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## Radiometric calibration intercomparison of Sentinel-2 MSI, Sentinel-3 OLCI and Landsat OLI using Deep Convective Clouds

Emphasis on the **Sentinel-2 MSI** and **Landsat OLI** DCC methods

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GSICS Meeting, July 13<sup>th</sup>, 2023

Online meeting

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# Context

## Deep Convective Clouds for calibration monitoring

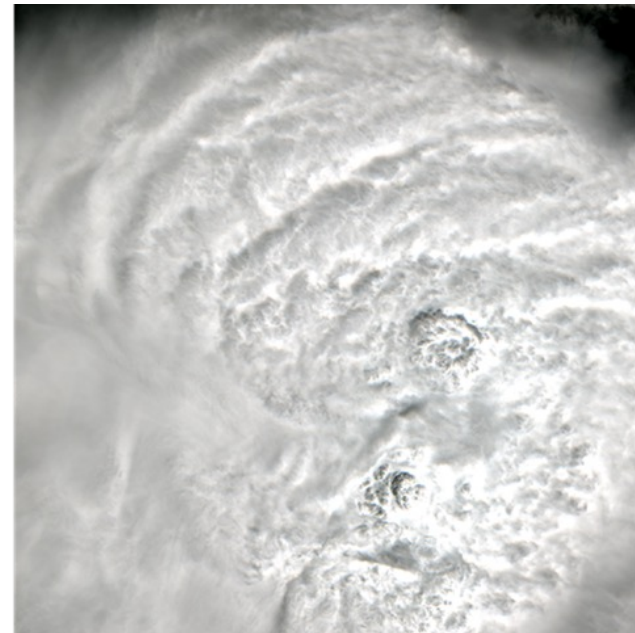
- ❖ DCC used for over two decades (*Vermote and Kaufman, 1995; Hu et al. 2004; Doelling et al. 2004...*)
- ❖ DCC properties:
  - ✓ high altitude (close to tropical tropopause)
  - ✓ high occurrence in the tropics
  - ✓ bright and white (high radiance, spectrally flat)
  - ✓ very vertically-extended, high optical thickness (low/no signal from beneath the cloud)



*Expedition Crew 16, ISS, Image Science and Analysis Laboratory, Johnson Space Center*

## Deep Convective Clouds for calibration monitoring

- ❖ DCC used for over two decades (*Vermote and Kaufman, 1995; Hu et al. 2004; Doelling et al. 2004...*)
- ❖ DCC properties:
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  - ✓ bright and white (high radiance, spectrally flat)
  - ✓ very vertically-extended, high optical thickness (low/no signal from beneath the cloud)
  - ✓ can be very extended horizontally
  - ✓ nearly Lambertian



*DCC extending over a complete S2 tile  
(~100x100 km<sup>2</sup>)*

DCC cross-sensor intercalibration → 2 twin sensors

❖ **Sentinel-3 OLCI A/B**

- ✓ From November 2019
- ✓ *Lamquin et al. (2020) OLCI A/B Tandem Phase Analysis, Part 3: Post-Tandem Monitoring of Cross-Calibration from Statistics of Deep Convective Clouds Observations. Remote Sens. 2020, 12, 3105. <https://doi.org/10.3390/rs12183105>*

❖ **Adaptation to Sentinel-2 MSI A/B**

- ✓ From early 2022 to now
- ✓ Presented at CALCON 2022: *Monitoring Sentinel-2 MSI inter-calibration using Deep Convective Clouds*

❖ **Adaptation to Landsat-8 OLI / Landsat-9 OLI-2**

- ✓ From early 2022 to early 2023

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# DCC flowchart Sentinel-2 MSI A and B

Copernicus data hub query

- For a given time period
- 90% min cloud cover

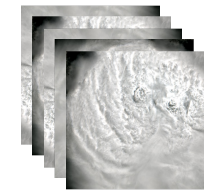
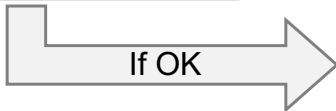


List of products



Filtering

- Footprint > 0.1
- -20 to 20° latitude
- $B10 > 0.3 > 5e5$
- Quality check



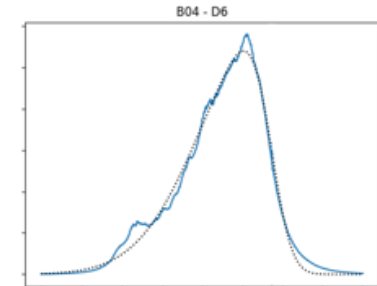
Good products list

~1200/2500 each month

For each product in Good products list:

Format data
<ul style="list-style-type: none"> <li>▪ S2 L1C = TOA reflectance</li> <li>▪ Down sample all bands to 60 m</li> <li>▪ Scale to 0 - ~1 TOA reflectances</li> </ul>
Get metadata
<ul style="list-style-type: none"> <li>▪ Ozone in DU</li> <li>▪ Sun-earth distance</li> <li>▪ Angles (SZA, VZA)</li> </ul>
DCC clusters extraction
<ul style="list-style-type: none"> <li>▪ <math>B10 &gt; 0.4</math> &amp; <math>B8A &gt; 0.7</math></li> <li>▪ Remove small clusters</li> <li>▪ Shadow dilation (avoid gaps)</li> </ul>
DCC pixels processing
<ul style="list-style-type: none"> <li>▪ Correction of gaseous trans.</li> <li>▪ PDF of DCC pixels</li> </ul>

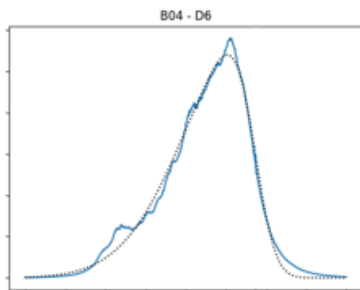
## Methodology Sentinel-2 MSI



Top of DCC reflectance PDF for each band and detector

~1200/2500 each month

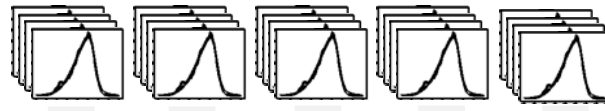
# Methodology Sentinel-2 MSI



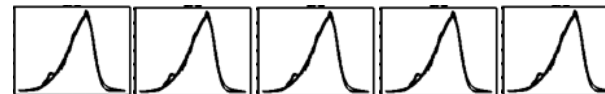
Top of DCC  
reflectance PDFs for  
each band and  
detector

~1200/2500 each  
month

5 batches of ~400 PDFs



Accumulation

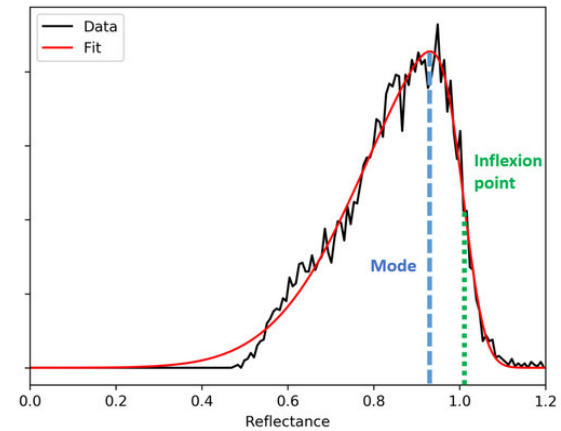


5 accumulated PDFs

For each accumulated PDF:

Skewed-Gaussian fit

Post-mode inflexion point extraction



Reflectance indicator  
=  $\text{mean}_{5 \text{ batches}}$  inflexion points

Estimation of the random uncertainty  
=  $\text{STD}_{5 \text{ batches}}$  inflexion points

For each band and detector



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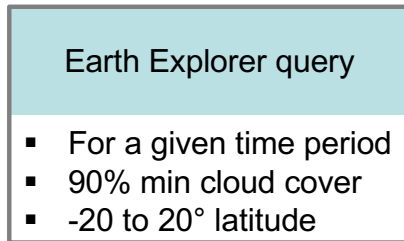


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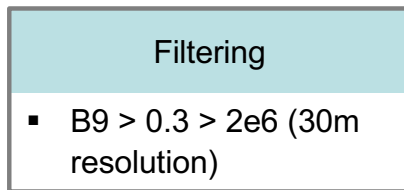
# DCC flowchart Landsat-8 and 9 OLI

## Methodology Landsat OLI

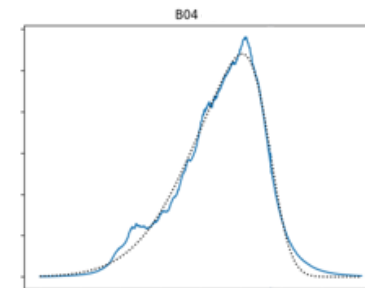
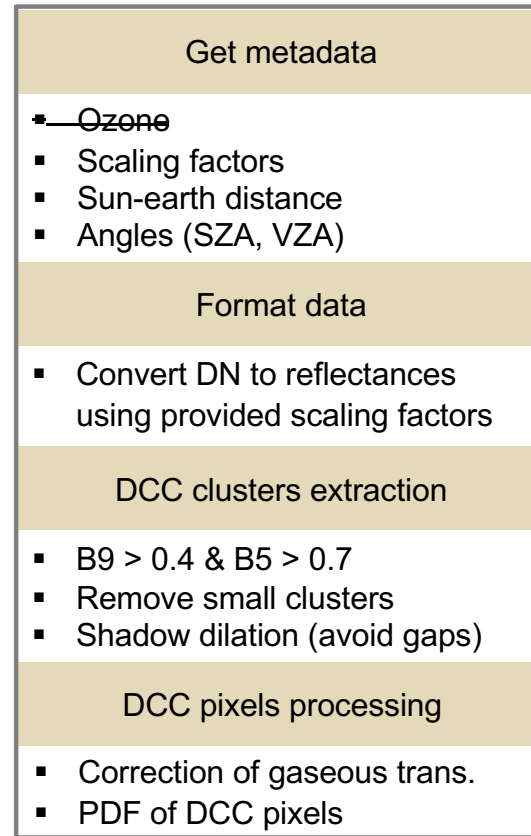


List of products

For each product in products list:



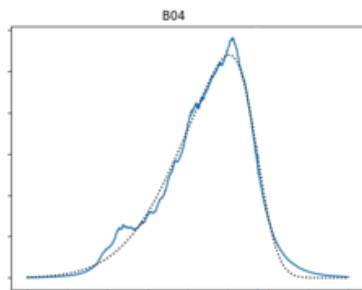
If filtering OK:



Top of DCC  
reflectance PDF  
for each band  
~~and detector~~

~200/300 each month

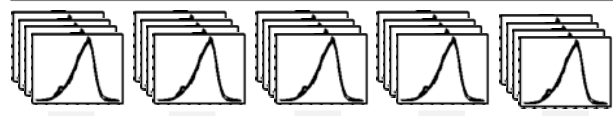
# Methodology Landsat OLI



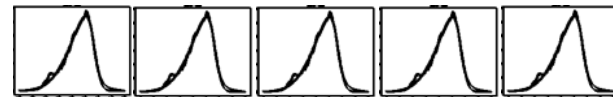
Top of DCC  
 reflectance PDFs for  
 each band and  
 detector

~200/300 each month

5 batches of ~40/60 PDFs



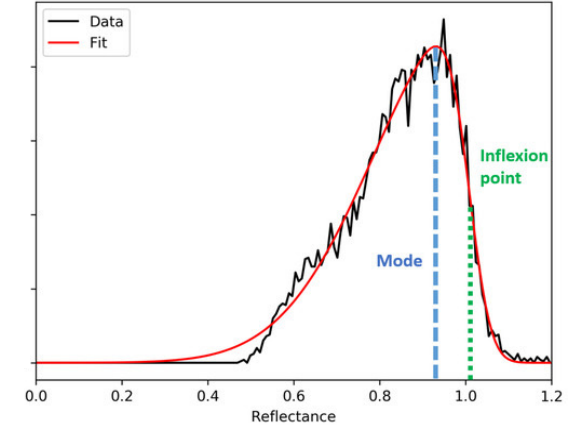
Accumulation



5 accumulated PDFs

For each accumulated PDF:  
 Skewed-Gaussian fit

Post-mode inflexion point extraction



Reflectance indicator  
 =  $\text{mean}_{5 \text{ batches}} \text{ inflection points}$

Estimation of the random uncertainty  
 =  $\text{STD}_{5 \text{ batches}} \text{ inflection points}$

For each band and detector

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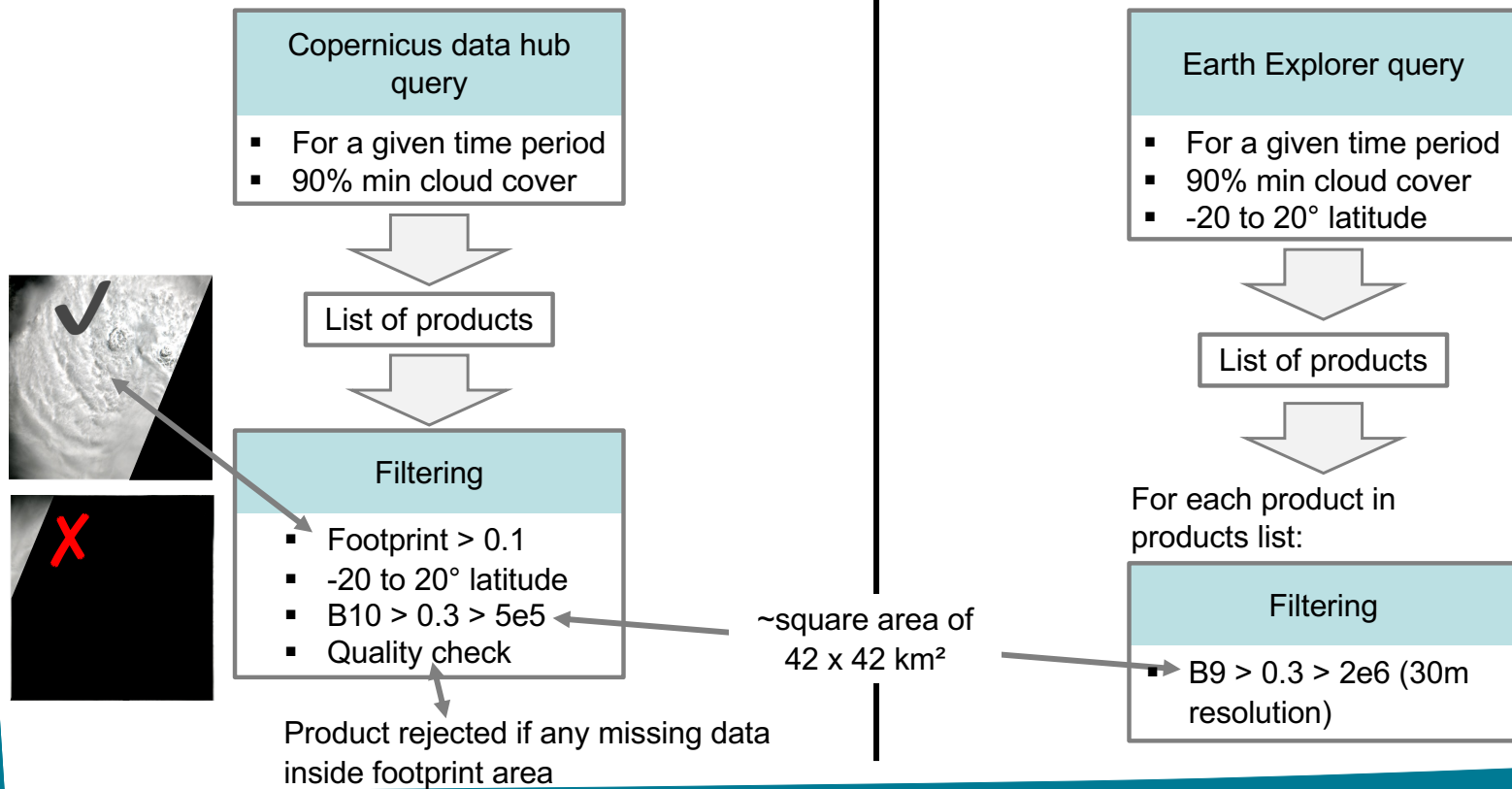
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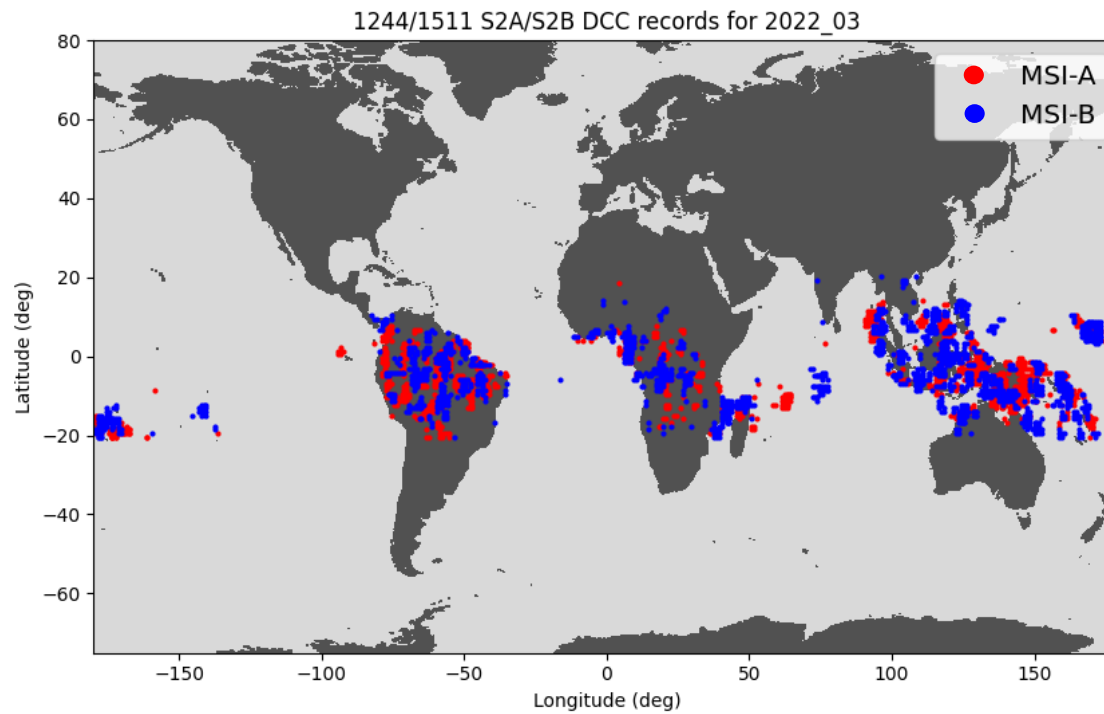


## Detailed methodology

## Products filtering

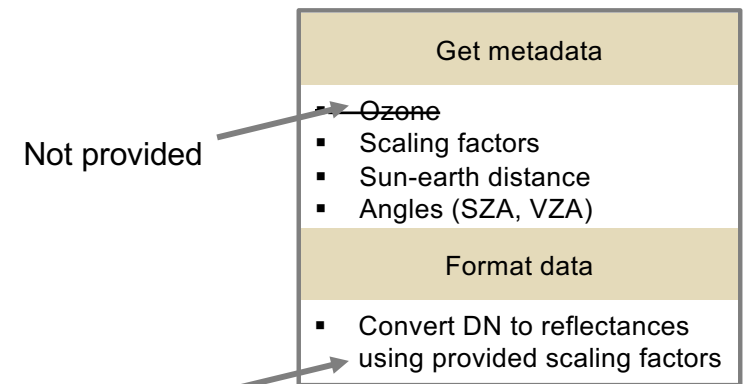
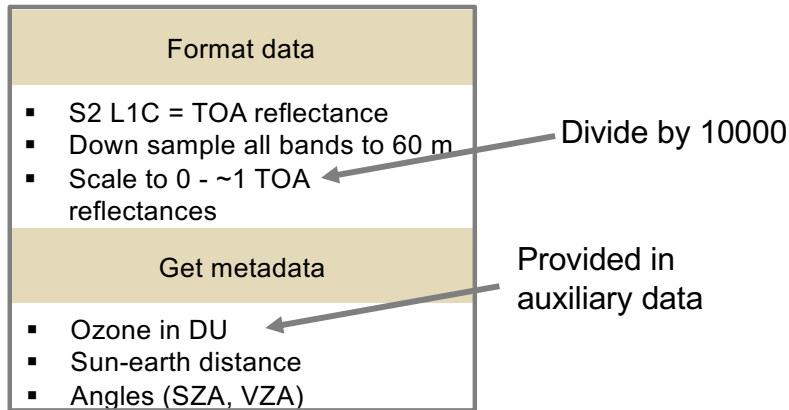
Sentinel-2 Landsat-8/9





*Example localization of the DCC products for Sentinel-2 MSI, March 2022.*

Sentinel-2 Landsat-8/9



$$\rho_{TOA|\lambda} = (M_p Q_{cal} + A_p) / \cos(SZA)$$

With:

$\rho_{TOA|\lambda}$  the TOA reflectance,

$M_p$  the band-specific multiplicative scaling factor,

$Q_{cal}$  the quantized and calibrated standard product pixel values (DN),

$A_p$  the band specific additive scaling factor,

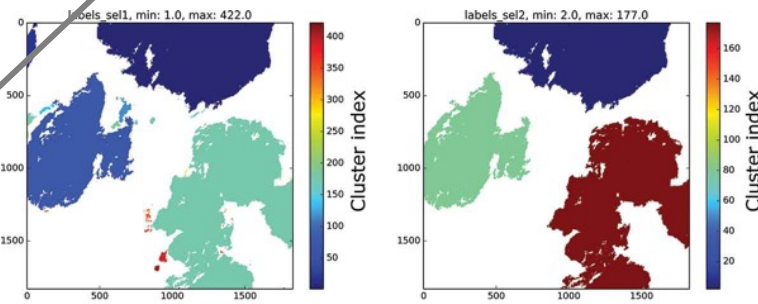
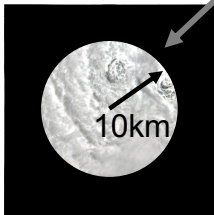
$\cos(SZA)$  the local sun zenith angle.

### Sentinel-2

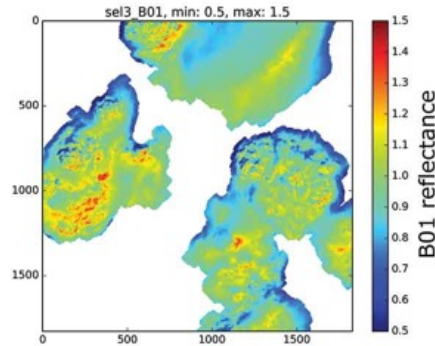
- Get clusters from thresholds on cirrus and NIR bands
- Label clusters from `scipy.ndimage.label`
- Remove cluster with area lower than 314 km<sup>2</sup>

DCC clusters extraction

- **B10 > 0.4 & B8A > 0.7**
- Remove small clusters
- Shadow dilation (avoid gaps)



- Iterative dilation (30 pixels for S2, 60 for Landsat) of clusters by binary erosion of the negative mask (`scipy.ndimage.binary_erosion`): remove gaps and get continuous DCCs



## Processing

### Landsat-8/9

DCC clusters extraction

- **B9 > 0.4 & B5 > 0.7**
- Remove small clusters
- Shadow dilation (avoid gaps)



## Sentinel-2, Landsat-8/9

DCC pixels processing

- Correction of gaseous trans.

Nadir gaseous transmissions from top of DCC to TOA using RTM (ARTDECO code)  
Standard profiles of H<sub>2</sub>O, NO<sub>2</sub>, O<sub>2</sub>, CO<sub>2</sub>, CH<sub>4</sub>  
Fixed DCC height of 16 km

Variable content of O<sub>3</sub> (from 200 to 350 DU)Fixed content of O<sub>3</sub> (260 DU)

$$\rho_{DCC}(\theta_s, \theta_v, \Delta\varphi, \lambda) = \rho_{TOA}(\theta_s, \theta_v, \Delta\varphi, \lambda) / T_{gas}(\theta_s, \theta_v, \lambda)$$

With:

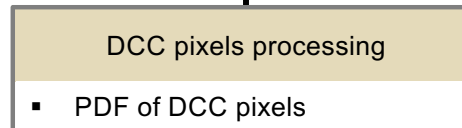
$$T_{gas} = T_{gas|nadir}^{airmass/2}$$

$$airmass = 1/\cos(SZA) + 1/\cos(VZA)$$

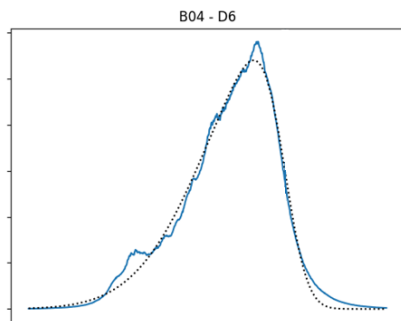
$T_{gas|nadir}$  is the gaseous transmission, function of  
ozone content of the product

$T_{gas|nadir}$  is the gaseous transmission, with the  
assumption of a fixed content of ozone

Sentinel-2 Landsat-8/9



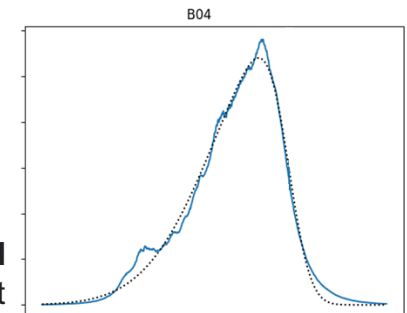
Calculation of a Probability Density Function for the selected top of DCC reflectances  
 From 0.5 to 1.3 with a reflectance step of 0.001 for VNIR bands  
 From 0 to 0.8 with the same step for SWIR bands (lower reflectances)  
 Typically a hundred thousand to millions of pixels selected



One distribution for **each band** and **each detector\*** for each processed product

Typically, ~1200/2500 products each month both for S2A/S2B

*\*All 12 detectors are not present in a single image, S2 swath is of 290 km while products are about 100 width*

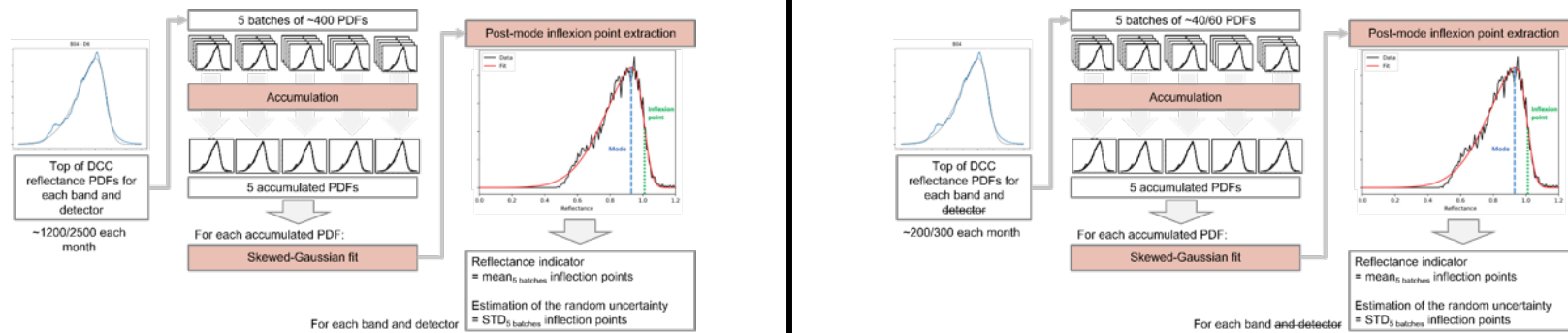


One distribution for **each band** for each processed product

Typically, ~200/300 products each month both for Landsat-8 and 9

Once a month of DCC corrected reflectance PDFs have been collected:

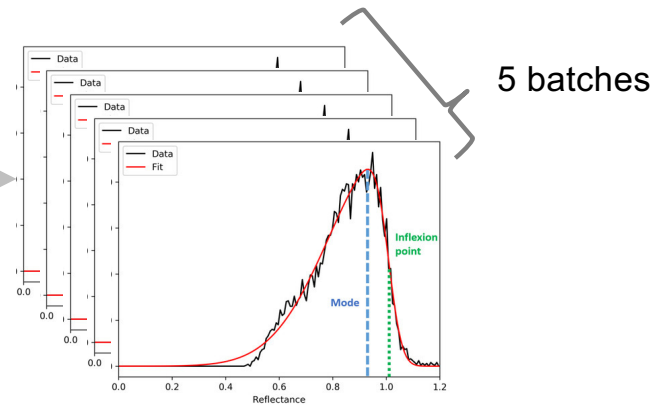
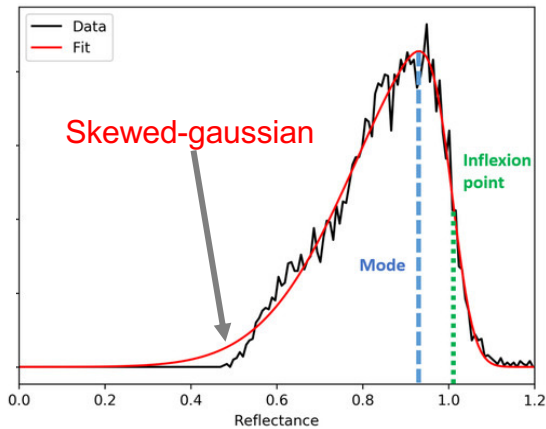
Sentinel-2 Landsat-8/9



- Random draw of 5 batches of PDFs (~400 per batch for S2, 30/40 per batch for Landsat)
- PDFs from each batch are accumulated to form one single PDF per month / per batch / per band / per det. for S2
- Fit of a skewed-gaussian function over the accumulated PDF

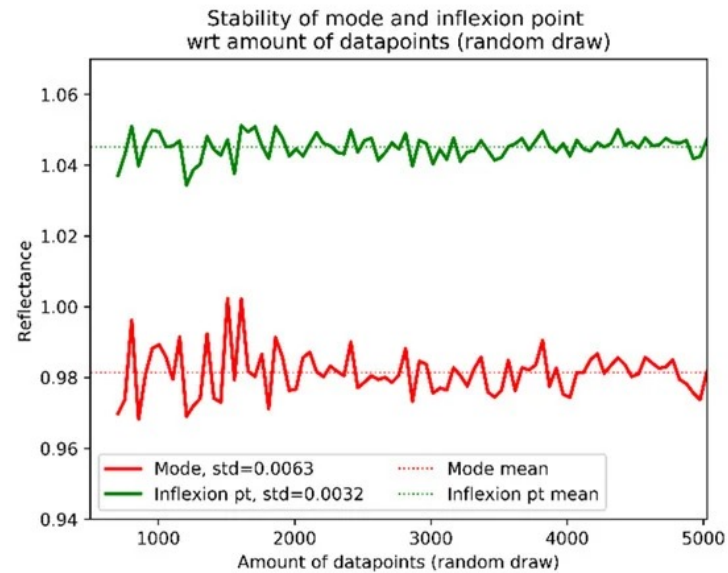
**Sentinel-2**, for each band and detector  
**Landsat-8/9**, for each band only

Post-mode inflexion point extraction



Reflectance indicator  
 =  $\text{mean}_{5 \text{ batches}} \text{ inflexion points}$

Estimation of the random uncertainty  
 =  $\text{STD}_{5 \text{ batches}} \text{ inflexion points}$



From Lamquin et al. (2020) OLCI A/B Tandem Phase Analysis, Part 3: Post-Tandem Monitoring of Cross-Calibration from Statistics of Deep Convective Clouds Observations. *Remote Sens.* 2020, 12, 3105. <https://doi.org/10.3390/rs12183105>

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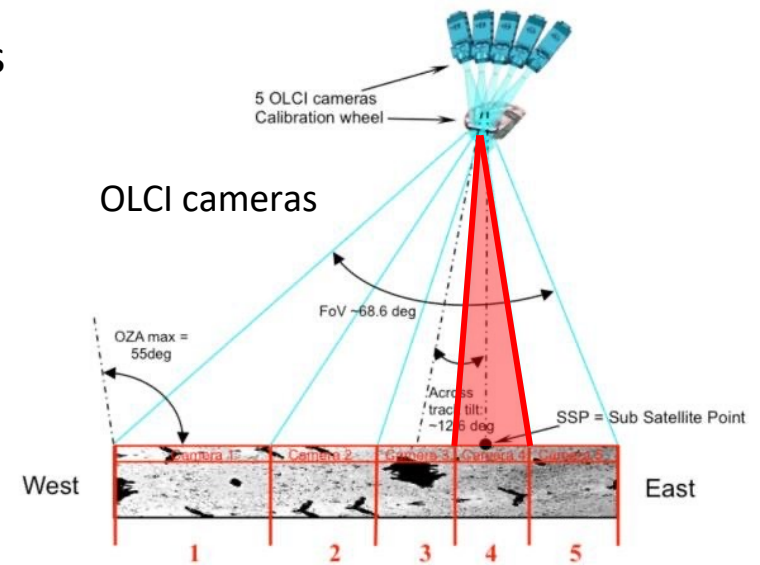
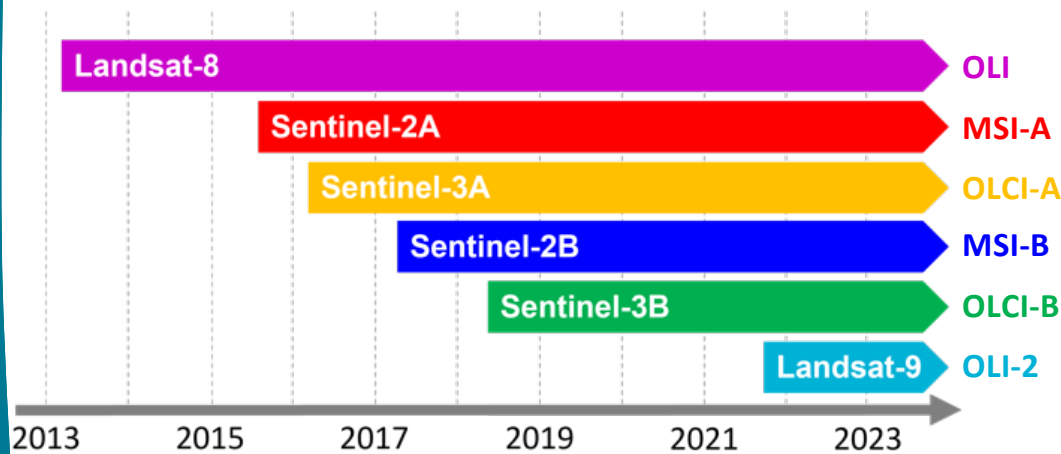
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## Definition of the objectives

## Objectives definition

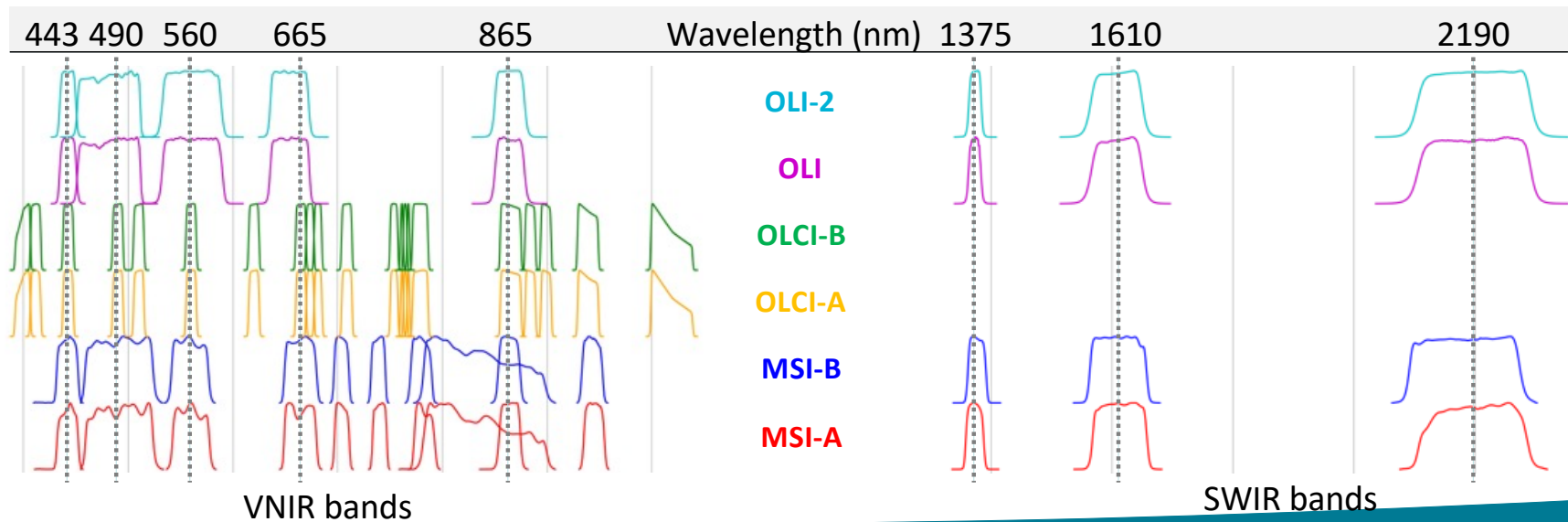
### Application of DCC method to 6 multispectral sensors



- ❖ Comparisons between twin sensors (cross-comparisons)
- ❖ 185, 290 and 1270 km swath for Landsat, S2 and S3
  - ✓ Use of near-nadir camera only for S3 (cam-4)
- ❖ Comparisons between all sensors (time-series intercomparisons) from March 2022 to January 2023

## Bands of interest

- ❖ Focus on several “comparable” bands
  - ✓ 5 in the VNIR (for all sensors)
  - ✓ 3 in the SWIR (OLCI excepted)







### Objectives are:

- ❖ Follow the intercalibration of each pair of “twin” sensors
- ❖ Follow the relative levels of the comparable bands of the different missions
- ❖ Detect a potential drift

### Objectives aren't:

- ❖ Provide an absolute level of radiometric calibration
- ❖ Rank the sensors in terms of radiometric accuracy

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# Results

## Average spectra

OLI-2

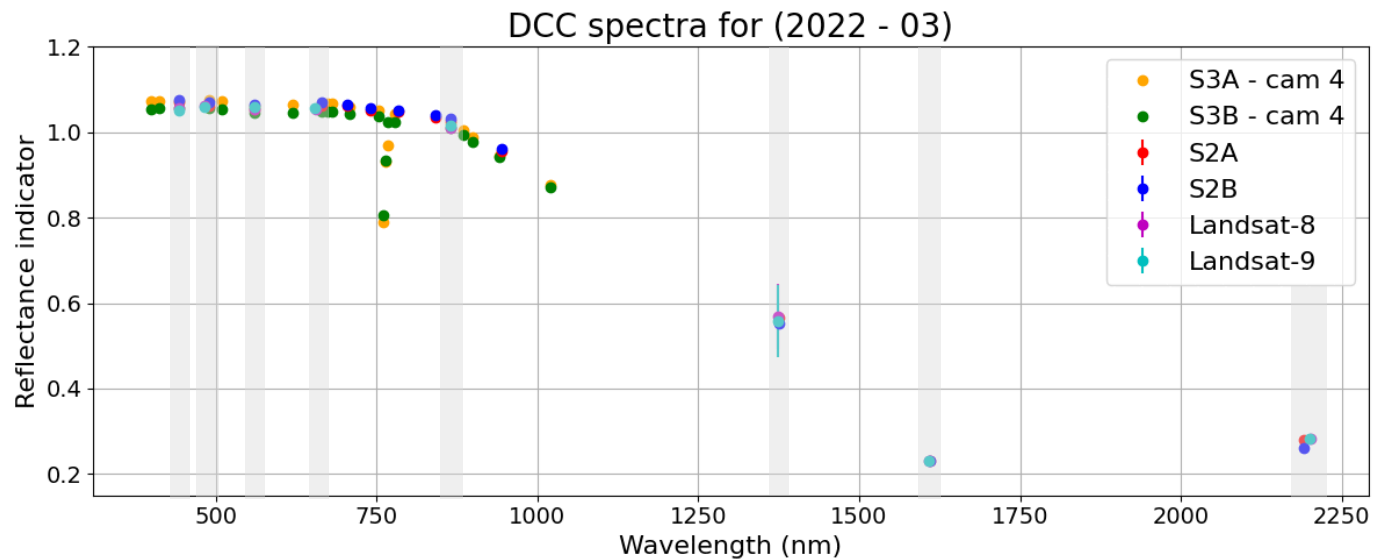
OLI

OLCI-B

OLCI-A

MSI-B

MSI-A



## Sensor-wise:

- ❖ VNIR: 3 % dispersion (except 01/2023 443nm, ~4%)
- ❖ Alignment of 1610 nm SWIR band ~correct
- ❖ More dispersion in cirrus and last SWIR band

## Temporally:

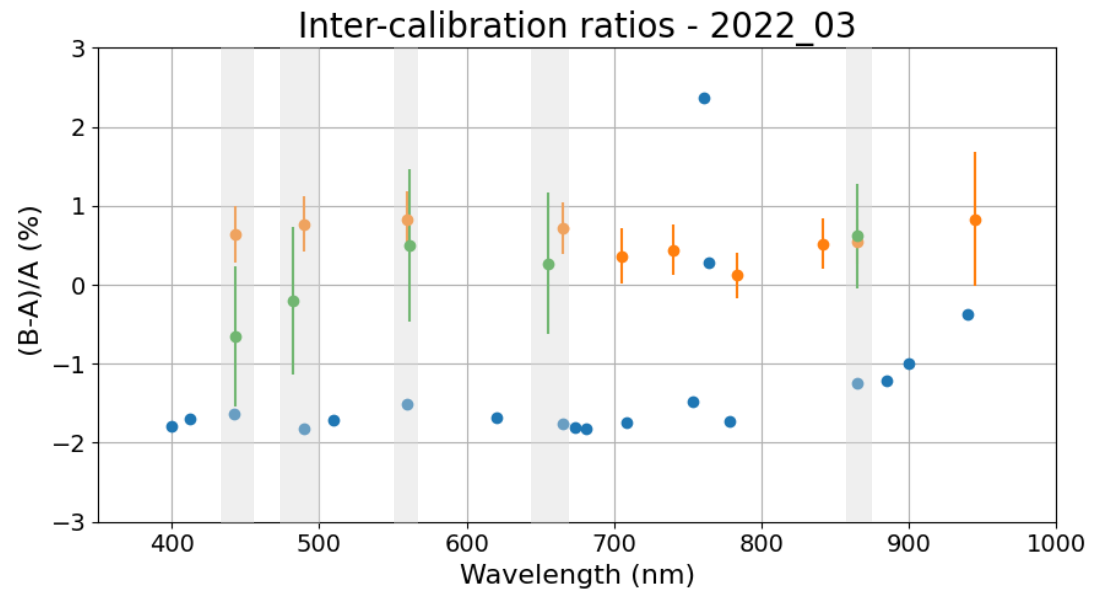
- ❖ Each sensor's VNIR band within 2 %
- ❖ More variability in the SWIR (cirrus band)

### VNIR inter-calibration ratio

$$\frac{OLI2 - OLI}{OLI} \times 100$$

$$\frac{MSIB - MSIA}{MSIA} \times 100$$

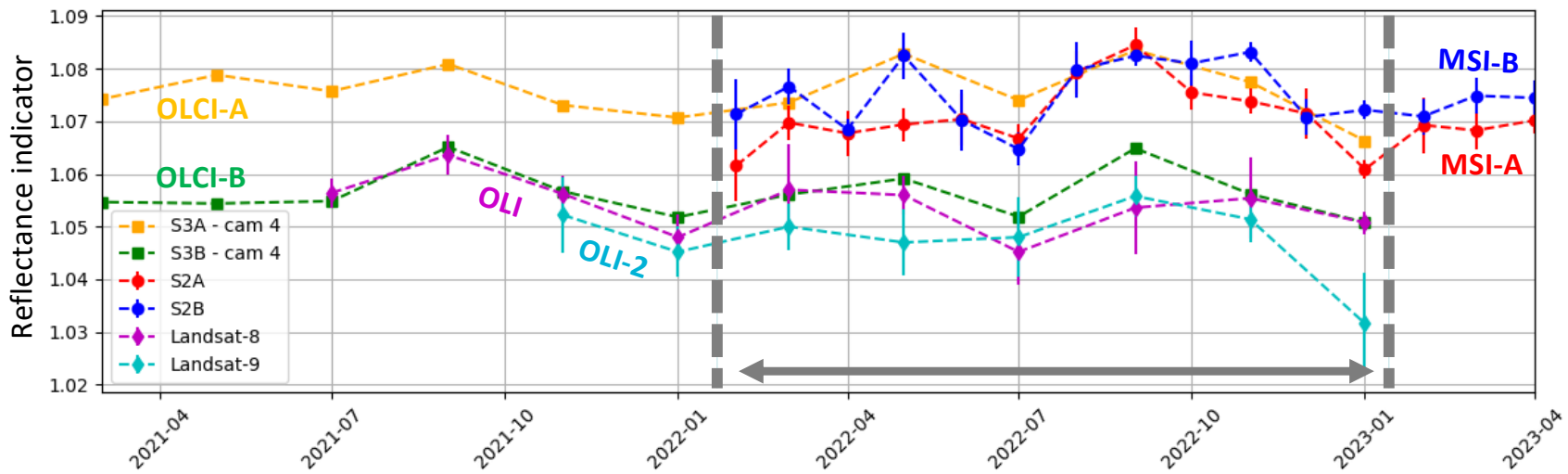
$$\frac{OLCIB - OLCIA}{OLCIA} \times 100$$



- ❖ S3 bias: ~2 % in the VIS, ~1 % in the NIR, OLCI-A brighter
- ❖ S2 ratios: around 0, up to 1.5 %
- ❖ Landsat: similar with more dispersion (lower number of products)

Time-series

~443 nm - Deep blue

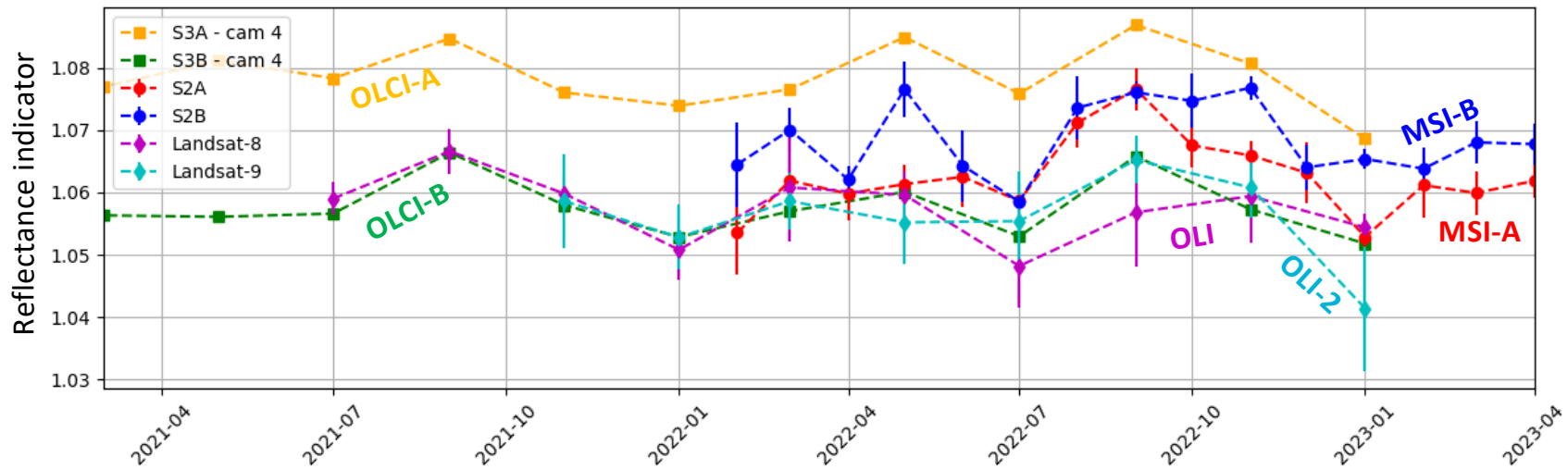


- ❖ OLCI-A and OLCI-B : 1.5 to 2% stable bias
- ❖ MSI-A and MSI-B ~aligned with OLCI-A
- ❖ OLI and OLI-2 ~aligned with OLCI-B

- ❖ MSI-A and MSI-B within 1%
- ❖ OLI and OLI-2 within 1% (except 01/2023)
- ❖ Overall dispersion of 3% max. (except 01/2023)

Time-series

~490 nm - Blue

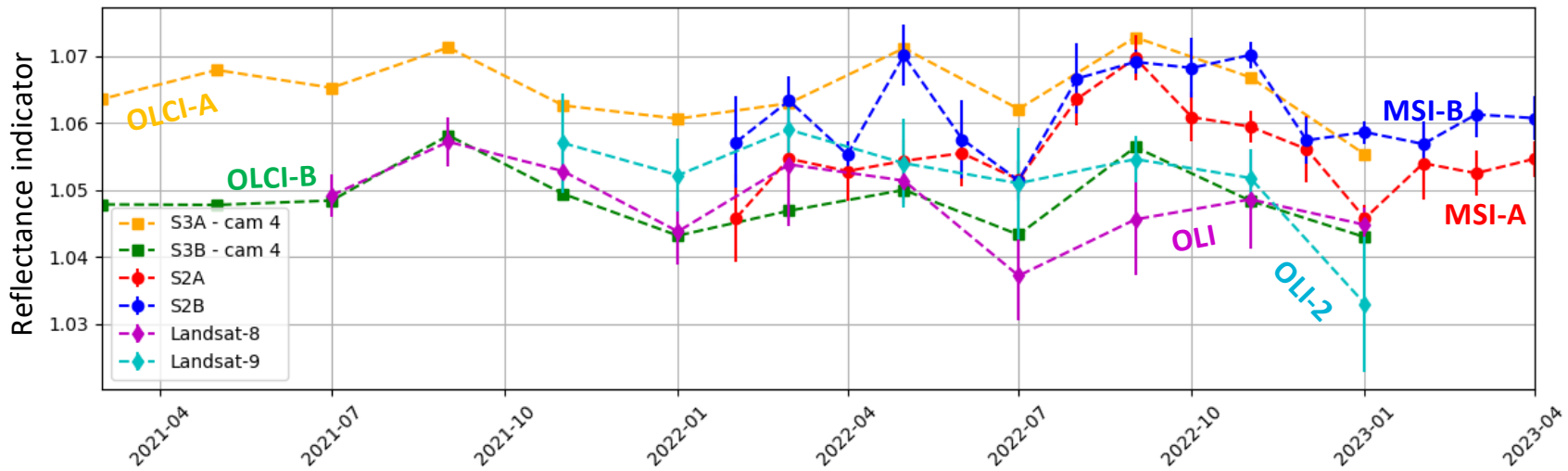


- ❖ OLCI-A and OLCI-B : 1.5 to 2.5% stable bias
- ❖ OLI and OLI-2 ~aligned with OLCI-B

- ❖ MSI-A and MSI-B between OLCI-A and OLCI-B
- ❖ Overall dispersion of 3% max.

Time-series

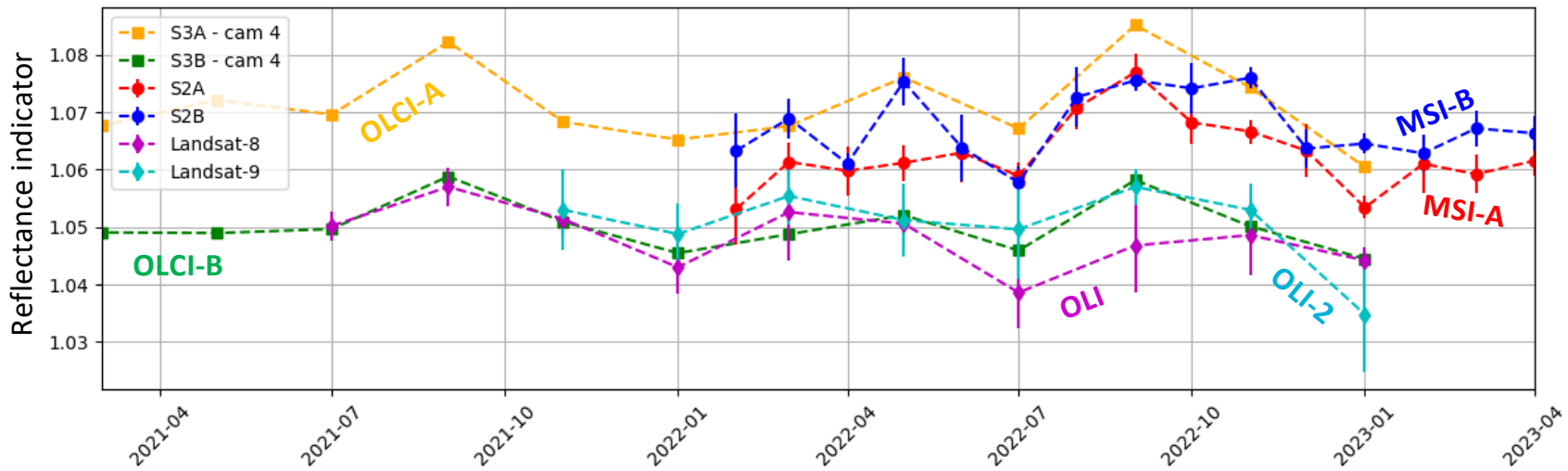
~560 nm - Green



- ❖ Lower bias between **OLCI-A** and **OLCI-B** (1 - 2% max.)
- ❖ Lower overall dispersion: 2.5% max. in July and Sept. 2022, January 2023

Time-series

~660 nm - Red

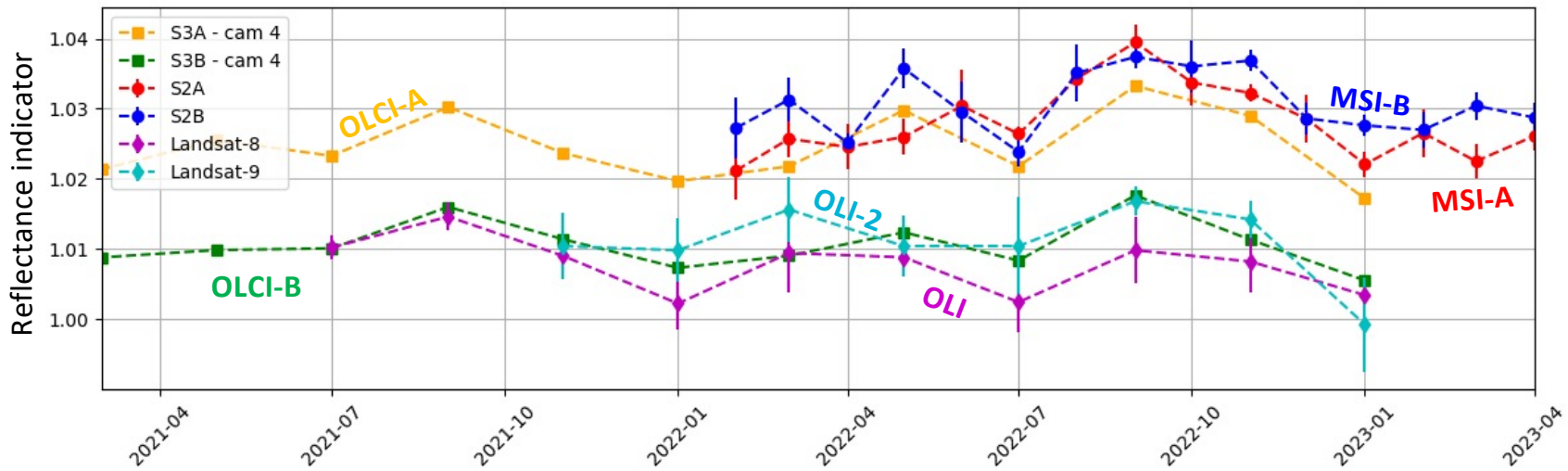


❖ Like green band with higher overall dispersion: 2 to ~4 % max. in Sept. 2022



Time-series

~865 nm - NIR



❖ Lower bias between **OLCI-A** and **OLCI-B** (1.5% max.)

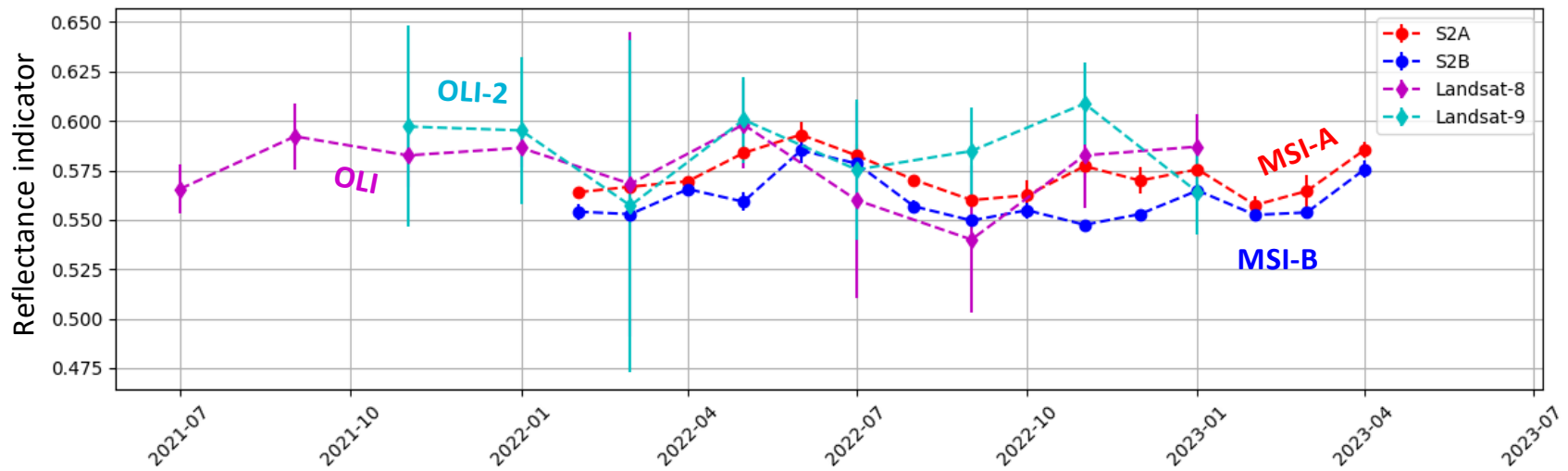
❖ Like 443 nm deep blue band:

✓ **MSI-A** and **MSI-B** ~aligned with **OLCI-A**

✓ **OLI** and **OLI-2** ~aligned with **OLCI-B**

Time-series

~1375 nm - Cirrus

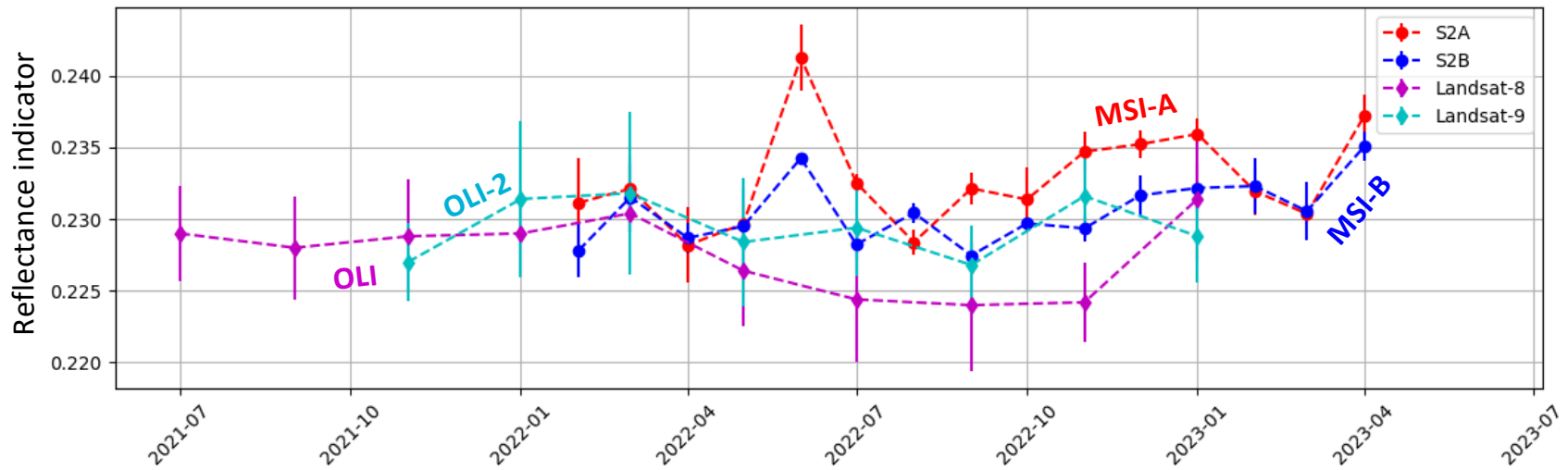


- ❖ Curves squeezed by big error bars
- ❖ Overall dispersion: ~11% max. (Nov. 2022)
- ❖ Overall dispersion: < 4% min. (March 2022)

❖ Known saturation effects for **MSI-A** and **MSI-B**

Time-series

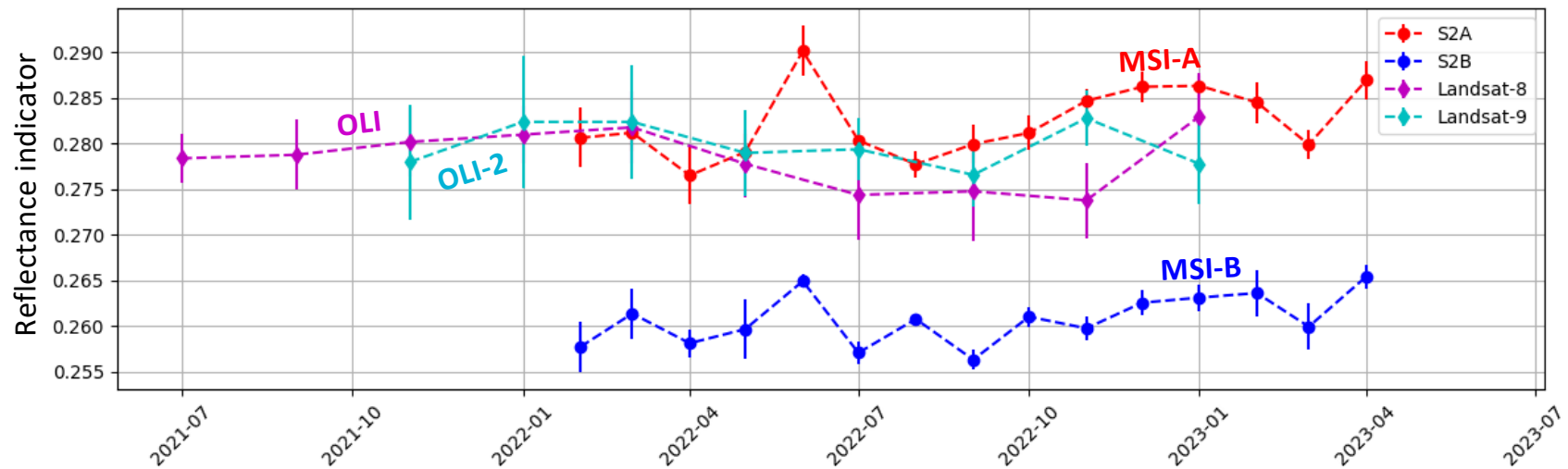
~1610 nm – SWIR 1



- ❖ Peak in June 2022 for **MSI-A** and **MSI-B**
- ❖ Good alignment of **OLI / OLI-2** and **MSI-A / MSI-B** early 2022
- ❖ Deviation until Nov. 2022, converge again in Jan. 2023

## Time-series

~2200 nm – SWIR 2



- ❖ Important bias between **MSI-A** and **MSI-B** (~8%)
- ❖ **OLI** / **OLI-2** aligned with **MSI-A** early 2022, slight deviation after

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## Conclusions and perspectives

### Conclusions

#### ❖ In the VNIR:

- ✓ **MSI-A** and **MSI-B** bias from 0 to 1.5%
- ✓ **OLI** and **OLI-2** bias from 0 to 1.5%
- ✓ **OLCI-A** and **OLCI-B** cam-4 bias from 1 – 2.5% (very stable)
- ✓ **MSI-A** and **MSI-B** between **OLCI-A** and **OLCI-B** cam-4 levels
- ✓ **OLI** and **OLI-2** aligned with **OLCI-B** (cam-4)

#### ❖ Overall:

- ✓ No systematic drift

#### ❖ In the SWIR:

- ✓ 4 to 11% overall dispersion in cirrus band
- ✓ Strong bias between **MSI-A** and **MSI-B** for 2200 nm band (8%)
- ✓ **OLI** and **OLI-2** aligned with **MSI-A** for 2200 nm band
- ✓ Peak in June 2022 for **MSI-A** and **MSI-B** in SWIR 1 and 2, TBC with **OLI** and **OLI-2** data

### Perspectives

- ❖ In-progress work
  - ✓ Missing months for Sentinel-3 and Landsat
  - ✓ Automation of the Landsat DCC
  - ✓ Automation of the Sentinel-3 DCC (+ saturation effects correction)
  
- ❖ Foreseen activities
  - ✓ Use the 5 OLCI cameras (+ directional effects correction)
  - ✓ Saturation effects for Landsat OLI and Sentinel-2 MSI ?
  - ✓ Generic DCC tool for any multi/hyperspectral sensor

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Thank you !



OPT-MPC



Optical Mission Performance Cluster

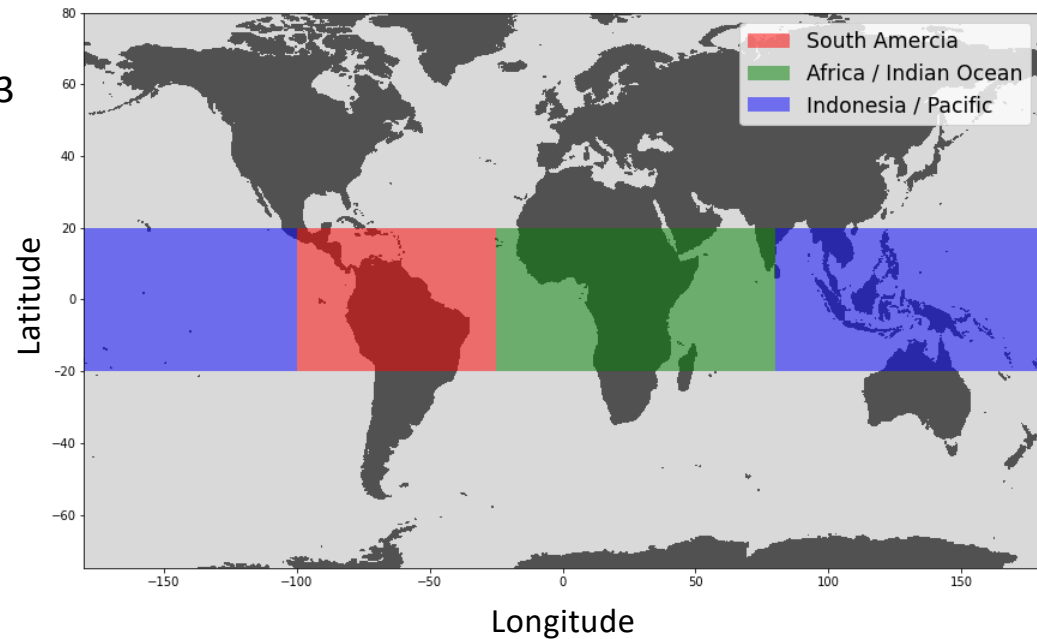


## Backup slides

- ❖ Payloads and missions have some major differences: swath, resolution, revisit, bands...
- ❖ Sentinel-2 and Landsat for land monitoring, Sentinel-3 for marine observation: acquisition plan differs.
- ❖ Sentinel-3 DCC detection uses a different method, taking advantage of SLSTR 10.8  $\mu\text{m}$  TIR band.
- ❖ Transmission spectra used for Sentinel-3 slightly differs from spectra used for Sentinel-2 and Landsat.
- ❖ Transmissions corresponding to a mean ozone content are used for Landsat.
- ❖ Products from a greater latitude range are considered for Sentinel-3 ( $-25^\circ - 25^\circ$ ).
- ❖ The use of post-mode inflexion point may depend on the context, it is subject to discussion.
- ❖ The effects of spectral band shape are currently being investigated at ACRI-ST, in a different context.

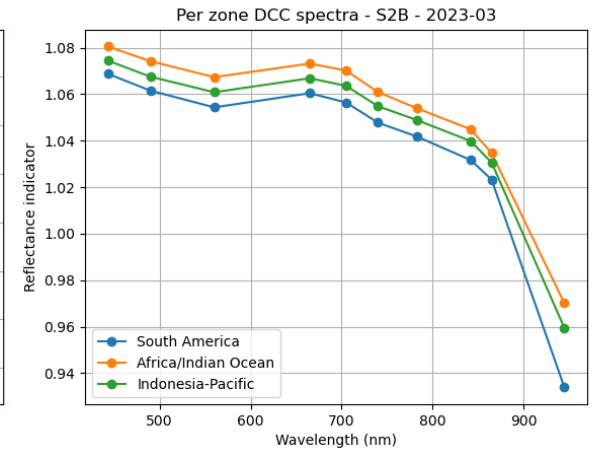
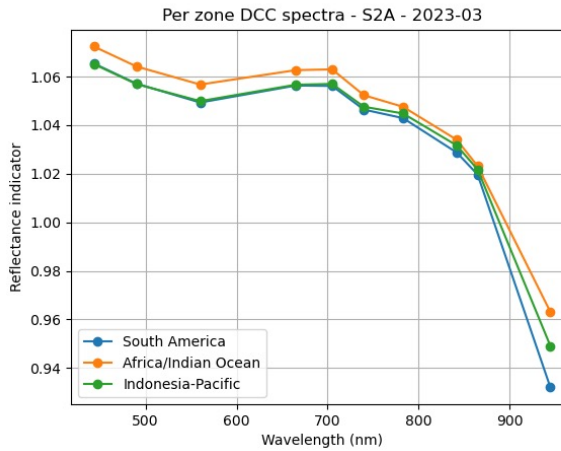
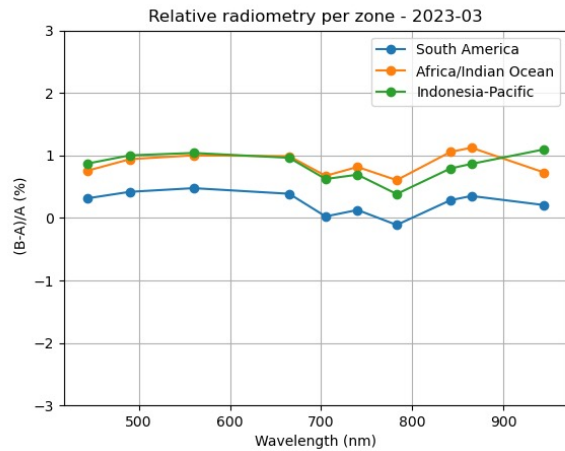
## Distinction of geographical regions

- ❖ To investigate regional effects
- ❖ Exact same methodology + distinction of 3 zones:
  - ✓ South America (-100°: -25° lat.)
  - ✓ Africa / Indian Ocean (-25°: 80° lat.)
  - ✓ Indonesia / Pacific (80°: -100° lat.)



## Per-zone

- ❖ Coming soon
- ❖ Examples for Sentinel-2, March 2023

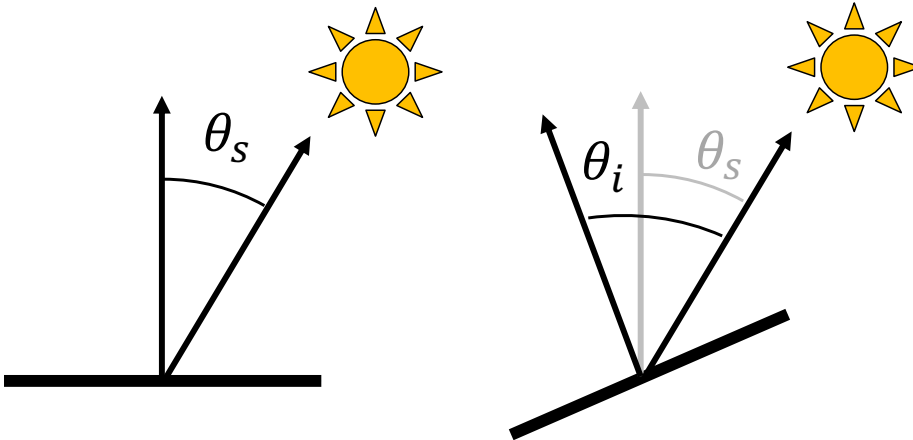


## Per-zone results

## Why is there reflectances greater than 1 ?

### Topology of the clouds and reflectance conversion

$$\rho(\theta_s, \phi_s, \theta_v, \phi_v) = \frac{\pi \cdot L(\theta_s, \phi_s, \theta_v, \phi_v)}{E_s \cdot \cos(\theta_s)}$$



- ❖ Reflectance normalized by  $\cos(\theta_s)$ , the angle between the direction of the sun and the vertical
- ❖ Should be normalized by  $\cos(\theta_i)$ , the angle between the direction of the sun and the normal to the surface, but the “topography” of the cloud is unknown