

Potential of the Moon as a calibration target for IASI instruments

Bojan SIC, Emmanuel DUFOUR, Jérôme DONNADILLE, Tristan LALANNE – NOVELTIS

Elsa JACQUETTE, Laura LE BARBIER, Sébastien MARCQ, Olivier VANDERMARCQ, François BERMUDO – CNES

Jean-Christophe CALVEL – AKKA



4th Lunar Calibration Workshop





Motivation

- Lunar infrared radiance model
- Simulations of IASI observations
- Model-observations comparison
- Conclusions



- IASI is an infrared sounder on MetOp (EPS) satellites
- Calibration of IASI observations
 - Absolute radiometric calibration < 0,5 K @280K
 - Inter-comparisons between sounders < 0,2 K @280K, but nevertheless inter-comparisons between IASI instruments using Earth View acquisitions are not perfect.
- Why consider the Moon as a calibration source?
 - No atmosphere on the Moon
 - Spectra are nearly flat \rightarrow easier to calibrate the whole spectrum
 - Radiometric time variability can be "perfectly" determined/calculated
 - Already used as a calibration source in VIS and NIR, but not in TIR
- How might lunar observations be used and can the current IASI performances be reached?
 - Absolute calibration
 - Inter-calibration (relative) between the instruments
 - Analyses of radiometric calibration stability over time

\rightarrow CNES study conducted by NOVELTIS to explore these questions



- How does IASI see the Moon?
 - The Moon passes regularly, twice a month, through a calibration view @zenith Cold Space View 2 (CS2)
 - The Moon phase (illuminated surface %) during the transits is ~10% (6-17%) and ~90% (83-94% = 33-48° phase angle)
 - CNES adapted the on-board coding tables for cold space (used to encode the on-board spectra) to the lunar dynamics
 - Moon observations were planned (CNES/EUMETSAT) and the Moon was successfully observed during 5 months in 2019 and from January 2021 to January 2022
 - Only ~90% phase transits observed
- How can lunar observations be used for calibration?
 - Necessity to develop a lunar infrared radiance model
 - Simulation of IASI lunar observations
 - position and size determination in the IASI FOV, IPSF convolution
 - Model-observations comparison
 - Estimation of the performance





- > A lunar infrared radiance model has been developed
 - Calculation of thermal emissive (dominant) and solar reflective component (contribution up to 30% in SWIR)

 $L_{eMoon}(\lambda) = \epsilon(\lambda) B(\lambda, T_{Moon}) \qquad \qquad L_{rSun}(\lambda) = \sum_{lon, lat} (\pi \cdot F_{SunIN}(\lambda) \cdot \cos(\theta) \cdot r_{Moon}(lon, lat, \lambda)) \quad \theta < 90^{\circ}$

in a high spatial resolution of 0.5°

- Terrestrial reflective component is negligible (maximal contribution of 0.00104%)
- Coverage of the whole IASI spectral domain 645-2760 cm⁻¹ (3.6-15 μ m)

> Key quantities/parameters to determine for the calculation of infrared Moon radiances

- Sun-Moon-satellite geometry (positions, distances, lunar phase and orientation)
- Surface temperature of the Moon surface
- Emissivity/reflectivity of the Moon surface
- Soil type distribution for the emissivity/reflectivity application



- Sun-Moon-satellite geometry (positions, distances, lunar phase and orientation)
 - Calculated with the semi-analytic models VSOP87 (Sun) & ELP2000-82B (Moon) developed by Paris Observatory
 - Good agreement with JPL ephemeris (DE440) verified for 780 dates of IASI Moon transits





- Surface temperature derived from LRO/Diviner bolometric temperature L4 product
 - Cumulative product (2009-2015) with a temporal resolution of 1h (15°) and a high spatial resolution (0.5°)
 - Contains the relief effects, but it is an averaged dataset
 - No libration
 - No changes in solar irradiance (implemented in the model)
 - It is a bolometric temperature dataset, necessary conversion to surface temperature
 - Determination of the coordinate system and calculation of the subsolar point to apply a T_{surf} map correctly
 - Modified selenographic coordinated system with (0,0) always in the sub-observer point (satellite / Earth's center)
 - We implemented also T_{surf} models (influenced by LRO/Diviner data):
 - Semi-analytical from Vasavada et al. (2012)
 - Empirical from Hurley et al. (2015)



NOVELTIS

Lunar infrared radiometric model

- Emissivity of the Moon surface
 - Data from Apollo samples
 - JHU data (Salisbury et al. (1997)) in ASTER/ECOSTRESS spectral library
 - RELAB/BU data in CRISM spectral library (compiled for MRO/CRISM)
 - Quite significant differences
 - Studies suggest that samples should be measured in Moon-like conditions
 - Lambertian approximation
 - Distinction between typical highlands and maria (+impact craters)
 - Apollo 11 & 12 maria
 - Apollo 15, 16 & 17 highlands
 - To distinct soil types, different datasets were considered :
 - Albedo (LRO/LOLA)
 - Chemical composition (Clementina)
 - Surface rugosity (LRO/LOLA)
 - Slope (LRO/LOLA)
 - Rock abundance (LRO/Diviner)
 - Empirical thresholds implemented with a gradual transition







Lunar infrared radiometric model





First performance estimation of the model was done with various sensitivity tests

Impact of various approximations and parameters on the calculated brightness temperature

Surface temperature maps Observations vs. models/parametrisations ٠ 2.5 Impact of terrain . difference Impact of libration ٠ Impact of variability of solar constant on surface 2.0 temperature (parametrization) temperature Soil type maps Impact of threshold rock abundance values 1.5 Impact of libration Solar component 1.0 Impact of variability of solar constant on radiance Emissivity 0.5 Difference between spectral bases

- Important differences in emissivity
- Observations are more performant than parametrizations.
- Neither of other impacts exceeds 0.2K.



Wavelength [um]

Simulation of IASI observations

Simulation of IASI observations

NOVELTIS

- Determine the position of the Moon in the field of view of IASI's imager (IIS)
- Colocate the position in IIS with IASI's FOV
- Convolve the modelled radiance with the IASI IPSF (4 pixels, 3 bands)
- Position in IIS (imager) FOV in one image
 - Calculate (theoretically) the Moon phase, size and orientation in the IIS FOV
 - The best results are obtained when the barycenter-center vector is calculated (simulation) and then applied on the observed barycenter.
 - Precision of ~0.25 pixel IIS
- Position can be improved by considering a series of images.









- Improvement of the position by considering a series of images
 - The trajectory of the satellite and movement of the instrument (yaw steering) are known → we can calculate the angle and the angular velocity of the Moon transit in IIS FOV.
 - The minimization of the distances permitted us to improve the precision of the Moon in IIS to ~0.1 IIS pixel.
 - Also permitted a better in-flight estimation of :
 - FOV IIS
 - _ IASI-B: 60.71 ± 0.12 mrad
 - IASI-C: 61.22 ± 0.11 mrad
 - This adds some uncertainties in the quality of IASI/imager coregistration
 - Orientation of the IIS image Yaw steering angle has a systematic bias of 0.1° ± 0.02°.





- Improvement of the position by considering a series of images
 - The trajectory of the satellite and movement of the instrument (yaw steering) are known → we can calculate the angle and the angular velocity of the Moon transit in IIS FOV.
 - The minimization of the distances permitted us to improve the precision of the Moon in IIS to ~0.1 IIS pixel.
 - Also permitted a better in-flight estimation of :
 - FOV IIS
 - _ IASI-B: 60.71 ± 0.12 mrad
 - IASI-C: 61.22 ± 0.11 mrad
 - This adds some uncertainties in the quality of IASI/imager coregistration
 - Orientation of the IIS image Yaw steering angle has a systematic bias of 0.1° ± 0.02°.





- After the colocation applied, the modelled radiances are convolved with the IASI IPSF of the concerned pixel to obtain a simulated IASI lunar observation.
 - Operational IPSFs are normalized (OK for IASI observations but not for lunar simulations) → had to be denormalized to take into account physical differences between pixels (inter-band differences are emissivity spectral base dependent)
 - Some uncertainties exist with IPSFs (exact size, quality of measurements)
- > Three possible types of Moon transits





Partial



Bordering

07/12/2023 NOV-FE-1454-SL-002 © NOVELTIS.



IASI lunar observations

- The Moon covers 35%-43% of the IASI FOV
- Smooth inter-bands are present only during central transits
- For the partial transits there is a systematic complete loss of some bands (coding table underflow)
- All this makes partial transits unusable, and bordering transits should be used with caution.
- There were detector (and coding table) saturations May-August 2021
 - Period when the moon irradiance was at maximum for the IASI transits
- Noise reduction is performed with a reduction of spectral resolution (0.25 cm⁻¹ -> 7.5cm⁻¹).
- Simulations and observations can finally be compared.



0.000

radiance [Wm2/stm-1] P0000

0.0002

0.000



- In absolute values, the comparison shows a ~2.5K accuracy between the simulations and observations.
- Results between the bands are quite consistent, but there is a strong temporal variation





Results

> The observed bias shows a strong dependency of lunar phase and is clearly model-related





> The observed bias shows a strong dependency of lunar phase and is clearly model-related





- The observed bias shows a strong dependency of lunar phase and is clearly model-related
 - Although the moon phase range is the IASI data is quite small (84-92%)
- > After extensive tests, it seems that the cause of the bias is the Lambertian approximation
- It appears that the Moon infrared emissivity is strongly directional
 - LRO/Diviner data suggests the same
 - We currently explore this question further
 - This effect impacts both the emissive and the reflective components
- Given the very high correlation of the bias to lunar phase, the hope is that a correction of this effect will improve an absolute accuracy of the simulation to ≤ 0.5 K
- Standard deviations of the differences between the bands suggest this
 - Band B3 behavior is more different probably because of the solar reflective contribution (more uncertainties)

std [K]	B1-B2	B1-B3	B2-B3
IASI-B	0.14 K	0.42 K	0.36 K
IASI-C	0.23 K	0.39 K	0.32 K



- **Results**
- In relative values, we performed inter-instrument comparisons between various pixel pairs (where we obtained enough data points). Relative errors in brigthness temperature between PN4 IASI-B and PN1 IASI-G
 - The results give an accuracy of 0.5 1 K.
 - This is worse than what the 2019 data suggested (only 2 data points available gave an estimated accuracy of 0.2K)
 - And less good than Earth-view based massive relative comparisons (<0.2K)
 - It is presumed that colocation uncertainties are a strong contributor to these uncertainties (?)
 - Relative comparison of pixel pairs observed during a same transit to estimate • this contribution (time difference of ~15 sec between observations)
 - In that timescale the impact of the physical model is negligeable





Relative comparison of pixel pairs observed during a same transit (time difference of 15 sec)



- Colocation is more precise with IASI-B than (±0.2K impact) with IASI-C (±0.5K impact)
 - Results confirmed with other imager-sounder co-registration tests that we performed
- Colocation uncertainties is the most important contributor to relative inter-instrument results (~0.5 K), but not the only one



- We are investigating a potential to use the Moon as calibration source for IASI observations in thermal infrared.
- The lunar observations are obtained in 2019 & 2021 and an infrared radiance model is developed.
 - Related uncertainties are identified and analyzed (simulations and observations).
- Results give an accuracy of ~2.5K in absolute and 0.5–1K in relative values.
 - Absolute results are dominated by the model (directional emissivity), and relative results by the imager-sounder colocation uncertainties
 - Solving these two identified sources would approach the results to the Earth-view based performance
 - Different approaches could be employed to address the directionality of lunar soil emissivity:
 - LRO/DIVINER data from its off-nadir campaign (performed in the phase 3 since 2016 and mid to high latitudes might be already decently covered)
 - Inversion approach using IASI data (high spectral resolution, spatially integrated, moon phase dependent)
 - Modelling or parametrisation approach (mature enough? various results suggest that the multiple scattering is important)
- We can conclude that the modeling is (also) hard in the infrared domain!



- CNES and EUMETSAT recognize that IASI lunar data is quite unique and that it might be very interesting to the scientific community
- > The wish to start distribute it in the coming weeks and the preparations are on-going
- If you are interested in exploring the IASI lunar dataset, you can approach me in order to make sure that the distributed data will correspond to your needs/ideas



Thank you for your attention