser are very consistent except for some on.
			bration and solar diffuser are within 1-2% the behaviour is quite (between SNPP and N20) methods were applied to cross-check.
	calibration, a Kal har calibration.	man filter has	been implemented to account for a set of various methods, including
Moon	views not availat	ole to VIIRS du	Iring summer months
Q: Ca	use of seasonal o	oscillations in F	-factors (slide 8)?
•			 has not been corrected in operations yet – in discussion
17f	Fangfang Yu	NOAA	ABI lunar radiometric calibration
ABI ca	an scan the Moor		appears in the FOR
•	With 0.14 to 2.	•	les per image is in sample solid angle, oversampling factor, lunar irradiance
•	Carrieneve ve	ery sinali biase	s in sample solid angle, oversampling factor, funal infadiance
	interested of usi or response unife		OES: solar calibration validation, degradation trending, RVS, MTF,
GOES	-17 ABI cannot o	control focal pla	ane temperature consistently
Overs •		ery stable – so	escribed in 2 nd Lunar Calibration Workshop: oversampling factors are very consistent & normalised with respect
Phase	angle depender	nce increases v	with wavelength – up to 12% at 90° phase in the SWIR (slide 13)
	look contaminati shine correction After correctior	– impact very s	

Q: fuzzy edges of B04 Moon image?

• Due to detector selection not being compensated in processing of lunar images

Q: solid angle calculation?

- Use Angular Separation Distance value provided by instrument vendor
- Should be included in assessment of uncertainties

17g	All participants	Discussion

Hugh has 10 topics for discussion

- to be circulated by email via Seb to participants
- with request for proposals for how to follow-up (e.g. at GSICS WG meeting in March 2021)
- e.g. ask who is planning to work on each topic in the coming year:
- List can already be revisited in Thursday discussion session
- 1. How to do irradiance integration & impact of cut-off? (sensitive to cosmic rays) LEO/GEO diffs.
- 2. Calibration extent to which lunar calibration is included in operational
- 3. Agreement on solar model & Account for solar variability
- 4. GEO sensitivity to view angle
- 5. Need to separate the satellite position and time from the input parameters to the lunar models themselves.
- 6. If participants send Hugh data, he will provide model simulations, but not share results further
- 7. Need for consistent terminology for detectors to avoid confusion when comparing sensors
- 8. Need for naming convention for model versions as they evolve
- 9. Need to include polarisation in Moon radiance/irradiance models
- 10. Effect of Earth-shine accounting for variable cloud situation (needed for <0.1%)

Seb: Consistent terminology and approach on Uncertainty analysis

Lawrence: any attempt to account for instantaneous solid angle variations in SLSTR observations? Mireya: Yes – but little impact when the Moon is in the centre of the swath

Seb: Use of lunar imagery to characterise MTF post-launch being led by Fred Wu (NOAA) and IVOS

 See recommendation R.LCWS.2020.19d.1.

N.b. Some participants have suggested using the LIME model instead of the GIRO as LIME has a different absolute calibration – tied to observations it is based on. LIME is expected to continue to evolve as additional observations become available. LIME currently only has 2.5yr observations, so does not cover full phase/libration space. GIRO was established as a common reference, using one implementation of ROLO and the drivers needed to apply it – could be replaced as reference

EUMETSAT need to resolve outstanding issues with GIRO licence, so that US agencies and CMA have access.

GLOD could be used in Hugh Kieffer consensus model.

18/11	Microwave mi	ini-session	
ltem	Chair: Vinia M	lattioli	
18	Vinia Mattioli	EUMETSAT	Introduction to the session and discussion
Attende		bold attended	this session. Other names attended previous sessions:
	usivand (EUMET		
	ndro Burini (EUN	METSAT)	
	pping (XIOPM)	N N	
	Okuyama (JMA) hlers (ESA-EST		
	nd Fougnie (EU		
Chris (
	., Intine Lukashin (NASA)	
		niversity of Han	nburg)
	Smith (RAL)		6,
David (
	Woolliams (NPL	_)	
	/nch (?)		
	ing Yu (NOAA)		
	Iturbide-Sanch		
	esco De Angelis Bordo (2)	S (EUNEISAI)	
	Borde (?) /u (NOAA)		
	opp (UCAR)		
	g Qian (NOAA)		
	i Tanaka (JMA)		
	zu Yamamoto (A	IST / GSI)	
	Kieffer (Celestia		
	er Yang (UMD)		
	Yoo (NOAA)		
	(rizek (EUMÉTS	SAT)	
	Pradeep Thapliya		
	nes Frerick (ESA		
	oodward (NIST	/	
	i Kodera (JMA)		
	Furpie (UMBC/N		
	a Junichi (Hokk	• /	
	nce Ong (NASA) Le Barbier (CN		
	Neneman (ESA		
	ouvet (ESA)	·/	
	Dobber (EUME	TSAT)	
	,	y of Rome Sapi	enza)
Mario	Montopoli (CNF	Ř)	
	Burgdorf (Uni	Hamburg)	
	aka Imai (AIST)		
	w Kowalewski		
	js Krijger (ESS)		
	Etxaluze (RAL)		
	N Sinclair (NPL)	I)	
	s Lamquin (ACR Gu (KMA)	1)	
	Philipps (EUMET	SAT)	
		UMETSAT/TPZ)	
	• •	versity of Milano	
	o Bonsignori (l		
	Ekelund (EUME		
	Taylor (NPL)		

Sebastien Wagner (EUMETSAT) Stefan Adriaensen (VITO) Stephen Maxwell (NIST) Steven Brown (NIST) Steven Miller (CSU) Tae-Hyeong O (KMA) Taeyoung Choi (NOAA) Taichiro Hashiguchi (RESTEC, Japan) Thierry Marbach (EUMETSAT) Thomas Müller (MPE) Tim Hewison (EUMETSAT) Tom Stone (USGS) Toru Kouyama (AIST) Vincent Debaeker (EUMETSAT) Vinia Mattioli (EUMETSAT) Woordward (?) Xiaoxiong Xiong (NASA) Xu Geng (NASA) Yu Can (XIOPM) Yuan Li (CMA) Yu Zhang (?) Zhipeng Ben Wang (NOAA)

Vinia introduced the microwave mini-session and outlined the presentation planned.

18a	Roberto	EUMETSAT	In-Orbit Verification of MHS Spectral Channels Co-
	Bonsignori		Registration Using the Moon

Roberto introduced the Microwave Humidity Sounder (MHS), which is operational on Metop-A/B/C and NOAA-18/19. He explained how Moon intrusions occur regularly in the space views, depending on the orbital geometry.

Two time periods were used for the analysis of the co-registration post-launch: Jan 2015 and Nov 2016 He performed a Gaussian fit of the observed radiance curves to derive the relative position of the Moon between different channels.

Concept is applicable to IR and MW scanners where a space view port is available. In-flight co-alignment of MHS channels in the along-track direction could be verified with moon observation to an accuracy of a small fraction of the beam width.

Q: Channel H1 (89GHz) offset wrt other channels - could check misalignment with coastlines?

- Possible in principle wrt H2 or H5
- However, checking the result for channel H1 with ground landmarks to the accuracy achieved with lunar observations would be impossible, due to the poor sampling scheme (1.1 deg spacing, 1.1 degrees FWHM). The moon is oversampled because the space port position is close to the orbital axis and the moon moves slowly, thus providing the wanted oversampling although only in the along-track direction. Oversampling in the across-track direction would only be obtained by changing the scan profile or performing roll manoeuvres

Q: Do multiple intrusions during mission lifetime help reduce uncertainties?

- Not investigated further but could be possible effects which could bias the measurement
- Jan 2015 and Nov 2016 are perfectly consistent
- Martin Burgdorf has analysed 20 Moon intrusions with consistent results

Martin also remarked that he was able to derive co-alignment information also in the across-track direction without oversampling, thanks to his analysis based on a larger data set

Q: Which channels of MHS share common optics (feedhorns, etc)? Would you expect the same pointing error for H3 and H4? And H5 too?

H3 and H4 share the feedhorn and front-end electronics (central frequency 183.311 GHz). H5 has a different feedhorn and central frequency (as well as the other two channels) unlike for AMSU-B, ATMS or MWS.

18b	Martin	Universität	Calibration and characterisation of microwave sounders with
	Burgdorf	Hamburg	the Moon

Martin extended the analysis presented by Roberto light curves, applied to all MHS and AMSU-B to retrieve pointing error in 2-D. L1B files give the pointing direction. This is compared with what comes out of the lunar intrusion data analysis. These were not consistent with requirements in 1/3 of cases.

He went on to show analysis of the beam size from the width of light curves during the Moon intrusions into space views. This showed unexpected results with >1.12° for all MHS and AMSU-B (except N17 and Metop-B).

The moon is smaller than the beam. Therefore, we have an integrated measurement of the Moon BT. Compared to reference models, (Liu and Jin, 2020, or Keihm - 1984) MHS measurements seem not to always agree, with a difference up to 5% for NOAA18 MHS for instance. The measurements were adjusted to allow for the varying distances between Sun-Moon-Satellite.

Liu and Jin could be used a radiometric reference after some adjustment (in order to match measurements that are regarded to be fully accurate, the model had to be "shifted" upwards by a constant factor.

Hence the photometric calibration of microwave sounders can be characterised post launch using the moon.

More than 20 moon intrusions were used to produce the results.

Q: How to derive pointing error in along-track direction?

Slightly different view from Roberto – although 4 space view pixels are >1° apart, multiple Moon intrusions can be averaged, with focus on those where the signal is exactly the same from 2 pixels, which pinpoints the moon's position in the middle between them.

Q: Could you quantify the uncertainty of the fit between the observed BT and model (after 5.5% scaling)? Post-meeting answer: I have calculated the difference between the measured TB of the Moon and the prediction by Liu's model for all points I got with channel 1 of MHS on NOAA-18. Then I calculated the standard deviation of these values with MATLAB. The result was 2.01 K. If I do not scale the model, then it is 2.02 K (but then mean is of course quite different). If I fit a fifth order polynomial to the measured points and use this as my new model, I get also an std of 2.02 K. If I use Keihm's model, I get std = 3.52 K. This shows me that Liu's model fits the measured brightness temperature of the Moon as a function of phase angle very well. The difference between Liu's model and observation is mainly due to the random scatter of the measured values, whereas Keihm's model has a considerable, systematic error.

18c	•		Lunar Disk Integrated Microwave Brightness Temperature
	(Tiger)	of Maryland	from 23 to 183 GHz

Tiger introduced the ATMS. The NOAA-20 ATMS current noise performances are well within requirements for all 22 channels.

He explained the pitch-over manoeuvre performed on NOAA-20, which provided very good Moon scans in the nominal Earth views.

In the channels with oversampling (achieved by instrument design), uncertainties are lower on the lunar measurements. Those uncertainties are higher in the channels where oversampling is less.

Tiger fitted the observations to a Gaussian response function and derived disk-average microwave antenna temperature (Ta) and brightness temperature (Tb) spectra, accounting for the different channels' different beamwidths.

Although it is possible to model the impact of Moon phase, satellites in very stable orbits can always observe the Moon in the same phase – unlike the older NOAA satellites

18d	Francesco	EUMETSAT	Future EUMETSAT Microwave Missions and Plans for Making
	De Angelis		Use of Lunar Observations

Francesco introduced the MWI and ICI instruments (conical scanning radiometers) which will operate on the next generation EUMETSAT Polar System (EPS-SG).

First he described the geometry of the cold space view observations for these two instruments. During a small angular section of the scan, the rotating feed horns point at a fixed dedicated reflector, which collects energy from the cold space at temperature around 2.73K. 352 and 52 samples are acquired during the cold space view for MWI and ICI, respectively, but only a portion of them is considered for the calibration.

Occasionally the presence of the Moon can contaminate the cold counts degrading the calibration. Possible contaminations by the Moon are first detected using an angle threshold and, then may be corrected. The algorithm by Mo and Kigawa 2007 has been analysed. This method has been already used operationally for several microwave sounders but cannot be directly applicable for a conical scanning radiometer. This because the antenna pattern gain in the space view reflector reference frame varies along the angular section dedicated to the space view observations. The Mo and Kigawa 2007 method has been customized to be suitable for conical scanning radiometers. Advantages and disadvantages of this customized method have been presented and discussed.

Q: How to select Space Views from 352/52 available for MWI/ICI?

• Only part of the space view is free from boundary effects

Comment: Need to be very careful about model parameters - especially solar angle subtended by Moon – might be necessary to adjust post-launch

Comment by Tiger Yang: The model planned for the EPS-SG algorithms does not account for the phase lag between full moon and maximum brightness temperature. This should be addressed.

18e	Laura Le	CNES	Moon study for IASI instruments inter-comparisons and
	Barbier		absolute calibration

Further activities on lunar acquisitions using IASI will be undertaken by CNES next year. The presentation by Laura is about the first part of the activities.

Only 5 external calibrations dedicated to Moon acquisitions in 2019 between IASI-B & C – to minimise outages

IASI imager (IIS) used to check alignment of Moon wrt IASI FoV – imperfect alignments result in problematic interferograms

Moon has a smooth radiance spectral ==> can average several wavelengths to minimise noise A model for moon radiances in the TIR domain was developed by NOVELTIS for CNES. CNES analysed sensitivity of model to different factors, based on comparisons with IASI observations. Highlight issue with high "geolocation" uncertainty for analysis of Moon observations

Q: IASI pixel is larger than the Moon – so no saturation – so what impact of PSF on BT?

• Uncertainty ~2K based on analysis of IASI observations and model

Q: Spectral features in model or observations?

• None detected in observations – hence co-averaging multiple channels

Q: Why so few samples?

- Looking for simultaneous observations from IASI-B and -C
- Planned for End Of Life for IASI-A? Still difficult to coordinate timing with IASI-B and -C

Q:What is the lowest wavelength covered by model?

• Focus on IASI spectral band

Q: Will CNES share model?

• Planning to publish in June 2021

Q: Planning Moon acquisitions for IASI-NG?

• Yes - Depending on outcome of ongoing studies

18f	Flavio Iturbide- Sanchez	NOAA	Potential lunar cal/val activities for next-generation GEO IR sounder
Flavio gave an overview of current and planned geostationary hyperspectral IR sounders, including the potential NOAA GEO-HyIRS and potential of lunar observations to support Cal/Val			

Comment: importance of CNES' model development work

Comment: Would be interesting to know CMA's experience with the lunar observations – particularly from FY-4/GIIRS

• **R.LCWS.2020.18f.1**: CMA is invited to share in upcoming GSICS and/or Lunar Calibration meetings its experience on the use of lunar observations acquired by their IR sounders.

18g	All participants	Discussion
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Topics for further cooperation:

- Algorithms for geolocation, antenna pattern / FOV characterisation and
- Radiance Modelling initially full-disc

Inter-comparisons of algorithms, observations and models could be coordinated through GSICS, following the example of the reflected solar band.

Community should promote the use of lunar observations for MW and IR instruments, based on encouraging initial results presented here.

- **R.LCWS.2020.18g.1**: the Microwave + Infrared group is encouraged to pursue current effort and report within the context of GSICS regular meetings.
- **R.LCWS.2020.18g.2**: Microwave + Infrared group to liaise with CMA to foster collaborations.
- **A.LCWS.2020.18g.1**: UMD (Hu Tiger Yang) to coordinate with EUMETSAT (Vinia Mattioli) to draft a note outlining possible further collaborations on microwave and thermal infrared lunar calibration activities.

)/11 em	Chair: Sebas		unar Calibration / Alternative usage of lunar imagery
	Sebastien		Introduction to the session and discussion
	Wagner	LOWILISAT	
ende	es: - Names in	bold attended	this session. Other names attended previous sessions:
Ali	Mousivand (EU	METSAT)	
	ssandro Burini		
	Lingping (XIOP		
	ita Ökuyama (.	,	
	rit Ahlers (ESÀ		
	trand Fougnie (
	is (?)		
	nstantine Luka		
		(University of Ha	amburg)
	ve Smith (RAL)		
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	ma Woolliams ((NPL)	
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	elim Yoo (NOAA		
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Joh	annes Frerick (ESA)	
	nn Woodward (· /	
	zuki Kodera (J		
	•	lokkaido Univers	sity)
	/in Turpie (UM		
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	e Philipps (EU		
		g (EUMETSAT/T	
		(University of Mil	ano Bicocca)
	berto Bonsignor bin Ekelund (EL	i (EUMETSAT)	
	ah Taylor (NP		
		r (EUMETSAT)	

Ste Ste Ste Tae Mir Tae Tai Thi Thi Thi Tor Vin Vin Vin Vin Vin Xua Yu Yu Zhi	erry Marbach (bmas Müller (MF m Hewison (EUM m Stone (USGS ru Kouyama (Al cent Debaeker (ia Mattioli (EUM ordward (?) oxiong Xiong (N Geng (NASA) Can (XIOPM) an Li (CMA) Zhang (?) peng Ben Wang	(NIST) ST) J) SMA) OAA) Chi (RESTEC, Ja EUMETSAT) PE) METSAT) ST) EUMETSAT) ETSAT) ASA) (NOAA)		
19a	Arata Okuyama	ЈМА	Lunar Calibration and Himawari-8 AHI monitoring	
Schedu A corre Monitor More th Non-un • The dis Need to	Ile to move H9 to ction for Bands of ing methods inc an 100 images iformity of space This can includ crepancy in the account for Ou as like a spectac	o prime satellite 4,5 and 6 is appl lude SD, RTM, r can be acquired e count can affec e stray-light - es DS may come fr t of Field Anoma ular dataset to ir	and 9 was presented. is being discussed at JMA lied to the lunar data to remove phase dependency. ray-matching and DCC. for moon chasing configuration. Used for RVS monitoring. ct constant term of calibration equation – can include N-S variation p in B01 and B02 rom the fact there is no DS look before and after lunar observation. alous Response (OFAR) - ghosting – in B01-B03 mprove modelling of lunar irradiance. Is it available? <i>v</i> ided as part of the GSICS Lunar Observation Dataset (GLOD).	
• Q: Whic	 Q: What magnitude of RVS is expected? E.g. based on ground characterisation Good question – Solar Diffusor is viewed 2x per month, but includes seasonal variation, which may be explained by RVS ~0.5% - is this achievable with GIRO? Believed to be more stable in Moon-chasing events Fangfang commented that although these issues are very small per pixel, they are resolving in lunar irradiance – also, the stray light is not always present – and is not corrected in ABI data NOAA provided to Hugh Q: Which is the solar diffusor in Slide 6? Does it have a different trend? Yes in B02 and B03, but trends still within 0.1%/yr Q: Is operational calibration still based on solar diffusor? Yes – calibration coefficients stored in L1 data and updated annually Would be a good example for a GSICS correction – e.g. in a blended approach 			
19b	Tae-Hyeong Oh	КМА	GK2A AMI Mission Monitoring Using Lunar Calibration	

Tae-Hyeong introduced Korea's geostationary satellite, KOMSAT-2A, which carries the AMI imager, similar to ABI and AHI

KMA have implemented vicarious calibration using ocean, desert, water cloud and lunar calibration to monitor the solar band channels

He explained that some Moon observations are contaminated by Earth straylight

Oversampling factors are estimated using the method proposed by NOAA in 2nd lunar calibration workshop. Value is about 1.005

The analysis of the results over >1yr shows seasonal variations up to ~10%, depending on channel

- Related to phase angle dependence not yet corrected?
- But also seen in GSICS DCC and Ray-matching methods

Q: Impact of Moon shape fitting?

- Not used to reject contamination from cases near the Earth limb
- Is it necessary? Could be instrument-dependent

Comment from Hugh:

- Could GEO operators agree a consensus on how to characterise and correct for scan angle dependence?
- Q: Did you also plot how the background varies in time? Could this influence seasonality in Slide 13?
 Will check!
- Q: Residuals in B03 are unusually large and should be investigated
- Q: Has the phase angle dependence been corrected in the time series e.g. in slide 13?
 - Could contribute to observed seasonal variation as could the solar diffusor
 - Not yet (would be helpful to isolate the different factors)

19c	All participants	Discussion	

Deferred to 19g

40.1			
19d	Jason Choi	NOAA	NOAA-20 VIIRS Initial On-orbit BBR and MTF Estimations
			Using the Scheduled Lunar Images

Jason explained how VIIRS can view the Moon in the regularly in the space view on a monthly basis (except the summer months) - and also in dedicated manoeuvres

Band-to-Band Registration is estimated by comparing the Moon's centroid relative to a reference band (M1).

Then MTF is analysed, based on sharp edge over all lines cutting the Moon disc

BBR very stable in time but there are some slight differences band-to-band causing potential artefacts in L2 products making use of band registrations (NDVI for instance).

Seb noted that this activity was identified at previous LCWs, and that NOAA had hoped to make more progress on this topic also for GEO imagers.

Q: Was the BBR analysis also done for S-NPP/VIIRS? This had very strong light leaks which caused spatial effects.

See paper by Zhipeng Wang *et al.* (2015, IEEE TGRS, "Update of VIIRS On-Orbit Spatial Parameters Characterized With the Moon").

Q: any indication that VIIRS MTF changes with time in a systematic way & why?

- Focal length changes e.g. due to deformation in optics (e.g. thermal?)
- But mainly during launch process due to mechanical stresses
- Most sensors don't change too much during mission life
- BBR is also sensitive to similar factors
- (Kevin Turpie): S-NPP/VIIRS light leak sensitive to changing contamination levels on optics

19e	Constantine Lukashin	NASA	ARCSTONE: Calibration of Lunar Spectral Reflectance from Space		
ARCST as soon Goal Sp One sin Targetir Stability On Cub	osty introduced the ARCSTONE project, which is coordinated with Mauna Loa LUSI and Air-LUSI teams. RCSTONE project would allow the calibration of fleets of CubeSat satellites to be accurately calibrated is soon as they would regularly view the moon. oal Spectral range of ARCSTONE = [350nm, 2300nm] at 4nm resolution. (min 380-900@8nm) ne single pixel FOV of about 0.7 degrees (no scanning) argeting combined uncertainty on lunar spectral irradiance <0.5% (k=1) <1.0% threshold at 70° phase ability <0.1%/decade (0.15% threshold) n CubeSat, but well stabilised with 2 star trackers oon observed at all phases (requirements established for a phase at 75 degrees)				
		ience every 12 h			
	Built and chara	cterised two ser	nours. nsors – UVVNIR + SWIR T detector covering 350-2300nm - now fabricated – SNR>100		
Mission	lifetime: 1 year	(mimimum), goa	al = 3 years		
		wer detector sys ailable technolog	stems, a redesign of the instrument was done in the last 2 years to gy.		
Q: Tech	nnical design de	tails			
•	 Q: Earliest launch? 2022/23 - still not Q: Solar irradiance observed? TSIS is used or successor (TSIS-II). Those instruments are part of a long-term NASA program. So the mission continuity should not be an issue. 				
19f	Stephen Maxwell	NIST	Some update on the Mauna Loa LUSI project		
Based of Expect Mauna Q: pote Q: Will of •	Context: project fits into the development of an accurate lunar irradiance reference model. Based on same measurement principle as air-LUSI: refractor telescope + image + polarisation scramblers Expect uncertainty ~0.5%, but Mt Hopkins too instable Mauna Loa site = similar conditions at Canarian Islands (Pico Teide). Q: potential cooperation with ESA? • Already in touch – through Air-LUSI + ARCSTONE • Aiming to establish absolute lunar irradiance scale Q: Will only new model come out or also data? • Aiming to produce and share TOA radiances Q: COVID issues? • Planned to deploy in March 2021 for 6 months – maybe delayed 1 month				
19g	All participant	ts	Discussion and concluding remarks		
Sebasti • •	Sebastien reviewed the topics discussed this week: Lunar model development Measurement campaigns and future dedicated missions Mission monitoring – for the RSB 				

- **A.LCWS.2020.19g.1**: S. Wagner (EUMETSAT) to circulate the list of topics to be addressed by the Lunar Calibration Community and to solicit interest from its members.
- **R.LCWS.2020.19d.1:** NOAA is encouraged to pursue its initiative on comparing approaches for post-launch assessment of MTF using lunar imagery. This initiative, in collaboration with other agencies would lead to the definition of best practices for MTF assessment using the Moon.

Mission Monitoring

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- How to calculate observed lunar irradiance:
 - Pixel solid angle/oversampling factors
 - Integration of irradiance definition of cutoff radiance + sensitivity to cosmic rays
 - Costy suggested using PSFs to define annulus (planned for ARCSTONE)
 - Kevin Turpie pointed out that PSFs are difficult to characterise on-orbit
 - Typically characterised PSFs don't extend more than a couple of pixels need more
 - Tom: PSF also characterises solid angle, needed for oversampling factor
 - Hugh: need to examine integrated energy curves to define annulus down to ppm
 - Need to be aware of stray-light esp for GEO
 - How to remove background especially when it varies e.g. RVS?
 - Need to ensure dark side of Moon (lit by Earthshine) is included small impact
 - OLI experience very low stray light levels Removing stars has little impact
 - Uncertainty estimates need for each instrument's observations
 - •
 - e.g. define circle + annulus to encompass lunar energy and estimate dark level
 - Avoid including results based on lunar calibration

Recurring theme: defining standard terminology

- Need alignment
- Including detector terminology
- And uncertainties
- To discuss by email?

Lunar Models

- Solar irradiance spectrum
 - Model must be specified!
 - Solar variability becoming significant as algorithms & instruments improve
 - Need a consensus model which could evolve in time
 - Benefit of including GEO observations in developing/validating lunar models?
 - o e.g. ROLO is limited to observations within 8° of Moon centre
 - Need to ensure full range of libration space observed from GEO orbit is included
 - Increased modularity in algorithm in calc "reference" lunar signal
 - (
- Model version traceability and naming convention
 - o e.g. as Included in GIRO
- Inclusion of polarisation
 - Need to specify polarisation of observations used to derive model
 - LIME includes specification of degree of linear polarisation, but ongoing development
 - Tom: Impact on lunar irradiance depends on polarisation sensitivity of instrument
 - Kevin: modern grating spectrometers have a DOLP 2-4% critical for ocean colour
 - Tom: TRUTHS will also have polarisation sensitivity Air-LUSI not
 - Fred: Some instruments can have much higher DOLP
 - Also beneficial for polarimeters!
 - \circ $\,$ Moon's DOL Polarisation varies with phase angle (zero at 24°) and wavelength $\,$
- Model uncertainties
 - Earth-shine variation effect on lunar irradiance as a function of phase angle
- Benchmarking

- Cover the space of observables
 - e.g. is GEO worst case? High inclination?
 - Potential benefit of stepping through each variable of observation space to isolate the dependencies
 - Not to include SRFs? But need to account for fact that some models have different spectral resolution
 - Could also define an effective wavelength for most channels (not panchromatic)
- Allow systematic model assessment + traceability to a "reference" model
- Needs to be accompanied by efforts to validate the reference model against accurate observations – even at a few points
- Could extend model fitting based on ANN
 - Matthijs, Hugh and Costy are interested in this
- Shift to Reflectance model

Reviewed list of actions and Recommendations

All accepted as written, except:

- Letter of recommendation to NASA to include MLO-LUSI + ARCSTONE (in addition to A.LCWS.2020.16f.2 for Air-LUSI)
- **A.LCWS.2020.19g.2**: EUMETSAT (S. Wagner) to liaise with the participants to the Lunar Calibration Workshop to ensure a follow-on on the actions / recommendations
- **A.LCWS.2020.19g.3**: EUMETSAT (S. Wagner) to propose letter of recommendation by GSICS to NASA to highlight the benefits of ARCSTONE project for GSICS activities and its members.