A Consistent Data Record from the Inherited Solar Bands of VIRR

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Background

- Visible Infrared Radiometer (VIRR) is the first and the most historic instrument equipped on the Fengyun (FY) polar series satellite.
- After the historical data re-processing, VIRR instruments could provide a global data record over 20 years which offers the capacity on studying climate variability.
- Because of the lack of onboard calibration system for VIRR solar bands, they must be vicariously calibrated.

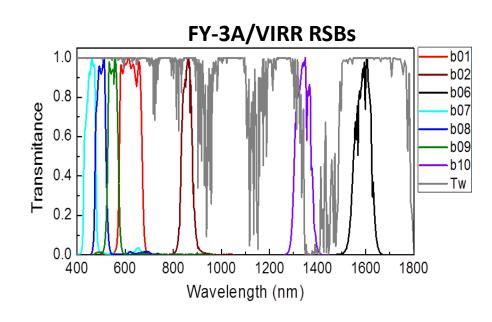


VIRR overview

• There are 3 versions of VIRRs carried on FY-1 and FY-3 satellites, covering the visible, near-infrared and thermal Infrared spectra.

VIRR Spectral Specifications

Band	FY-1A/B	FY-1C/D	FY-3A/B/C VIRR-3		
	VIRR-1	VIRR-2			
1	0.58-0.68	0.58-0.68	0.58-0.68		
2	0.725-1.10 0.84-0.89		0.84-0.89		
3	0.43-0.53	43-0.53 3.55-3.95			
4	0.53-0.58	10.3-11.3	10.3-11.3 11.5-12.5		
5	10.5-12.5	11.5-12.5			
6		1.56-1.64	1.56-1.64		
7		0.43-0.48	0.43-0.48		
8		0.48-0.53	0.48-0.53		
9		0.53-0.58	0.53-0.58		
10		0.900-0.960	1.325-1.395		



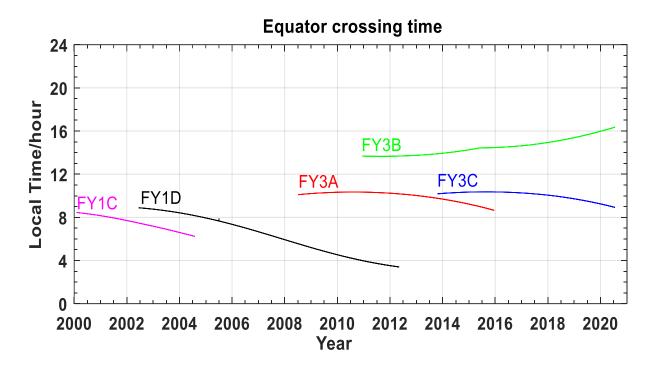
Global data could be provided since FY-1C.

VIRR Global Data Information

Satellite	Launch date	Time range	Coverage	Channels
FY-1A	1988/09/07	1988/09/07–1988/10/15	1-hr	1, 2 and 5
FY-1B	1990/09/03	1990/09/03-1991/02/14	1-hr	1, 2 and 5
FY-1C	1999/05/10	2000/01/21-2004/06/30	Global	1, 2, 4 and 5
FY-1D	2002/05/15	2002/07/11-2012/01/13	Global	1, 2, 4 and 5
FY-3A	2008/05/27	2008/07/01-2015/01/04	Global	1 to 10
FY-3B	2010/11/05	2010/11/14 till now	Global	1 to 10
FY-3C	2013/09/23	2013/10/01 till now	Global	1 to 10



• FY-1 satellites did not include system to maintain their sun-synchronous orbit. Due to the satellite orbit drift over time, the equator crossing time (ECT) continuously changed.





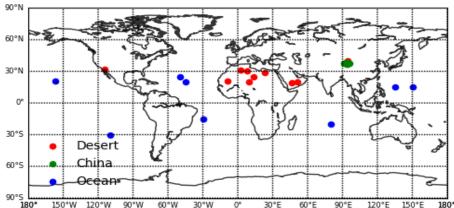
Calibration

- The multiple site calibration approach is employed for the Ch1 and Ch2 of VIRR sensors on FY-1 and FY-3 platforms, using the RTM predicted reflectance over desert and ocean invariant Earth targets.
- The calibration reference of the VIRR solar band record is further traced to Aqua MODIS C6.1 reference calibration by a systematic correction derived from Libya4 desert.



Long-term calibration scheme for each sensor

 Three kinds of sites are used, including Chinese PICS located in Qinghai province with altitudes nearly 3 km.



 The calibration coefficient is calculated by linear regression, using data during an accumulation period (e.g., 10 days) from all sites.

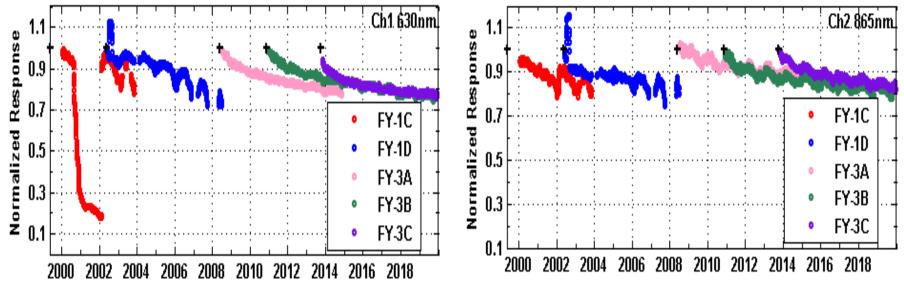
$$100\rho_i \cos(SZA)/d^2 = m_i (EV_i - SV_i)$$

• In linear regression to derive the calibration coefficient, data from different sites are assigned with weighting factor using the inverse of the variance from the radiative simulation evaluation with reference to Aqua MODIS.

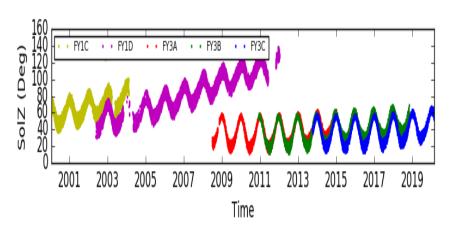
$$w_i = 1/\sigma_i^2$$

• Piecewise polynomial functions of DSL (number of days since launch) is adopted to describe the calibration coefficient series long-term varying feature.



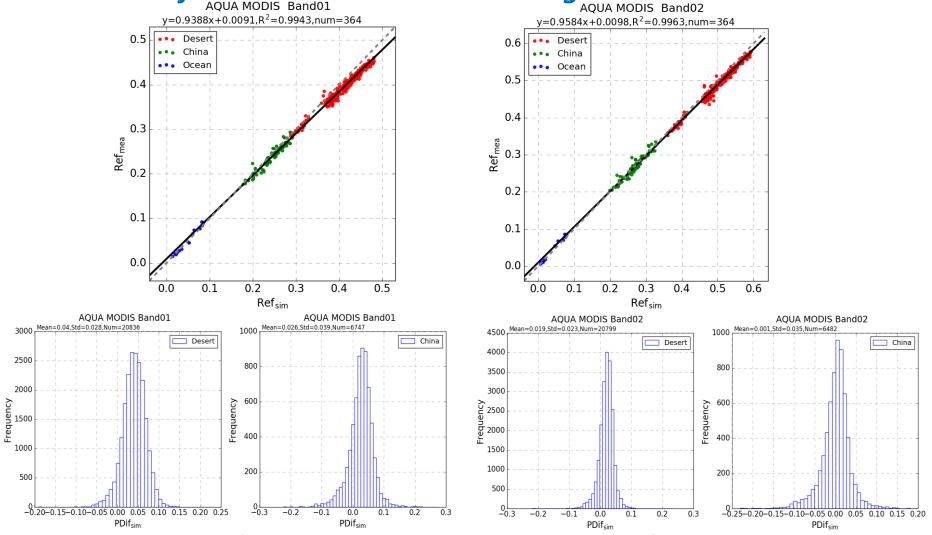


Lifetime normalized response variation of VIRR Ch1 and Ch2.



- Working unit switch for FY-1C and FY-1D.
- Large solar zenith angle due to the orbit drift, especially FY-1, resulting in large oscillation by inadequate description of the anisotropy of calibration targets.
- Seasonal variation of Ch2 for FY-3 is obvious, sensor related issues to be analyzed.

Calibration reference: RTM over stable targets
AQUA MODIS Band01



Calibration reference evaluation statistics using Aqua MODIS from 2005 to 2019

Band	Relative Difference(%, Mean $\pm\sigma$)				
Dallu	All Sites	Desert	China	Ocean	
1	3.62 ± 4.45	4.01 ± 2.79	2.61 ± 3.90	2.85 ± 13.24	
2	1.52 ± 3.98	1.93 ± 2.25	0.07 ± 3.52	2.54 ± 15.08	

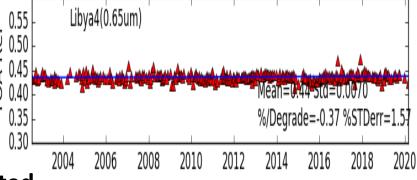


Tracing to Aqua MODIS calibration

• PICS stability: the average reflectance under clear-sky, and a given set of viewing and solar angular conditions, remains nearly stable over time.

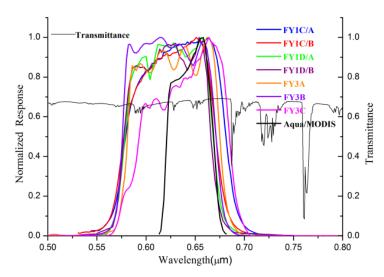
Libya4 is used, temporally stable within 0.5% per decade based on Aqua MODIS

band 1.

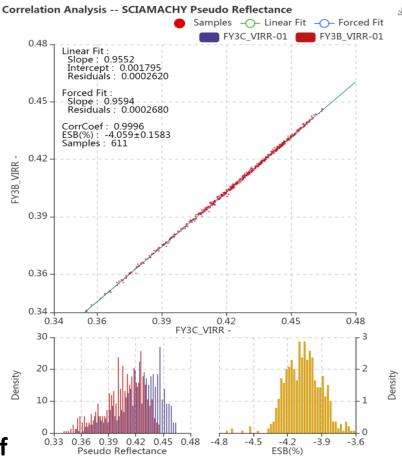


- For TOA reflectance comparison
 - Spectral differences should be corrected.
 - BRDF effects should be corrected especially at large viewing angles.
- The observed sensor reflectance is spectrally adjusted to the FY-3B VIRR SRF and to a common SZA of 30° to provide an observed normalized reflectance.
- VIRR record mean value of clear-sky TOA normalized reflectance is compared with that of MODIS, and the ratio is used as the systematic correction factor to trace the VIRR record to Aqua MODIS calibration.

Spectral band adjustments



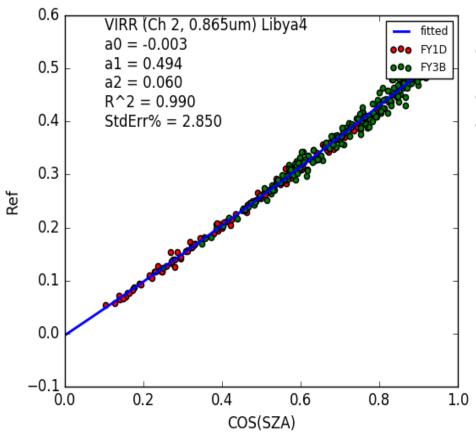
- SCIAMACHY data is used to derive the spectral band adjustment factors (SBAFs).
- SBAF is derived for certain target by linear regression through the origin (force fit).
- Over clear Libya4 desert, the reflectance of FY-3C is nearly 4% higher than that of FY-3B for Ch1, while nearly 4% lower than that of FY-3B for Ch2.



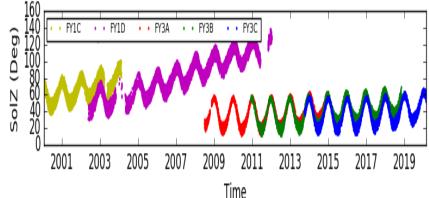
Libya4
FY-3B vs FY-3C



Site-specific directional model (DM)



Libya4 DMs derived from near-nadir reflectance



- FY-1D and FY-3B have relatively longer records.
- To cover the possible solar zenith angles, the recalibrated FY-3B and FY-1D VIRR records are combined to derive the DMs.



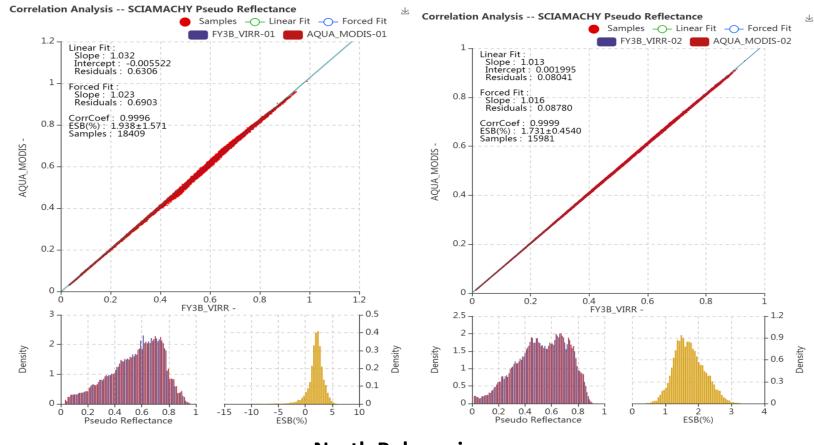
Evaluation

Vicariously calibrated VIRR record is evaluated using SNO targets with reference to Aqua MODIS, and global stable targets.

- Comparison with MODIS using SNO over polar regions: for reflectance biases.
 - Aqua MODIS C6.1 level 1b data.
 - Near-coincident (within 1 min), near-nadir (sensor zenith angle within 10°) matches after angle consistency and spatial uniformity screening.
 - SCIAMACHY-based SBAFs are applied.
- PICS reflectance time series: for consistency.
 - clear-sky TOA reflectance after anisotropic and spectral correction.

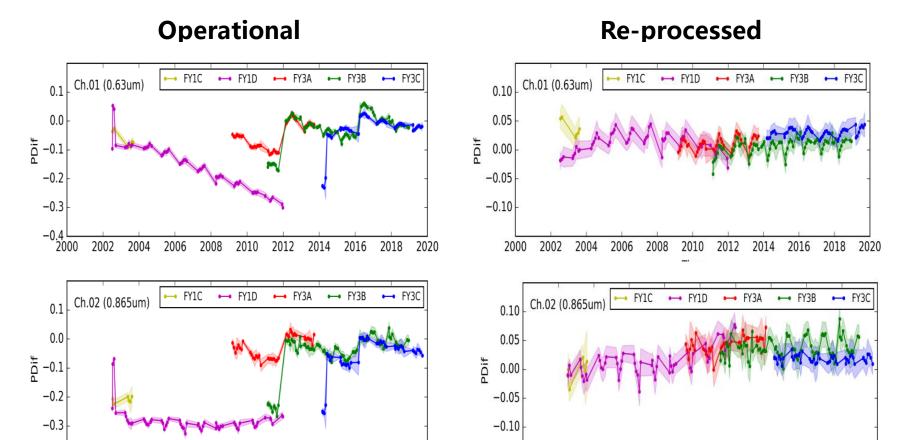


Spectral band adjustments



North Pole region FY-3B vs. MODIS

Over North Pole region, the FY-3B VIRR Ch1 reflectance should be adjusted by
 2.3% to achieve spectral consistency with Aqua MODIS, while by 1.6% for Ch2.



 Variation of sensor radiometric response both gradual and sudden degradation is corrected, and the radiometric stability and inter-platform consistency is improved after recalibration.

2004

2006

2008

2010

2012

2014

2016

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2020

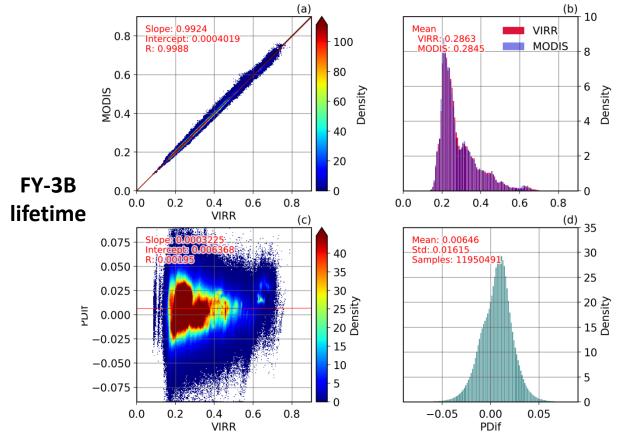
2016

2012

2014

2018

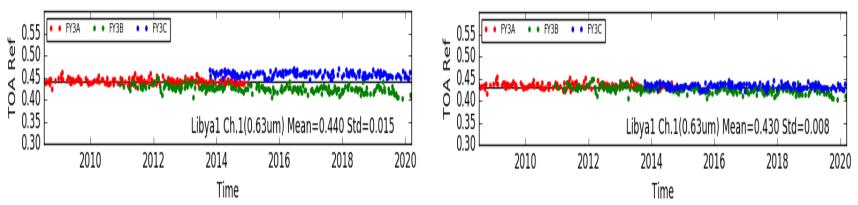
• Lifetime RMS of the relative difference is within 5% for Ch1, 2, 6, 7, 8, while relatively larger for Ch9 at low signal.



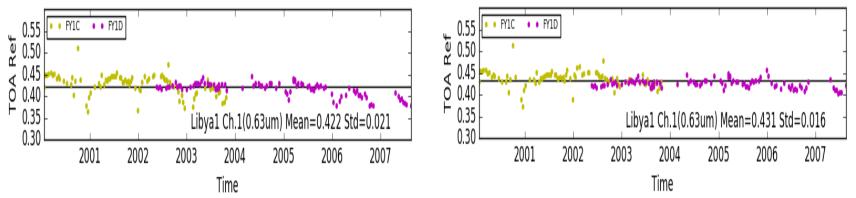
Comparison statistics of relative difference (%) by SNO against Aqua MODIS

		Ch1			Ch2		
_		Lifetime Mean	Mean of monthly RMS	Std of monthly RMS	Lifetime Mean	Mean of monthly RMS	Std of monthly RMS
	FY-1C	2.04 ± 2.07	3.24	1.01	0.62 ± 2.84	2.91	1.06
	FY-1D	0.87 ± 2.01	2.11	0.66	2.08 ± 2.86	2.70	1.17
	FY-3A	0.60 ± 1.60	1.63	0.49	4.31 ± 2.40	4.48	1.44
	FY-3B	0.65 ± 1.61	1.57	0.38	4.31 ± 2.47	4.31	s 1.43°
_	FY-3C	2.62 ± 1.43	3.03	0.60	1.69 ± 2.10	2.46	0.92 NS

PICS reflectance time series



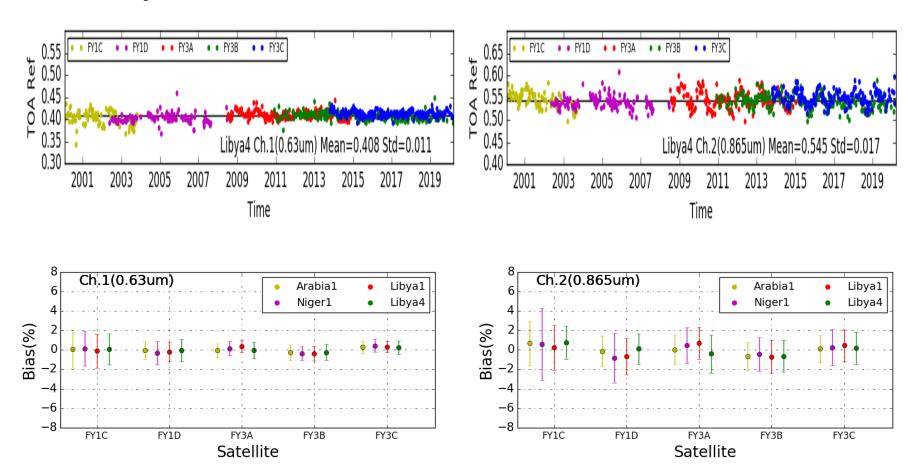
FY-3 VIRR multi-sensor time series of normalized reflectance (left) without and (right) with the SBAF



FY-1 VIRR multi-sensor time series of normalized reflectance (left) without and (right) with the DM correction



Clear-sky normalized reflectance of invariant deserts



In general, after anisotropic and spectral correction, the TOA reflectance means for each instrument are within 1% of the 20-yr average for channels 1 and 2.



Summary

- A multisite vicarious approach for consistent calibration of VIRR RSBs is presented and applied, producing calibration coefficients for 5 instruments on FY-1C/D and FY-3A/B/C over two decades (2000-2019), and the record calibration reference is further traced to Aqua MODIS C6.1 by a systematic correction derived from Libya desert.
- The VIRR visible and near-infrared records are systematically larger than Aqua MODIS over the SNO targets. The lifetime relative biases for each sensor is within 2.7% and 4.4% for Ch1 and Ch2, respectively.
- Invariant deserts are adopted to evaluate the VIRR record stability and consistency. In general, the DM and SBAF corrected reflectance means for each instrument are within 1% of the 20-yr average.
- · User feedbacks are expected through using the recalibrated dataset.



Thank you for attention.



