Implementation of GOES-R ABI vs. VIIRS Ray-Matching Inter-Calibration Method

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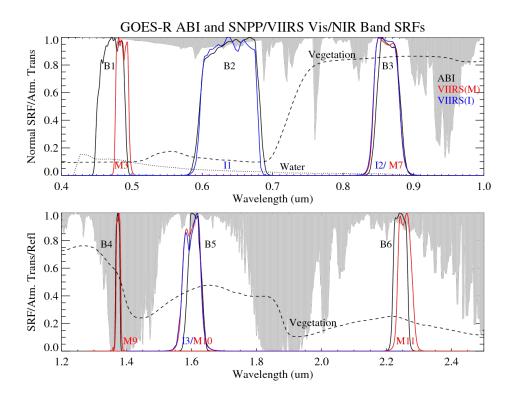
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NOAA GOES-R CWG Ray-matching

- Ray-matching is currently used to monitor the inter-calibration difference between GOES-R ABI and VIIRS onboard SNPP and NOAA-20
 - Operational ABI (L1b) and VIIRS (SDR) data are generated by NOAA
- Ray-matching algorithm and filtering criteria mainly follow the following two documents:
 - Doelling, D. 2011, ATBD
 http://gsics.atmos.umd.edu/pub/Development/AtbdCentral/GSICS ATBD RayMatch NASA 2011 09.pdf
 - Yu, F. and X. Wu, 2016, Remote Sensing, 8(3), doi:10.3390/rs8030165
- NOAA is planning to implement the GSICS harmonization coefficients to the ABI L1B data
 - Linear correction
 - Wu, X., GSICS webmeeting in December 2021

Spectral Match: VIIRS VNIR Band Selection

GOES-R ABI VNIR SRF and the matched VIIRS SRF



GOES-R ABI	VIIRS (reference)
B1 (0.47μm)	M3 (0.49μm)
B2 (0.64μm)	I1 (0.64μm)
B3 (0.86μm)	M7 (0.87μm)
B4 (1.37μm)	M9 (1.38μm)
B5 (1.61μm)	M10 (1.61μm)
B6 (2.23μm)	M11 (2.25μm)

- VIIRS I1 band for ABI B2, M bands are preferred to I bands for the other ABI VNIR channels
 - M bands (dual gain) have lower noise than I bands, I1 has best spectral match with B2
- The operational VIIRS data processed by NOAA is used as the reference.

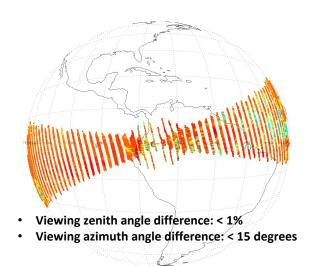
Ray-Matching Criteria Table for A

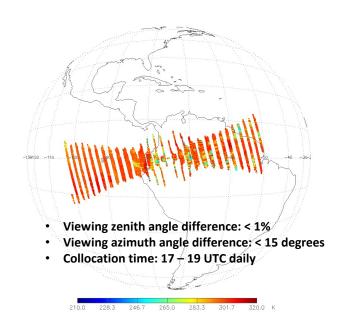
Ray-matching Criteria	Ray-matching threshold
Monitored sensor	GOES-R
Reference sensor and version	SNPP/NOAA-20 VIIRS, NOAA operational SDR data
Radiance or reflectance pair regression	Reflectance
SBAF	SCIAMACHY linear fitting
Latitude Domain	±1º latitude
Longitude Domain	$^{\sim}$ +-1.5 hours, centered at the LEO Equatorial ascending time. (corresponding to $\pm 25^{\circ}$ longitude of GEO sub-satellite position)
Underlying surface	All-sky tropical land (GOES-East), All-sky tropical ocean (GOES-West)
Spatial resolution for matched scenes	2 km
GEO/LEO pixel resolution	0.5, 1.0, and 2.0 km / 0.375, and 0.75 km
GEO/LEO pixel subsampling	ABI B01-B03 and B05 are sub-sampled to 2 km from the native spatial resolutions
Spatial homogeneity	FOV and ENV CoV < 5% (FOV ~ ABI FOV; ENV size ~ 3 x FOV size, for all ABI VNIR bands)
Time matching difference	< half of ABI timeline interval (ABI current operational timeline interval is 10 minutes)
Solar zenith angle (SZA) difference	Not applied. Yet the difference should be less than ~2 degrees
View zenith angle (VZA) difference	1. – cos(VZA_GEO)/cos(VZA_LEO) < 1%
Relative azimuth angle (RAA) difference	< 15 degrees
Scattering angle difference	?
Sun glint impact	Sun glint angle (> 40 degrees), TBD (need some analysis for GOES-West)
Linear regression, regression through space offset	linear regression (planning), y = ax + b

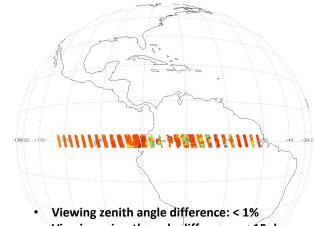
Timeline Criteria Table for B

Ray-matching ATBD	Ray-matching threshold
Timeline temporal resolution	TBD
Outlier Filter	Sunglint angle > 40 degrees
Other criteria	Uniform scenes (CoV of FOV and ENV < 5%) ~3 hours centered at the LEO equatorial ascending time
Temporal regression	-

G16 Spatial Domain







- Viewing azimuth angle difference: < 15 degrees
- Collocation time: 17 19 UTC daily
- · Within defined latitude range



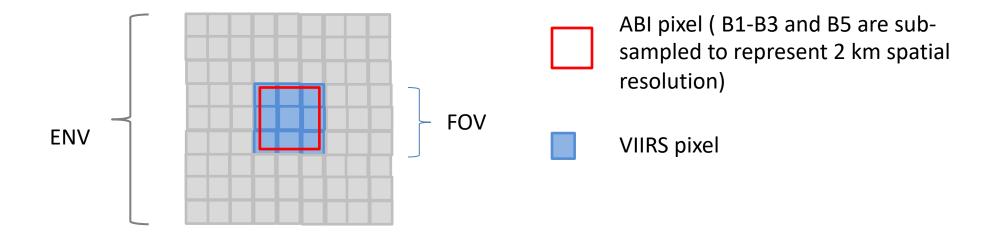
- Goal: reduce the data processing time by tailoring the input data
- ABI Input selection
 - Daytime
 - +-1.5 hours central at the LEO the ascending node crossing time (17 20 UTC for G16)
 - Spatial Domain:
 - Latitude range: [-1°, +1°]

Matching the FOV Sizes

GEO (ABI)	ABI Spatial Resolution at Nadir (m)	ABI Spatial Resolution used in Processing (m)	VIIRS Spatial Resolution at Nadir (m)	Geo/Leo Native FOV	Pseudo FOV: VIIRS Window Size (FOV Size)	ENV Size VIIRS Window Size (ENV Size)
B1 (0.47μm)	1000	2000	750(M3, dual gain)	1.33	3 x 3 (2250m)	9 x 9 (6750m)
B2 (0.64μm)	500	2000	375(I1, dual gain)	1.33	7 x 7 (2625 m)	17 x 17 (6375m)
B3 (0.87μm)	1000	2000	750(M7, dual gain)	1.33	3 x 3 (2250m)	9 x 9 (6750m)
B4 (1.38μm)	2000	2000	750(M9, single gain)	2.67	3 x 3 (2250m)	9 x 9 (6750m)
B5 (1.61μm)	1000	2000	750(M10, single gain)	1.33	3 x 3 (2250m)	9 x 9 (6750m)
B6 (2.25μm)	2000	2000	750(M11, single gain)	2.67	3 x 3 (2250m)	9 x 9 (6750m)

- Pseudo scenes are constructed with the higher spatial resolution instrument
 - In this case, it is VIIRS. Yet VIIRS reference data have a slight higher spatial resolution than ABI at B01, B02, B03 and B05, at the same magnitude
- To reduce the image processing time, ABI B01/02/03/05 images are sub-sampled to 2 KM spatial resolution.
 - B01/B03/B05: One from every two pixels
 - B02: One from every four pixels

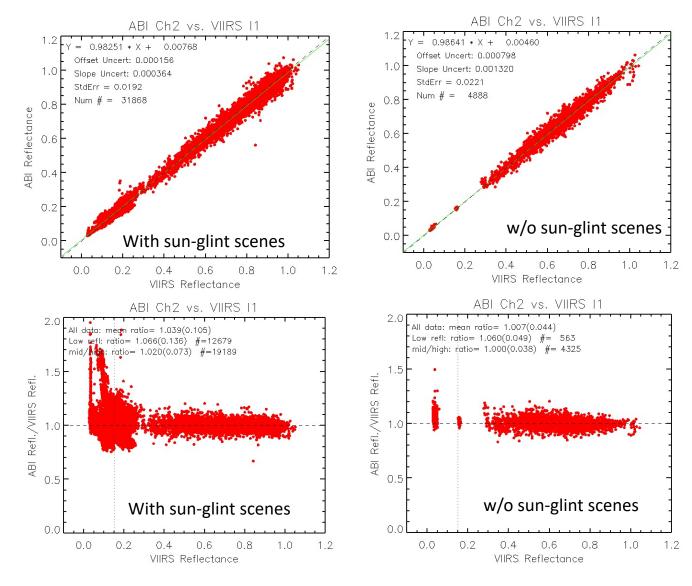
Uniform Scene Screening



- Concepts of ENV(environ) and FOV scenes are from the GSICS GEO-LEO IR inter-calibration
- Uniform scenes should be applied to ensure the same targets observed by the two instruments
 - Possible difference of INR and MTF performance
 - Moving targets
 - Possible unexpected calibration issues or anomalies

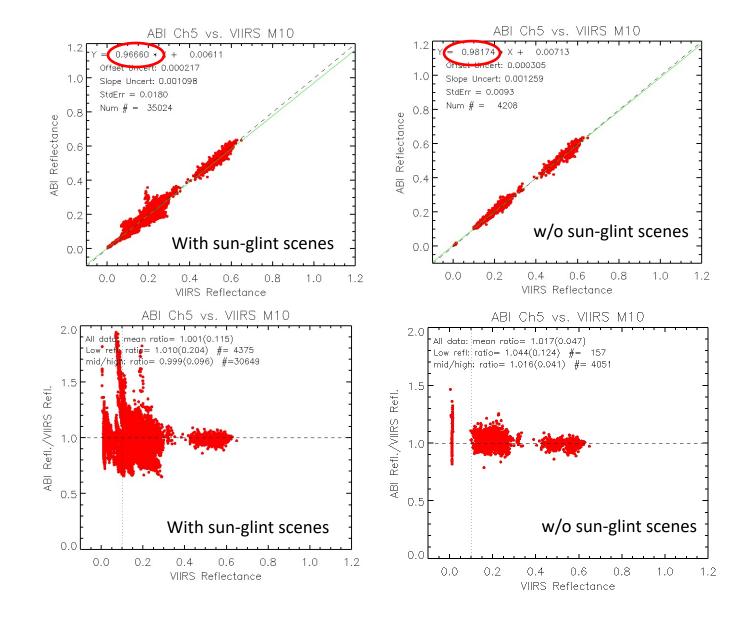
Impact of Sun-glint – Example 1

• Data: G16 vs. SNPP VIIRS from 2020/03/01 – 2020/03/31



- Temporal, geolocation, spectral and uniform collocation criteria are applied to all the pixels in the figures
- Right two figures: sun-glint contaminated scenes were removed from the left two figures.
- Impact of sun-glint is most apparent at the low scene radiance

Impact of Sun-glint – Example 2



In this case, the residual of the sun-glint scenes can cause ~1.5% change of the fitting slope

Summary of Main Criteria

- Temporal match criteria
 - Less than half of operational timeline (e.g. <5 minutes for Mode6)
- Viewing geometry
 - zenith angle difference: 1% difference of the cosine viewing zenith angle
 - Viewing azimuth angle difference: 15 degrees
- Geolocation
 - Light of sight difference < VIIRS pixel scan angle
 - Spatial resolution for ABI: essentially, the native ABI pixel spatial resolutions are retained
- Same target criteria
 - Uniform scenes: FOV + ENV cov < 5%
 - Sun-glint removal
- Spectral match
 - SCIAMARCHY linear SBAF coefficients provided by NASA Langley
- Others
 - Spatial domain: ±1 degrees in latitude, ±25 degrees longitude of sub-satellite location
 - Time: 3 hours centered at the LEO equatorial ascending time