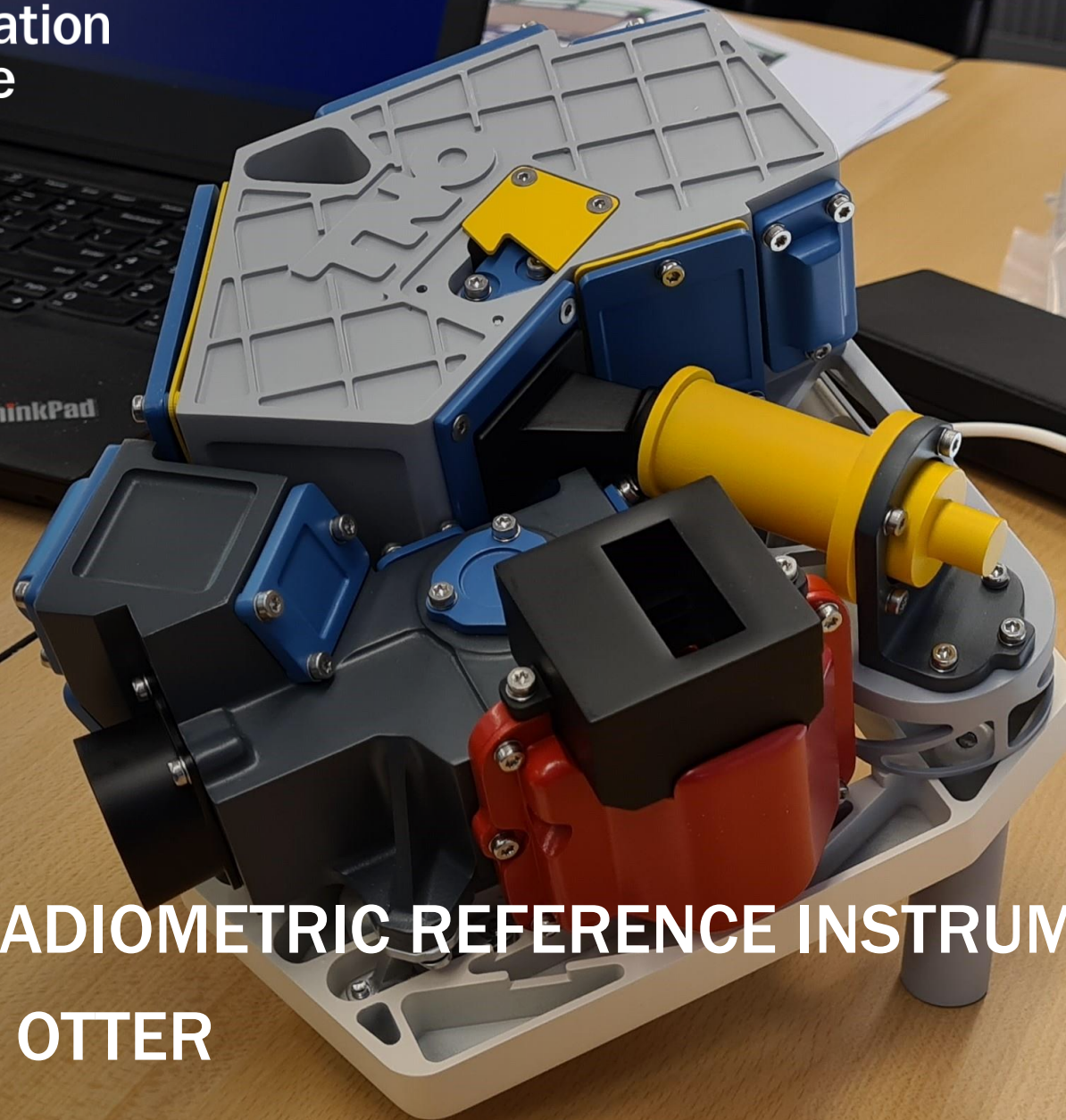


▶ **ARRI**

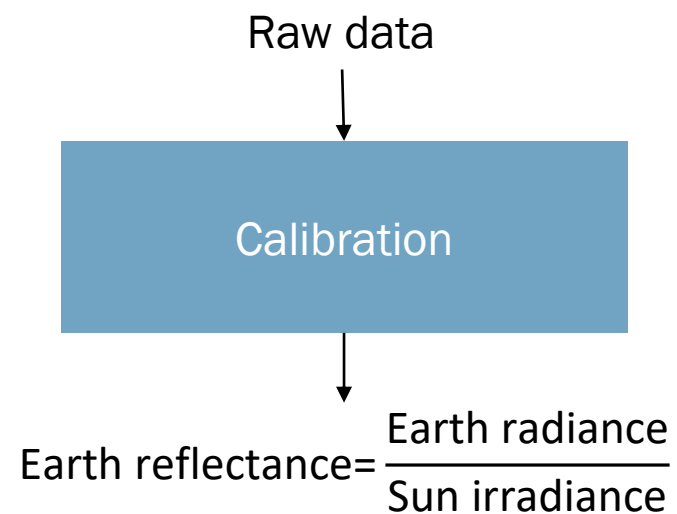
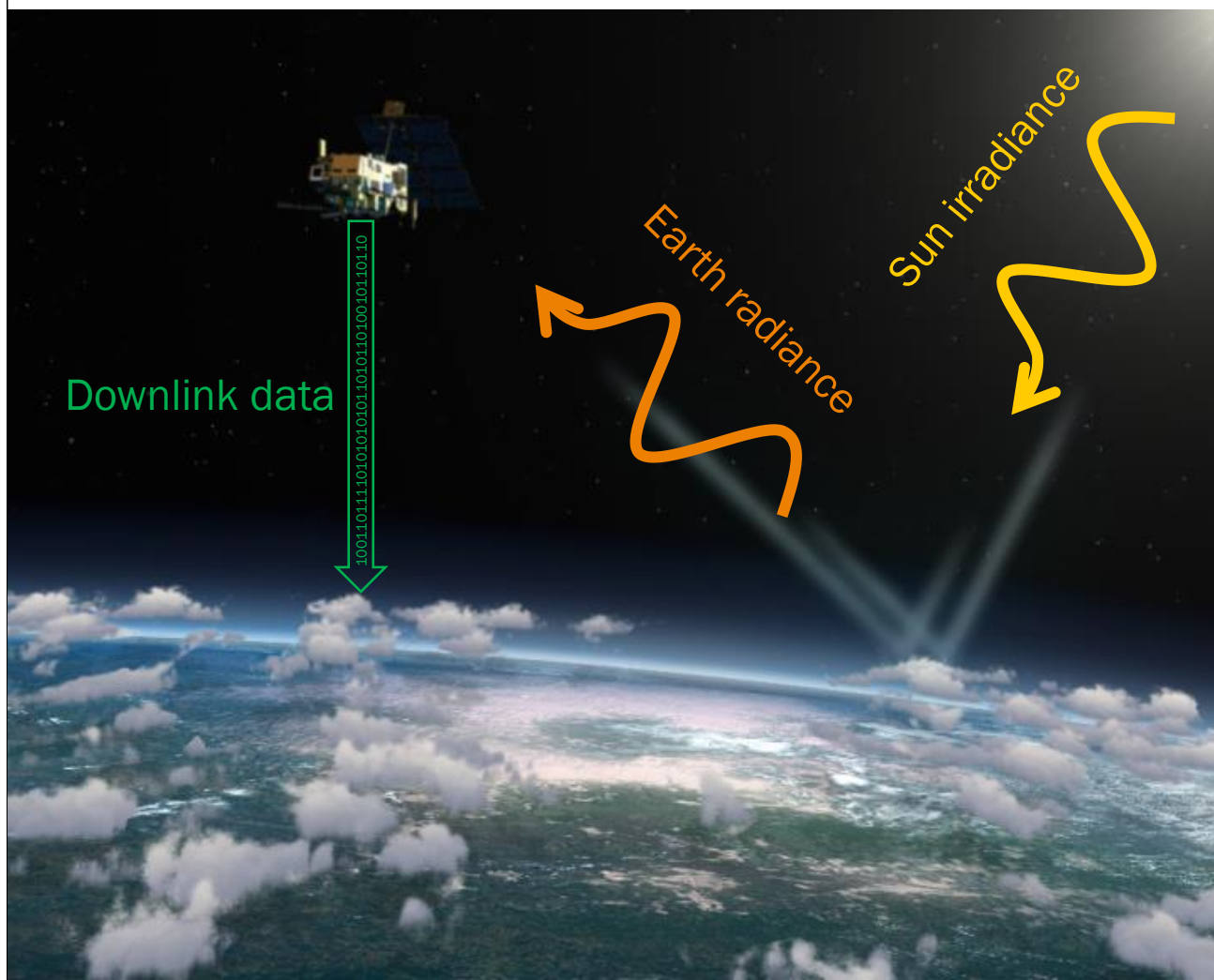
ABSOLUTE RADIOMETRIC REFERENCE INSTRUMENT

GERARD C.J. OTTER





## › INTRODUCING ARRI EARTH OBSERVATION





## › INTRODUCING ARRI

# CALIBRATION, MONITORING INSTRUMENT CHANGES DURING LIFETIME



Vicarious calibration using stable known scenes

- Requires no on board hardware
- Knowledge and stability is limited



Solar calibration using on board diffuser

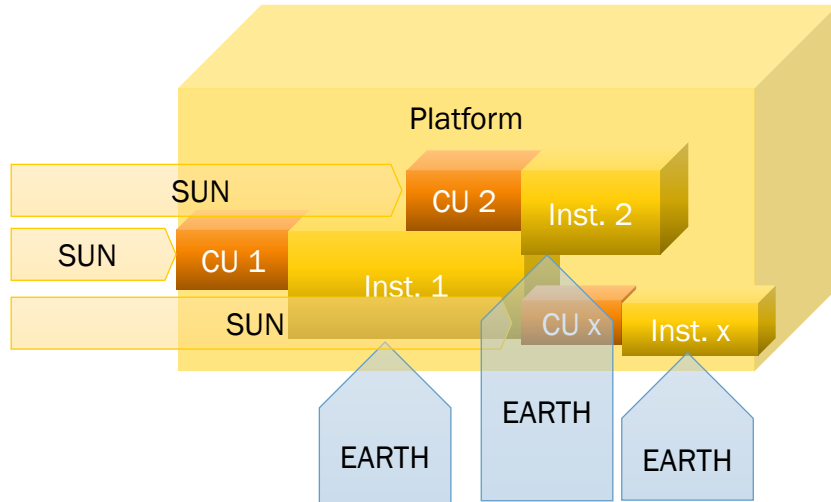
- More accurate
- Requires on board diffuser and diffuser monitoring (for highest accuracy)



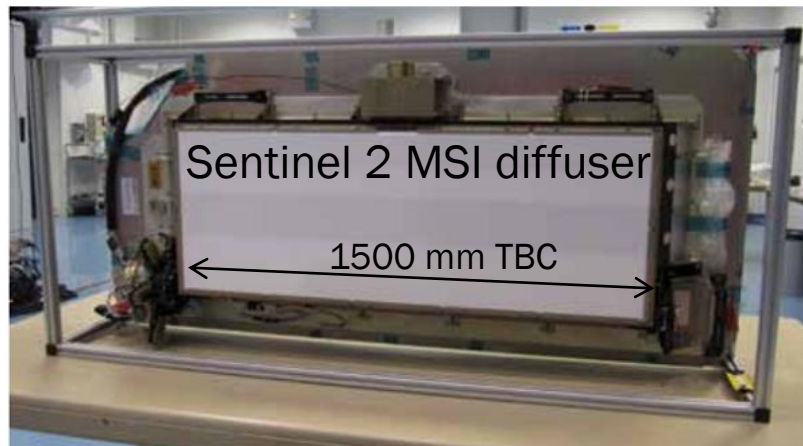
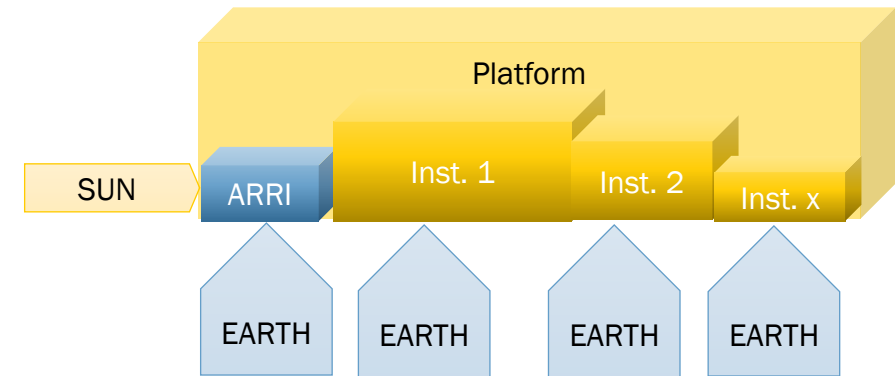
# INTRODUCING ARRI

## REDUCING ON-BOARD CALIBRATION HARDWARE

Each instrument with sun calibration unit



One instrument (ARRI) calibrated with respect to the sun providing reference reflectance to all instruments



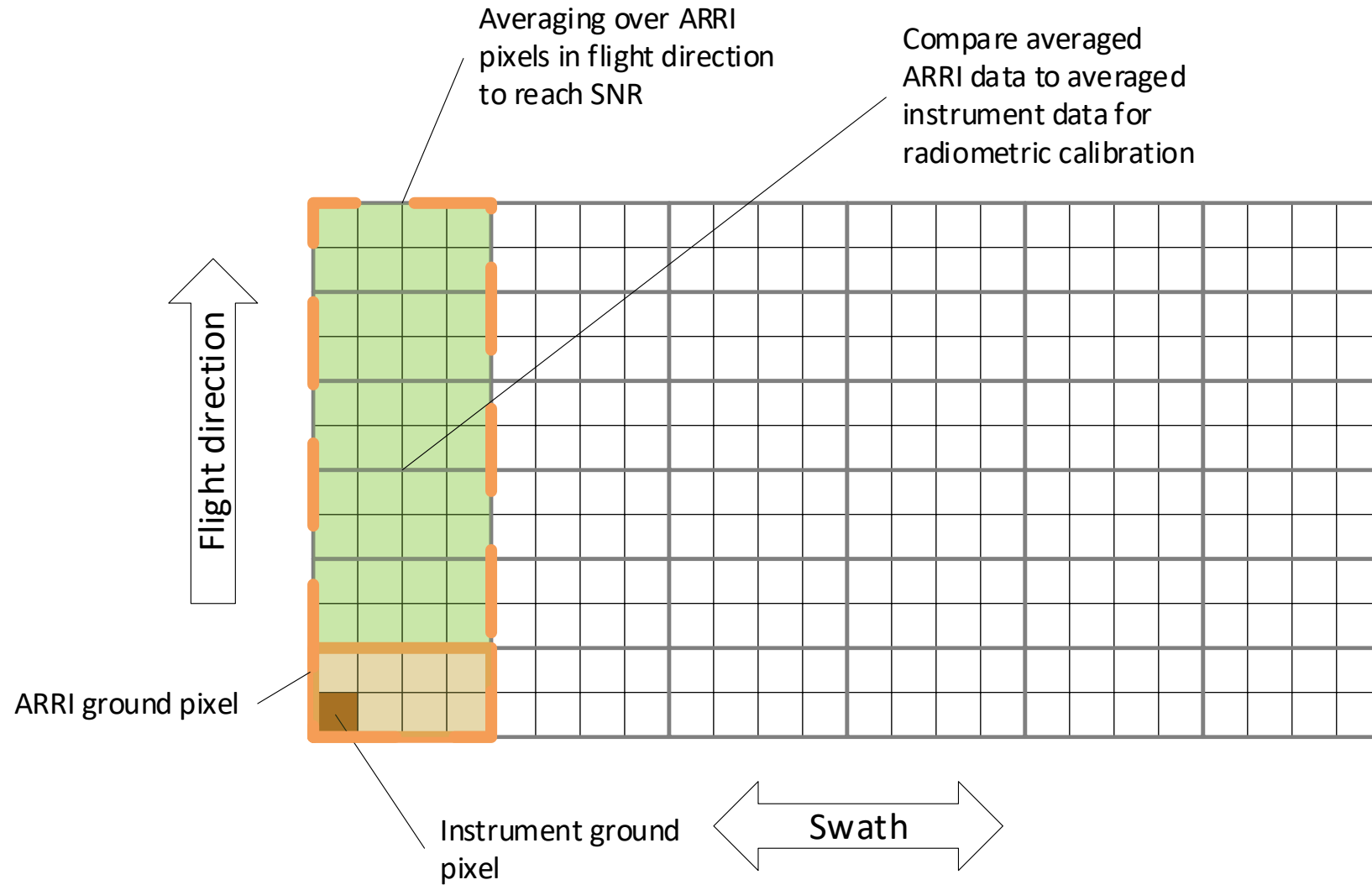
ARRI 1:1 model



200 mm

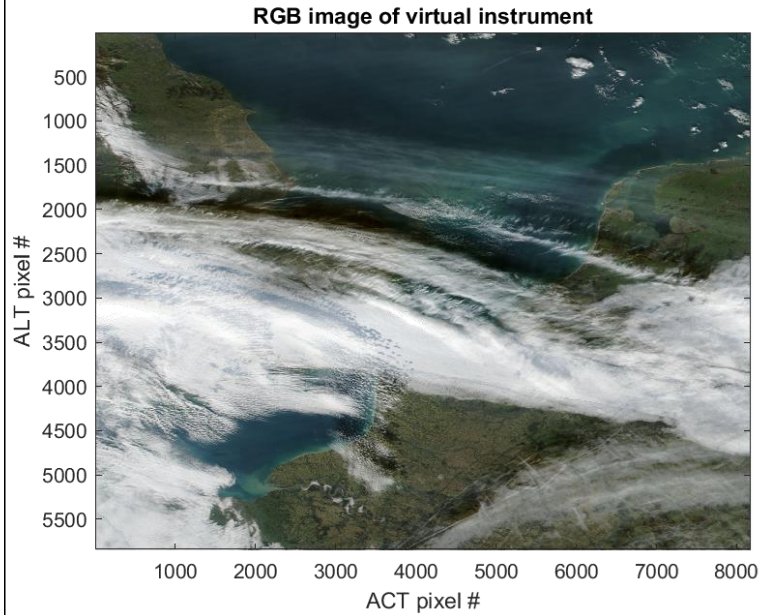


## › ARRI WORKING PRINCIPLE

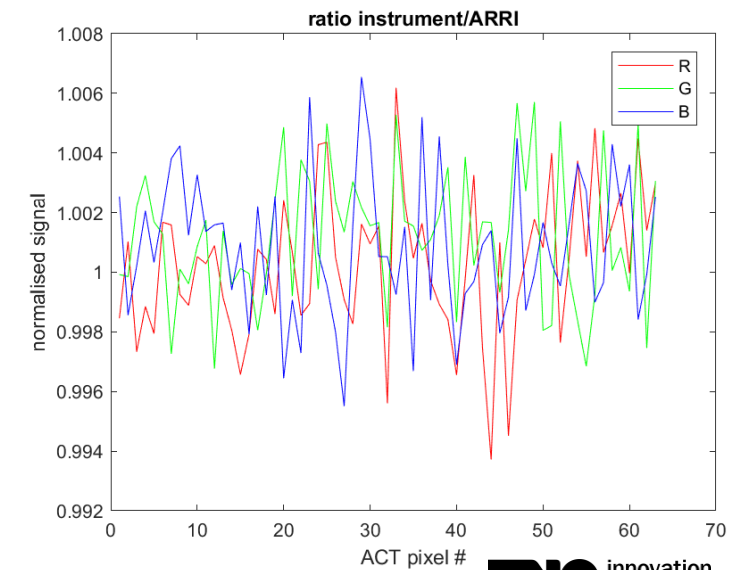
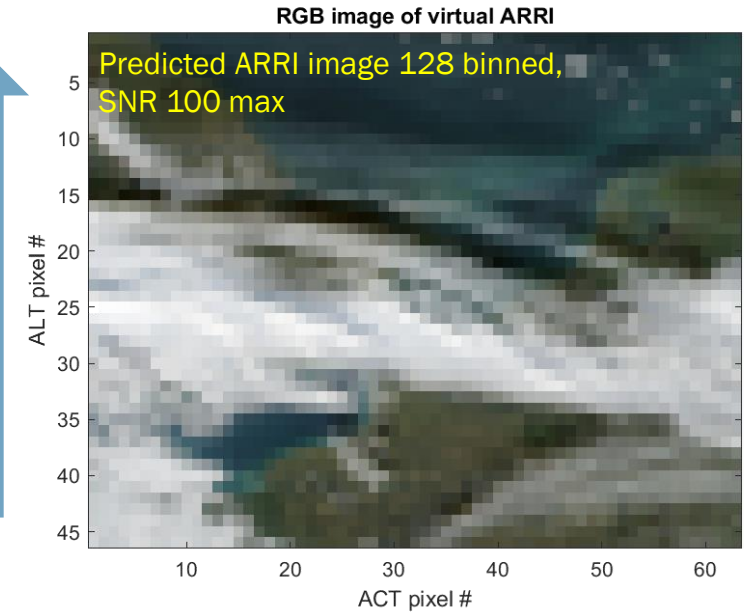
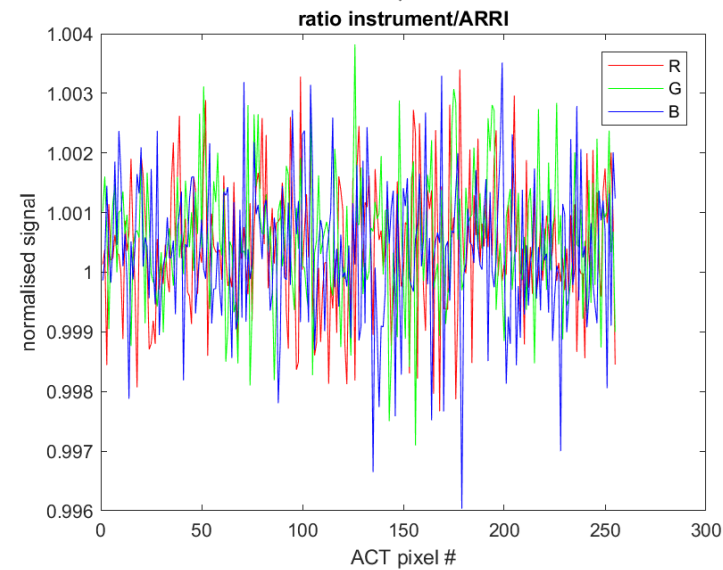
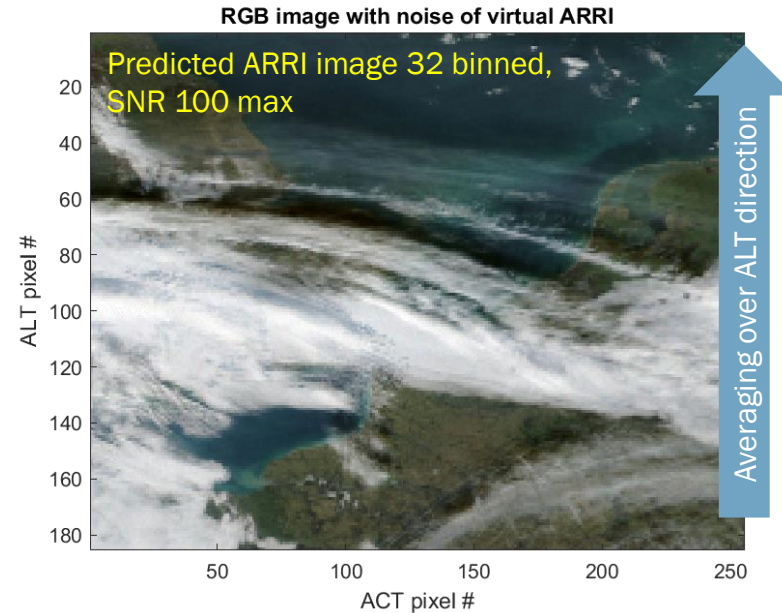




# ARRI WORKING PRINCIPLE



Original image (125 m sampling)





## › ARRI DESIGN

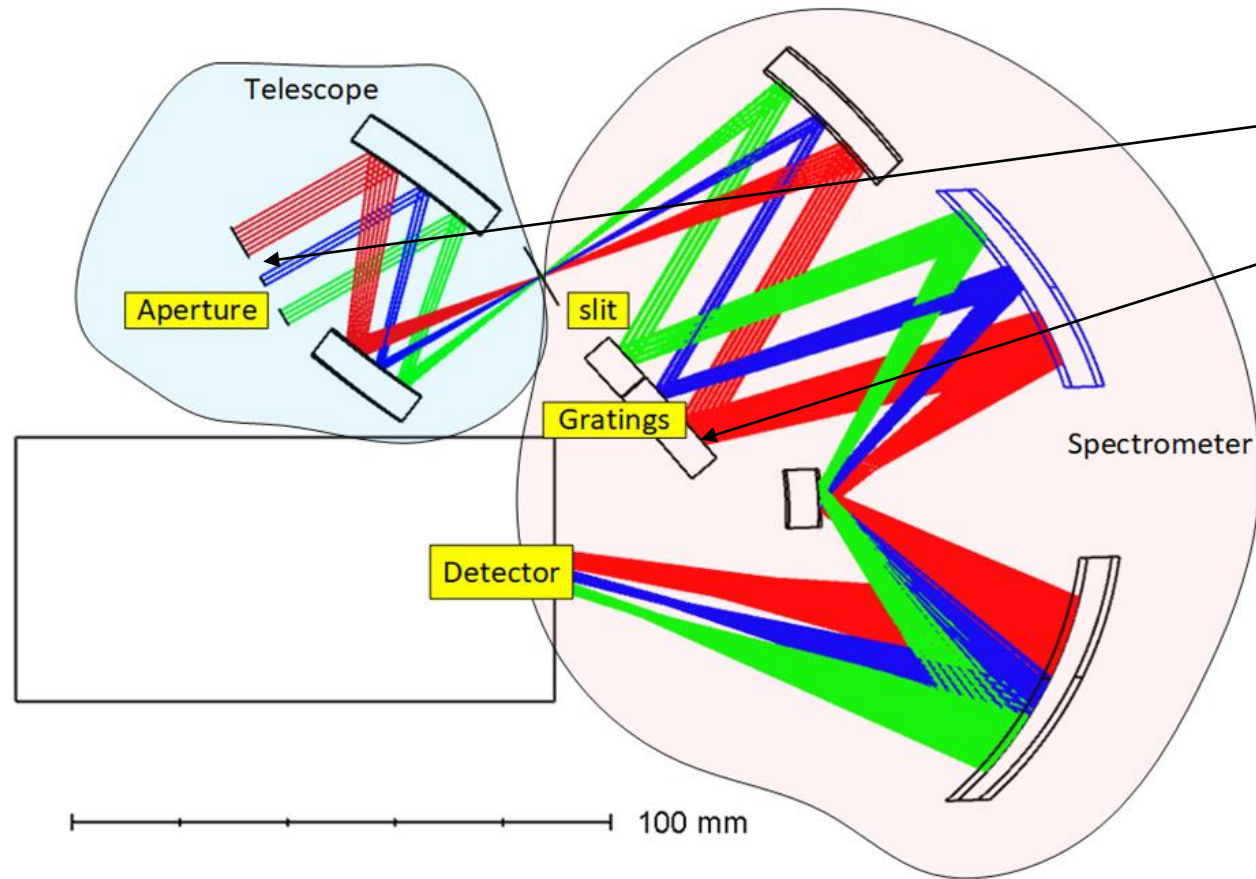
# ASSUMPTIONS AND SPECIFICATIONS

- Low earth orbit.
- The main instruments use a pushbroom strategy.
- The radiometric degradation of the main instrument is not strongly spectrally or spatially dependent. (no high frequent behaviour)

Parameter	Unit	Value	Justification
Altitude	km	800	Similar altitude to Sentinel 5, CO2M, CHIME
Swath	km	150	150 science pixels as a representative case
ACT GSD at nadir	km	1.0	
ALT GSD at nadir	km	35	Maximum temporal misregistration of 5 seconds
Min. wavelength	nm	400	Cover visible band up to shortwave infrared. In this wavelength range the sun is used as reference.
Max. wavelength	nm	2500	
Max. spectral resolution	nm	10-20	Increase towards longer wavelengths.
Min. spectral oversampling	-	1	The value is a compromise to cover the spectral range on a single detector. An oversampling of 2 would have been preferred. For radiometric calibration however it is deemed less important.
Min. spatial oversampling	-	2.0	To enable flexible co-registration
Max. acquisition time	min	30	Well within 1 orbit. This will be composed of multiple time samples.
SNR	-	1000	Within a single orbit. This allows for accurate trend analysis



## › ARRI DESIGN OPTICAL DESIGN



Three apertures for three spectral bands

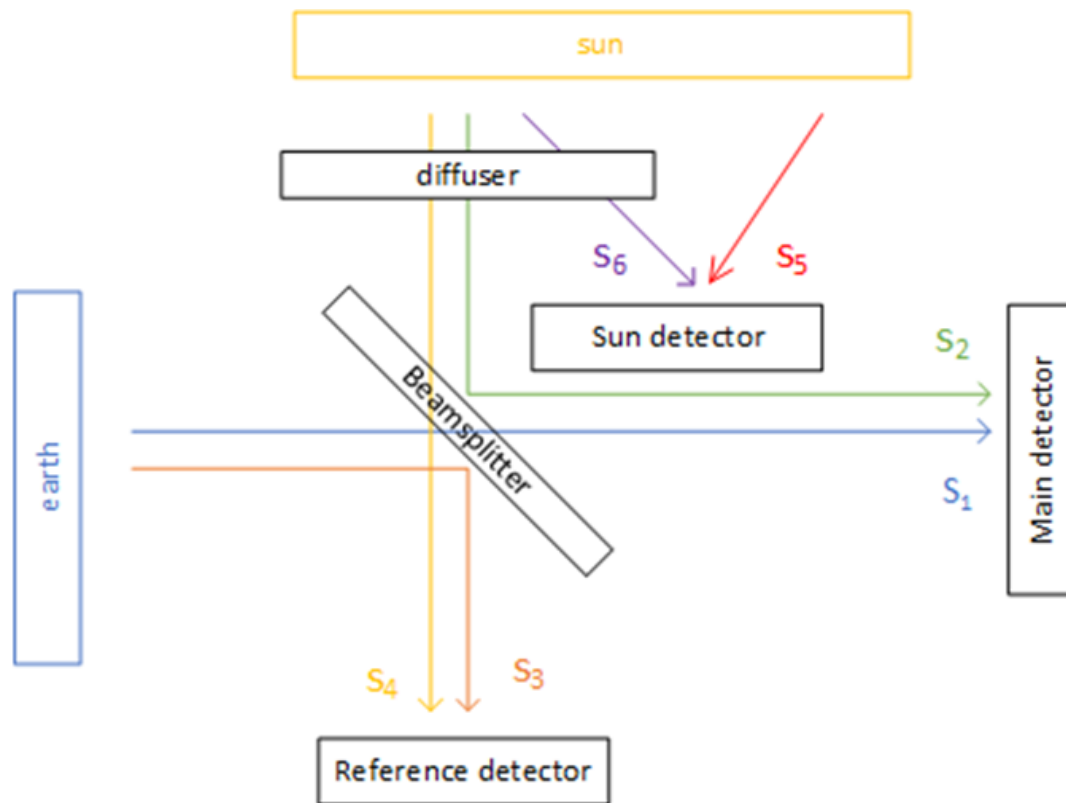
Three gratings for three spectral bands

Band filters to be implemented



## › ARRI DESIGN

### ON BOARD CALIBRATION APPROACH (PATENT PENDING)



Main detector

S<sub>1</sub> Earth radiance signal

S<sub>2</sub> Sun irradiance (via diffuser) signal

Reference detector

S<sub>3</sub> Earth radiance signal

S<sub>4</sub> Sun irradiance (via diffuser) signal

Sun detector

S<sub>5</sub> Sun irradiance signal

S<sub>6</sub> Sun irradiance (via diffuser) signal



# ARRI DESIGN

## BIT OF MATH

Sun observation

$$S_2(\theta, \lambda) = e_{sun}(\lambda) BSDF(\theta, \lambda) R(\theta, \lambda) H_s(\theta, \lambda)$$

$$S_4(\theta, \lambda) = e_{sun}(\lambda) BSDF(\theta, \lambda) T(\theta, \lambda) H_r(\theta, \lambda)$$



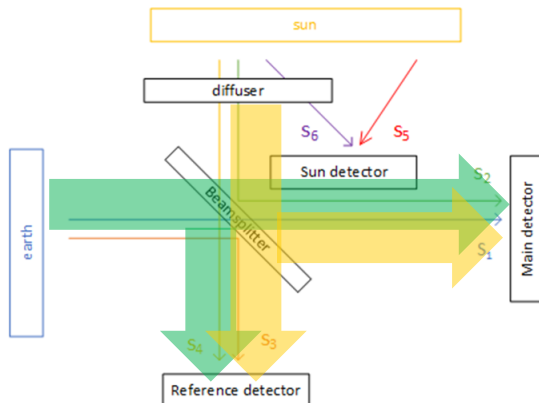
Earth observation

$$S_1(\theta, \lambda) = L_{earth}(\theta, \lambda) T(\theta, \lambda) H_s(\theta, \lambda)$$

$$S_3(\theta, \lambda) = L_{earth}(\theta, \lambda) R(\theta, \lambda) H_r(\theta, \lambda)$$

$$\frac{L_{earth}(\theta, \lambda)}{e_{sun}(\lambda)} = \frac{S_1(\theta, \lambda)}{S_2(\theta, \lambda)} \frac{BSDF(\theta, \lambda) R(\theta, \lambda)}{T(\theta, \lambda)}$$

$$\frac{L_{earth}(\theta, \lambda)}{e_{sun}(\lambda)} = \frac{S_3(\theta, \lambda)}{S_4(\theta, \lambda)} \frac{BSDF(\theta, \lambda) T(\theta, \lambda)}{R(\theta, \lambda)}$$



$$RT(\theta, \lambda) = \frac{R(\theta, \lambda)}{T(\theta, \lambda)} = \sqrt{\frac{S_3(\theta, \lambda) S_2(\theta, \lambda)}{S_4(\theta, \lambda) S_1(\theta, \lambda)}}$$



# ARRI DESIGN

## BIT OF MATH

Sun observation

$$S_5(\lambda) = e_{sun}(\lambda) \cos(\phi_5) H_{sr}(\lambda)$$

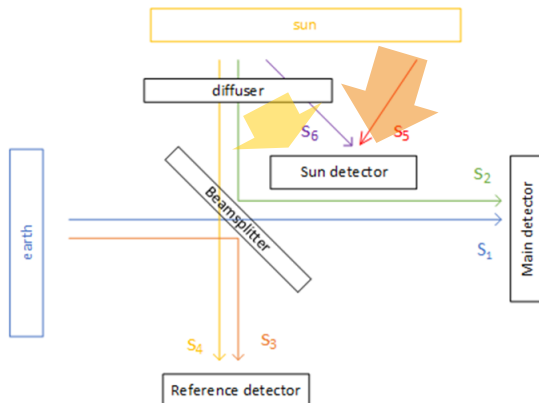


$$S_6(\lambda) = e_{sun}(\lambda) \cos(\phi_6) BSDF(\theta, \lambda) G H_{sr}(\lambda)$$

Direct sun illumination  
(can be anywhere during earth observation)

$$BSDF(\theta, \lambda) = \frac{S_6(\lambda) \cos(\phi_5)}{S_5(\lambda) \cos(\phi_6)} G(\theta)$$

Geometrical factors

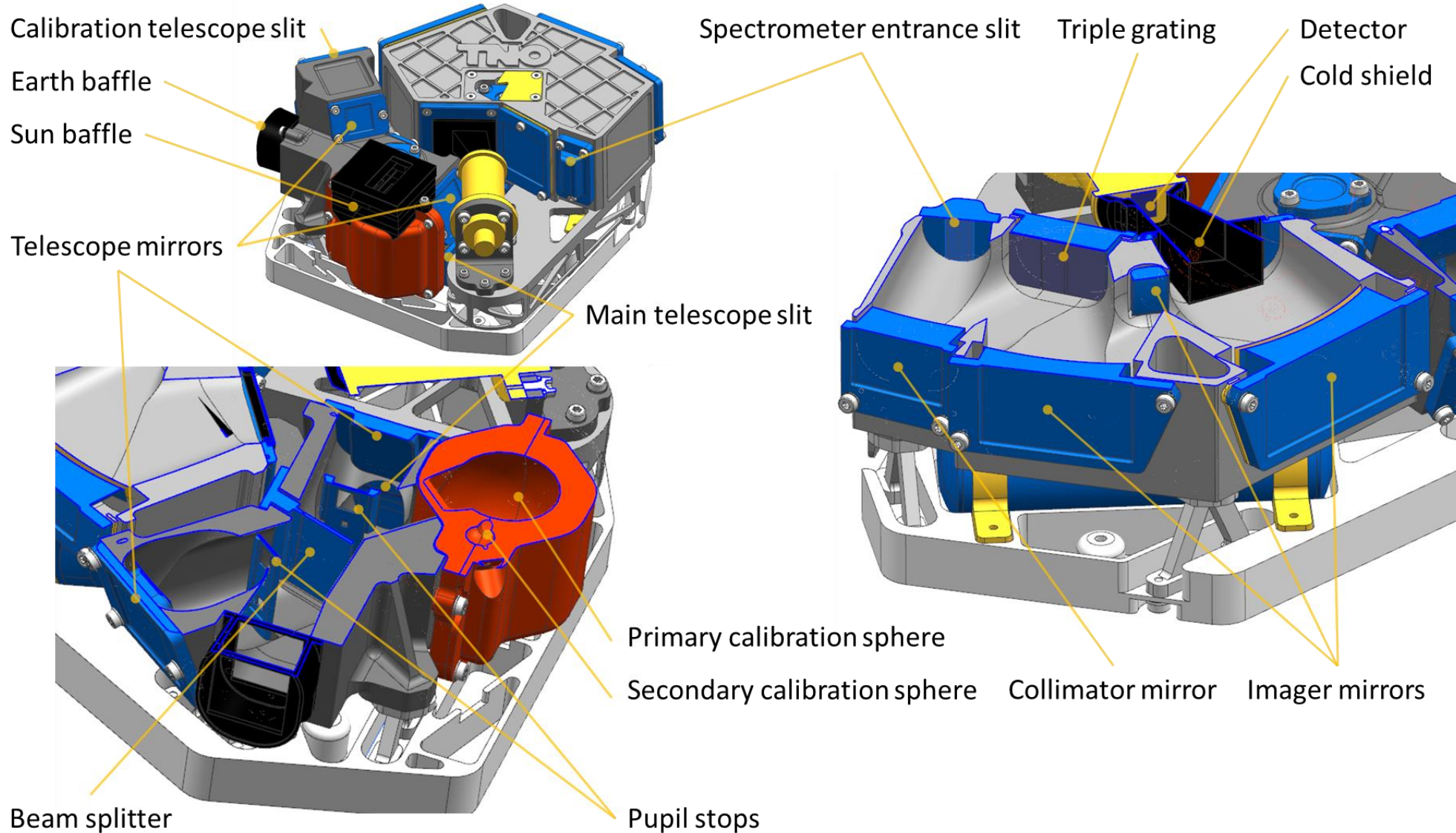


$$\frac{L_{earth}(\theta, \lambda)}{e_{sun}(\lambda)} = \frac{S_1(\theta, \lambda)}{S_2(\theta, \lambda)} \sqrt{\frac{S_3(\theta, \lambda) S_2(\theta, \lambda)}{S_4(\theta, \lambda) S_1(\theta, \lambda)}} BSDF(\theta, \lambda)$$

$$\frac{L_{earth}(\theta, \lambda)}{e_{sun}(\lambda)} = \sqrt{\frac{S_3(\theta, \lambda) S_1(\theta, \lambda) S_6(\lambda) \cos(\phi_5)}{S_4(\theta, \lambda) S_2(\theta, \lambda) S_5(\lambda) \cos(\phi_6)}} G(\theta)$$

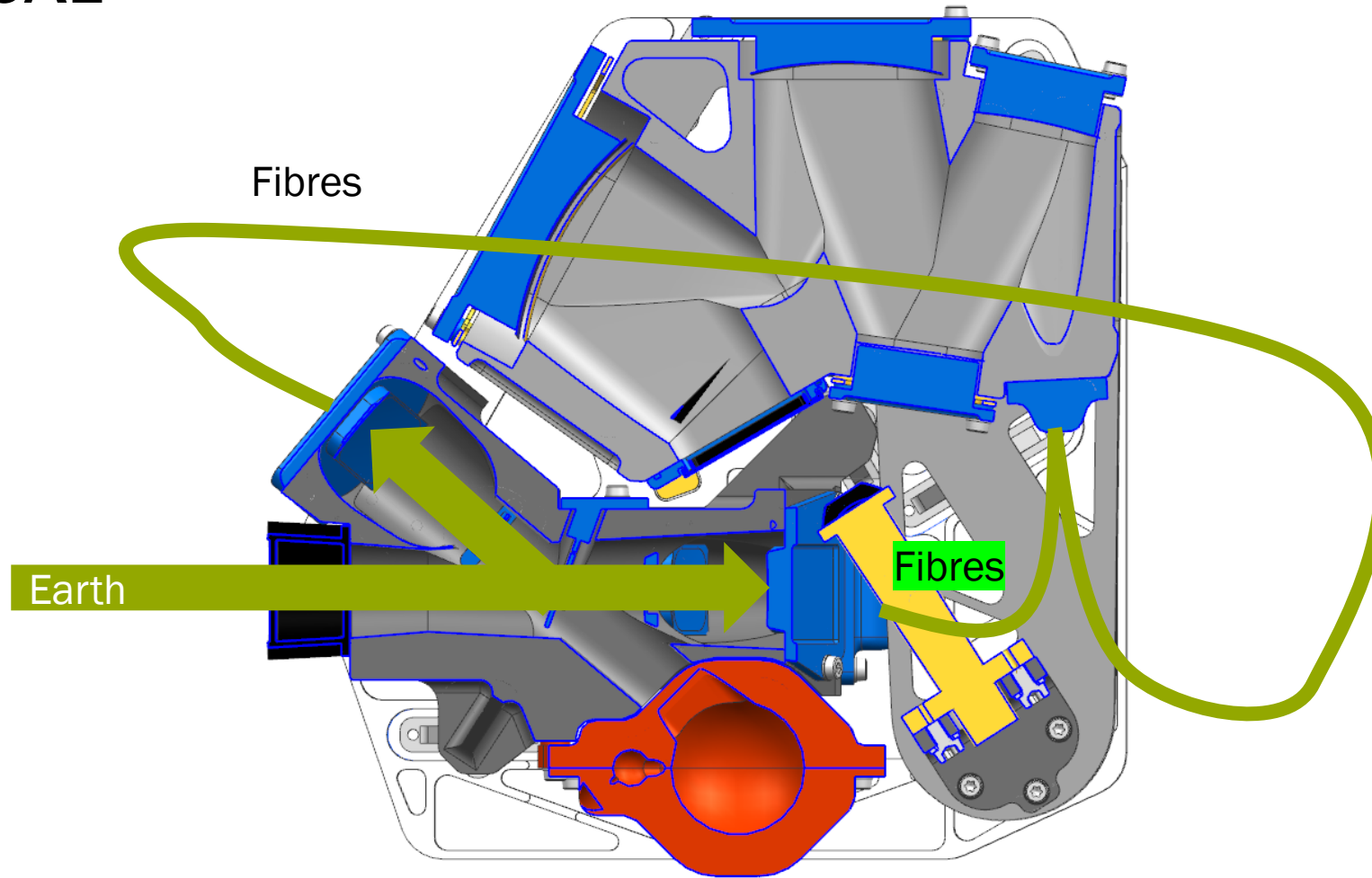


# ARRI DESIGN MECHANICAL



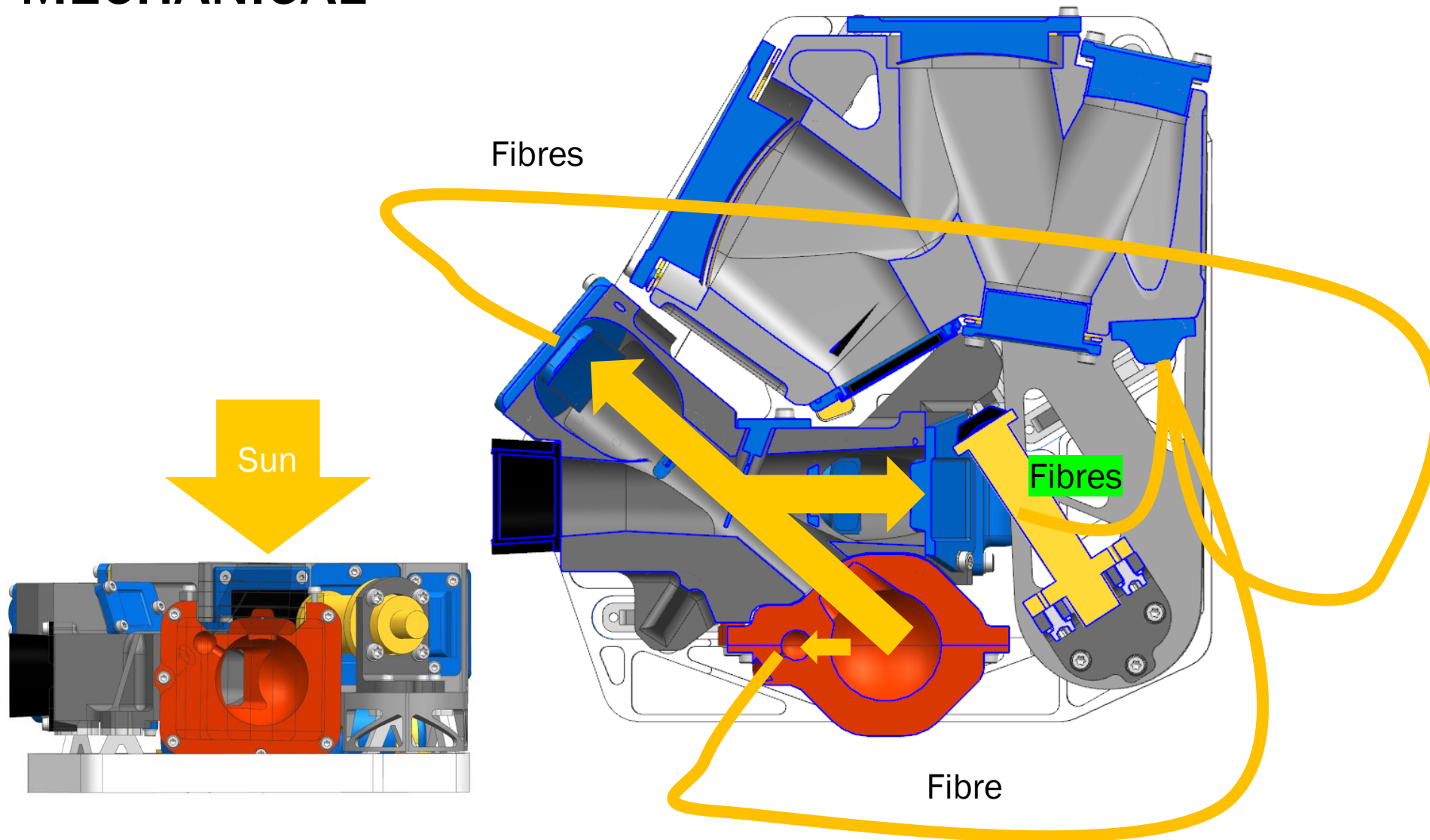


## › ARRI DESIGN MECHANICAL



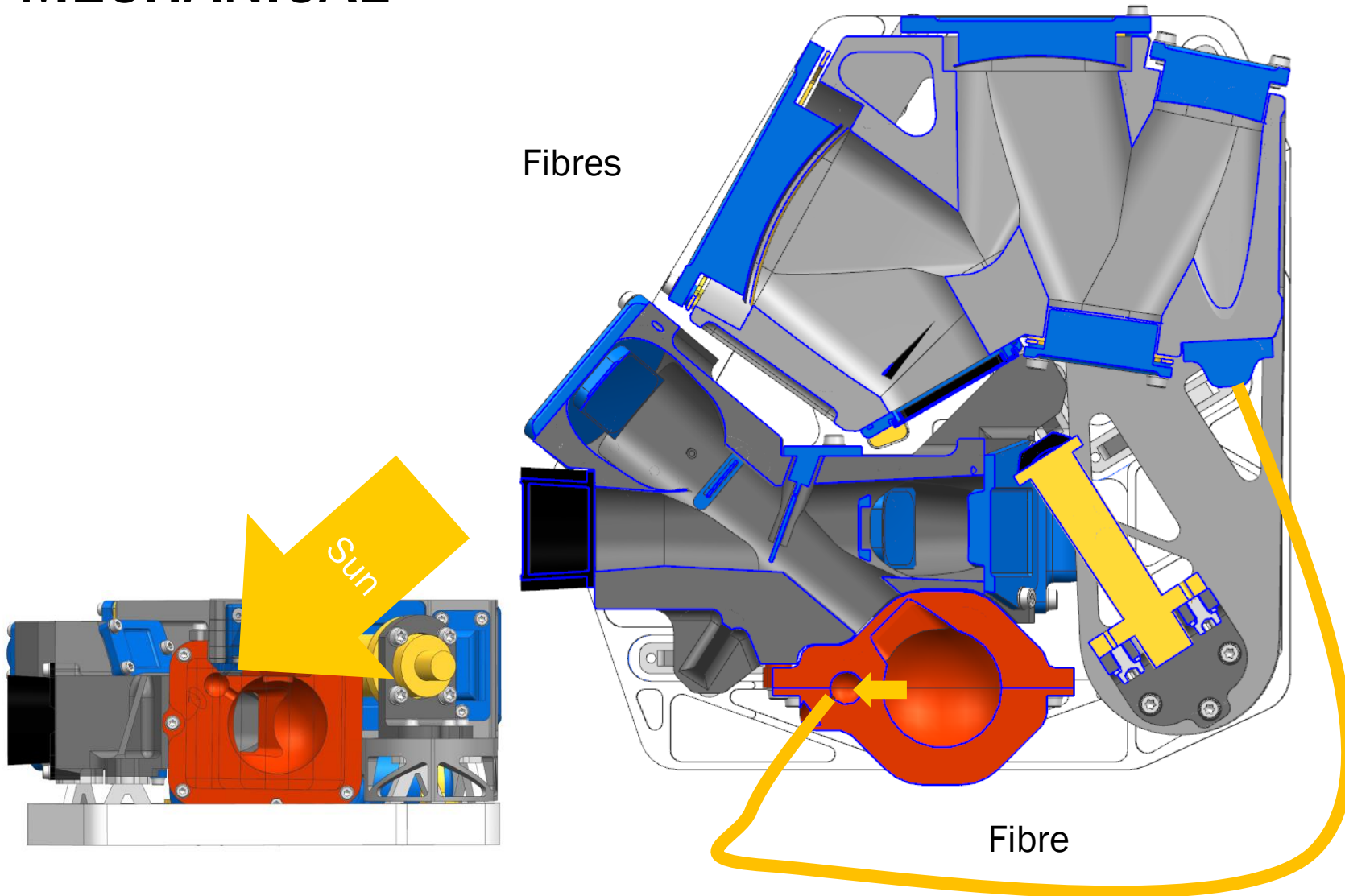


## › ARRI DESIGN MECHANICAL





## › ARRI DESIGN MECHANICAL



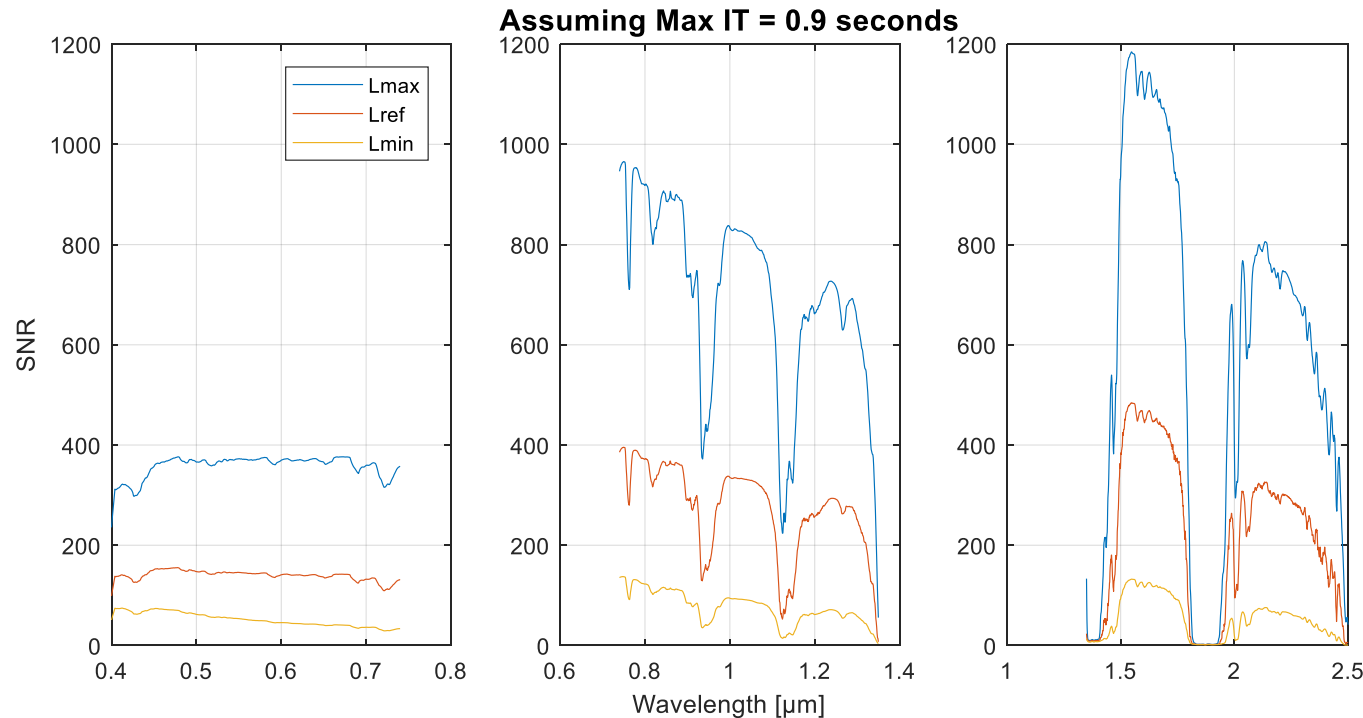


# ARRI PERFORMANCE

## SNR AND RADIOMETRIC UNCERTAINTY

Based on CHIME phase A/B1 spectra

$$\frac{L_{earth}(\theta, \lambda)}{e_{sun}(\lambda)} = \sqrt{\frac{S_3(\theta, \lambda) S_1(\theta, \lambda) S_6(\lambda) \cos(\phi_5)}{S_4(\theta, \lambda) S_2(\theta, \lambda) S_5(\lambda) \cos(\phi_6)}} G(\theta)$$



4xSNR 1000 -> 0.2%

2xSNR 1000 -> 0.14%

Geometrical knowledge  
Negligible error

Based on on-ground  
characterisation  
0.8%

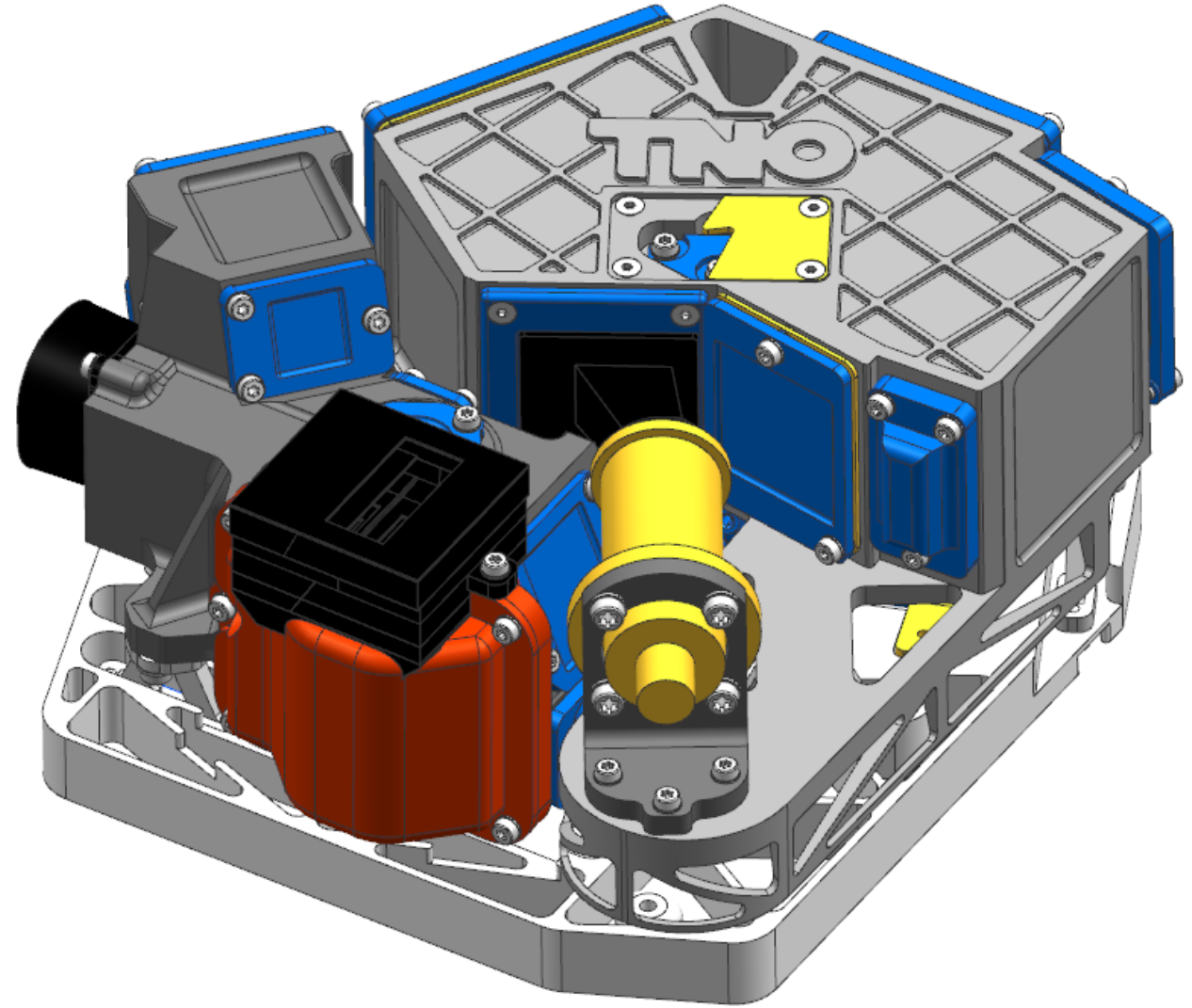
Inter instrument comparison 0.2%

**Radiometric uncertainty main instrument 0.86%**



## › CONCLUSION

- › It is possible to have a small instrument ( 4 U ) providing a radiometric reference.
- › Uncertainty of less than 1% seems feasible
- › In orbit strategies can still be further improved







› **THANK YOU FOR  
YOUR TIME**

**TNO** innovation  
for life